

# Automotive Series Serial EEPROMs 125°C SPI BUS ICs BR25xxxxFamily





# BR25Hxxx-WC Series (1K 2K 4K 8K 16K 32K)

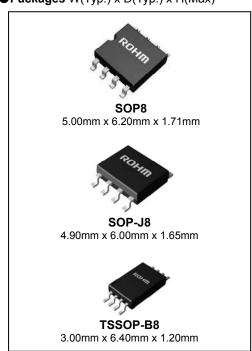
#### Description

BR25Hxxx-WC series is a serial EEPROM of SPI BUS interface method.

#### Features

- High speed clock action up to 5MHz (Max.)
- Wait function by HOLDB terminal.
- Part or whole of memory arrays settable as read only memory area by program.
- 2.5 to 5.5V single power source action most suitable for battery use.
- Page write mode useful for initial value write at factory shipment.
- Highly reliable connection by Au pad and Au wire.
- For SPI bus interface (CPOL, CPHA)=(0, 0), (1, 1)
- Auto erase and auto end function at data rewrite.
- Low current consumption
  - At write action (5V) : 1.5mA (Typ.)
  - At read action (5V) : 1.0mA (Typ.)
  - At standby action (5V) : 0.1μA (Typ.)
- Address auto increment function at read actionWrite mistake prevention function
  - Write prohibition at power on.
  - Write prohibition by command code (WRDI).
  - Write prohibition by WPB pin.
  - Write prohibition block setting by status registers (BP1, BP0)
  - Write mistake prevention function at low voltage.
- Data at shipment Memory array: FFh, status register WPEN, BP1, BP0: 0
- Data kept for 40 years.
- Data rewrite up to 1,000,000times.

#### ● Packages W(Typ.) x D(Typ.) x H(Max)



#### Page write

Number of pages	16 Byte	32 Byte			
Product number	BR25H010-WC BR25H020-WC BR25H040-WC	BR25H080-WC BR25H160-WC BR25H320-WC			

# ●BR25Hxxx-WC series

Capacity	Bit format	Туре	Power source voltage	SOP8	SOP-J8	TSSOP-B8
1Kbit	128×8	BR25H010-WC	2.5 to 5.5V	•	•	•
2Kbit	256×8	BR25H020-WC	2.5 to 5.5V	•	•	•
4Kbit	512×8	BR25H040-WC	2.5 to 5.5V	•	•	•
8Kbit	1K×8	BR25H080-WC	2.5 to 5.5V	•	•	•
16Kbit	2K×8	BR25H160-WC	2.5 to 5.5V	•	•	•
32Kbit	4Kx8	BR25H320-WC	2.5 to 5.5V	•	•	

# ● Absolute Maximum Ratings (Ta=25°C)

Parameter	Symbol	Limits	Unit	Remarks
Impressed voltage	Vcc	-0.3 to +6.5	V	
		560(SOP8)		When using at Ta=25°C or higher, 4.5mW to be reduced per 1°C
Permissible dissipation	Pd	560(SOP-J8)	mW	When using at Ta=25°C or higher, 4.5mW to be reduced per 1°C
dissipation		410(TSSOP-B8)		When using at Ta=25°C or higher, 3.3mW to be reduced per 1°C
Storage temperature range	Tstg	-65 to +150	°C	
Operating temperature range	Topr	-40 to +125	°C	
Terminal voltage	-	-0.3 to V <sub>CC</sub> +0.3	V	

# ● Memory Cell Characteristics (V<sub>CC</sub>=2.5V to 5.5V)

Parameter		Limits		Unit	Condition	
Farameter	Min.	Тур.	Max.	Offic		
	1,000,000	1	-	Times	Ta≦85°C	
Number of data rewrite times *1	500,000	1	-	Times	Ta≦105°C	
	300,000	-	-	Times	Ta≦125°C	
Data hold years <sup>*1</sup>	40	-	-	Years	Ta≦25°C	
	20	-	-	Years	Ta≦125°C	

<sup>\*1:</sup> Not 100% TESTED

Recommended Operating Ratings

Parameter	Symbol	Limits	Unit
Power source voltage	V <sub>CC</sub>	2.5 to 5.5	\/
Input voltage	V <sub>IN</sub>	0 to V <sub>CC</sub>	V

●Input / Output Capacity (Ta=25°C, frequency=5MHz)

Parameter	Symbol	Min	Max	Unit	Conditions
Input capacity*1	C <sub>IN</sub>	-	8	nΕ	V <sub>IN</sub> =GND
Output capacity*1	C <sub>OUT</sub>	-	8	p⊦	V <sub>OUT</sub> =GND

<sup>\*1:</sup> Not 100% TESTED

●Electrical Characteristics(Unless otherwise specified, Ta=-40°C to +125°C, V<sub>CC</sub>=2.5V to 5.5V)

Parameter	meter Symbol Limits Un		Unit	Conditions			
Farameter	Symbol	Min.	Тур.	Max.	Offic	Conditions	
"H" input voltage	VIH	$0.7xV_{\text{CC}} \\$	-	V <sub>CC</sub> +0.3	V	2.5V≦V <sub>CC</sub> ≦5.5V	
"L" input voltage	VIL	-0.3	-	0.3xV <sub>CC</sub>	V	2.5V≦V <sub>CC</sub> ≦5.5V	
"L" output voltage	VOL	0	-	0.4	V	IOL=2.1mA	
"H" output voltage	VOH	$V_{\text{CC}}$ -0.5	-	V <sub>CC</sub>	V	IOH=-0.4mA	
Input leak current	ILI	-10	-	10	μΑ	V <sub>IN</sub> =0 to V <sub>CC</sub>	
Output leak current	ILO	-10	-	10	μΑ	V <sub>OUT</sub> =0 to V <sub>CC</sub> , CSB=V <sub>CC</sub>	
Current consumption at write action	ICC1	-	-	2.0	mA	V <sub>CC</sub> =2.5V,fSCK=5MHz, tE/W=5ms VIH/VIL=0.9V <sub>CC</sub> /0.1V <sub>CC</sub> , SO=OPEN Byte write, Page write Write status register V <sub>CC</sub> =5.5V,fSCK=5MHz, tE/W=5ms	
action	ICC2	-	-	3.0	mA	VIH/VIL=0.9V <sub>CC</sub> /0.1V <sub>CC</sub> , SO=OPEN  Byte write, Page write Write status register	
Current consumption at read	ICC3	-	-	1.5	mA	V <sub>CC</sub> =2.5V,fSCK=5MHz VIH/VIL=0.9V <sub>CC</sub> /0.1V <sub>CC</sub> , SO=OPEN Read, Read status register	
action	ICC4	-	-	2.0	mA	V <sub>CC</sub> =5.5V,fSCK=5MHz VIH/VIL=0.9V <sub>CC</sub> /0.1V <sub>CC</sub> , SO=OPEN Read, Read status register	
Standby current	ISB	-	-	10	V <sub>cc</sub> =5.5V μA CSB=HOLDB=WPB=V <sub>cc</sub> , SCK=SI=V <sub>cc</sub> or SO=OPEN		

# Operating Timing Characteristics

(Ta=-40°C to +125°C, unless otherwise specified, load capacity CL1=100pF)

(1a=-40 C to +125 C, unless otherwise specifie		<u>1–100pi )</u> 2			
Parameter	Symbol	Min.	Тур.	Max.	Unit
SCK frequency	fSCK	-	-	5	MHz
SCK high time	tSCKWH	85	-	-	ns
SCK low time	tSCKWL	85	-	-	ns
CSB high time	tCS	85	-	-	ns
CSB setup time	tCSS	90	-	-	ns
CSB hold time	tCSH	85	-	-	ns
SCK setup time	tSCKS	90	-	-	ns
SCK hold time	tSCKH	90	-	-	ns
SI setup time	tDIS	20	-	-	ns
SI hold time	tDIH	30	-	-	ns
Data output delay time1	tPD1	-	-	0	ns
Data output delay time2 (CL2=30pF)	tPD2	-	-	55	ns
Output hold time	tOH	0	-	-	ns
Output disable time	tOZ	-	-	100	ns
HOLDB setting setup time	tHFS	0	-	-	ns
HOLDB setting hold time	tHFH	40	-	-	ns
HOLDB release setup time	tHRS	0	-	-	ns
HOLDB release old time	tHH	70	-	-	ns
Time from HOLDB to output High-Z	tHOZ	-	-	100	ns
Time from HOLDB To output change	tHPD	-	-	70	ns
SCK rise time <sup>*1</sup>	tRC	-	-	1	μs
SCK fall time*1	tFC	-	-	1	μs
OUTPUT rise time*1	tRO	-	-	50	ns
OUTPUT fall time*1	tFO	-	-	50	ns
Write time	tE/W	-	-	5	ms

<sup>\*1</sup> NOT 100% TESTED

# ●Sync Data Input / Output Timing

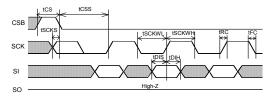


Fig.1 Input timing

SI is taken into IC inside in sync with data rise edge of SCK. Input address and data from the most significant bit MSB.

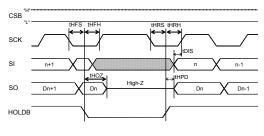


Fig.3 HOLD timing

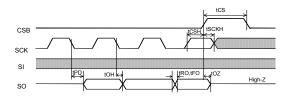


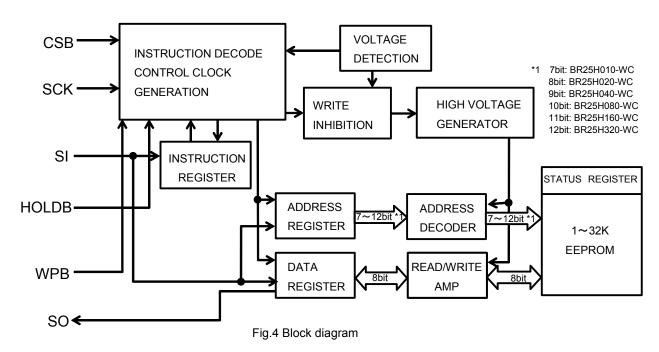
Fig.2 Input / Output timing

SO is output in sync with data fall edge of SCK. Data is output from the most significant bit MSB.

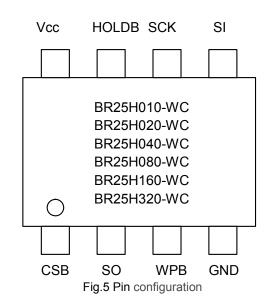
# **AC Measurement Conditions**

Parameter	Symbol		Unit		
Parameter	Symbol	Min.	Тур.	Max.	Offic
Load capacity 1	CL1	-	-	100	pF
Load capacity 2	CL2	-	ı	30	pF
Input rise time	-	-	1	50	ns
Input fall time	-	-	ı	50	ns
Input voltage	-	0.2V <sub>CC</sub> /0.8V <sub>CC</sub>			V
Input / Output judgment voltage	-	0.3	0.3V <sub>CC</sub> /0.7V <sub>CC</sub>		

# Block Diagram



# ●Pin Configuration



# Pin Description

Terminal name	Input/Output	Function
V <sub>CC</sub>	-	Power source to be connected
GND	-	All input / output reference voltage, 0V
CSB	Input	Chip select input
SCK	Input	Serial clock input
SI	Input	Start bit, ope code, address, and serial data input
SO	Output	Serial data output
HOLDB	Input	Hold input Command communications may be suspended temporarily (HOLD status)
WPB	Input	Write protect input Write command is prohibited *1 Write status register command is prohibited.

<sup>\*1:</sup>BR25H010/020/040-WC

# **Typical Performance Curves**

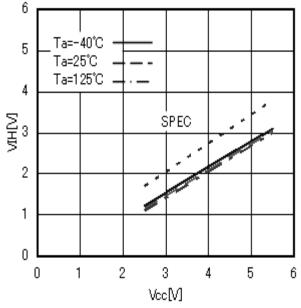


Fig.6 "H" input voltage VIH (CSB,SCK,SI,HOLDB,WPB)

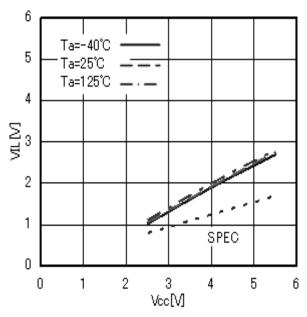


Fig.7 "L" input voltage VIL (CSB,SCK,SI,HOLDB,WPB)

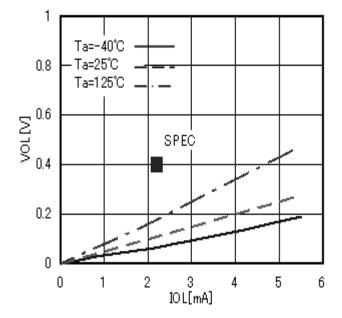


Fig.8 "L" output voltage VOL-IOL (Vcc=2.5V)

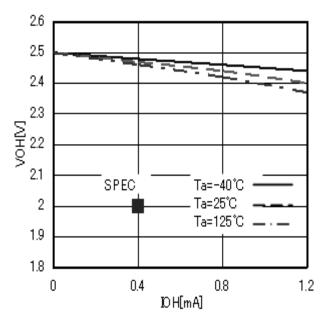


Fig.9 "H" output voltage VOH-IOH (Vcc=2.5V)

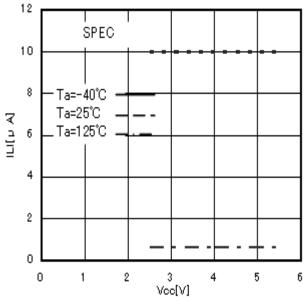


Fig.10 Input leak current ILI (CSB,SCK,SI,HOLDB,WPB)

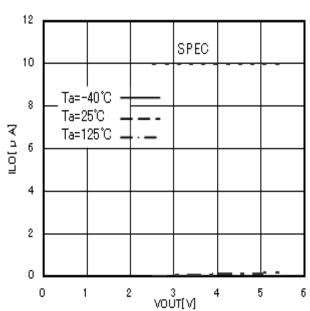


Fig.11 Output leak current ILO (SO)(Vcc=5.5V)

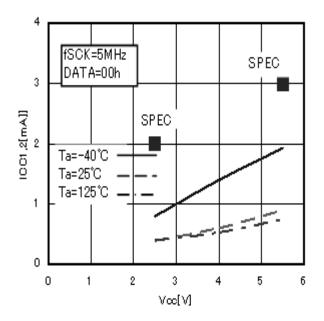


Fig.12 Current consumption at WRITE operation ICC1,2

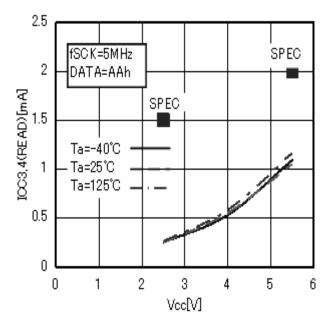
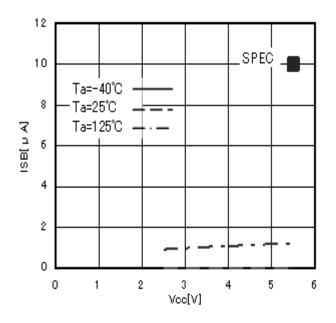


Fig.13 Consumption Current at READ operation ICC3,4



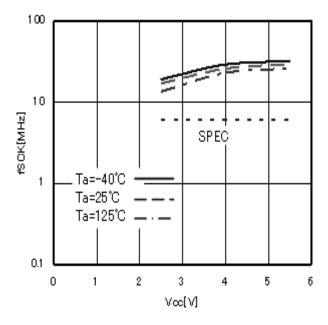
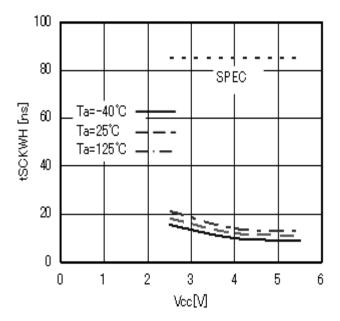


Fig.14 Consumption current at standby operation ISB

Fig.15 SCK frequency fSCK





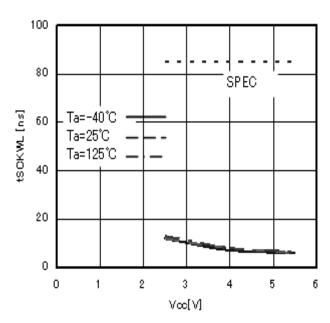


Fig.17 SCK low time tSCKWL

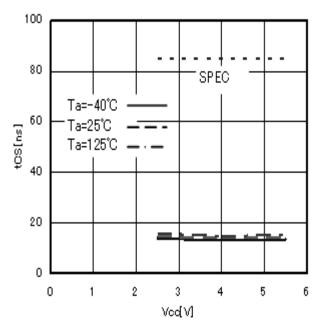


Fig.18 CSB high time tCS

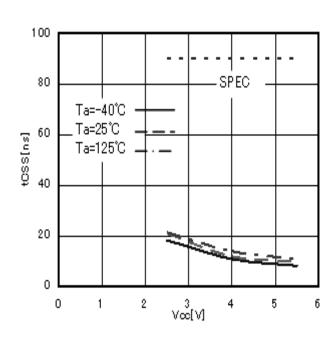


Fig.19 CSB setup time tCSS

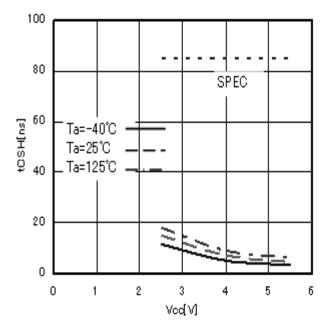


Fig.20 CSB hold time tCSH

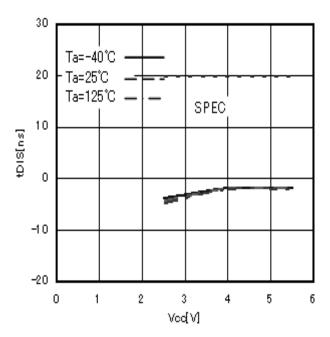


Fig.21 SI setup time tDIS

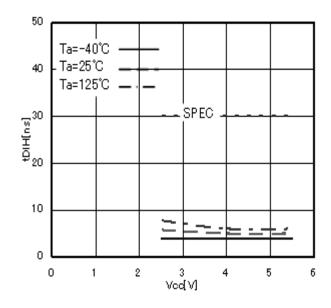


Fig.22 SI hold time tDIH

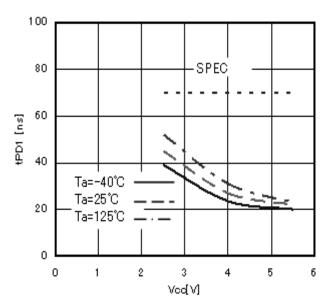


Fig.23 Data output delay time tPD1 (CL=100pF)

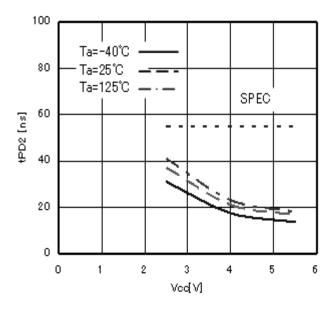


Fig.24 Data output delay time tPD2 (CL-30pF)

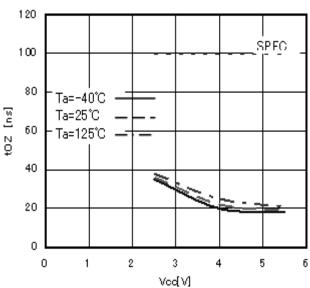
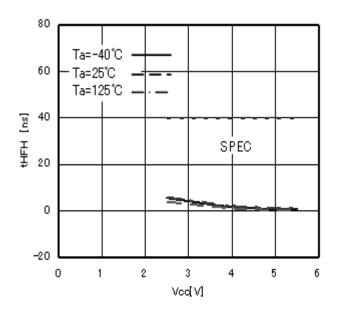


Fig.25 Output disable time tOZ





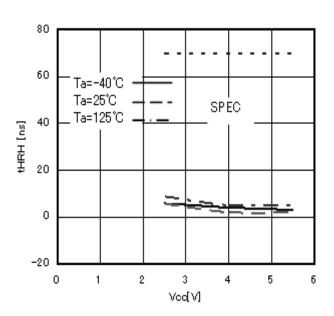


Fig.27 HOLDB release hold time tHRH

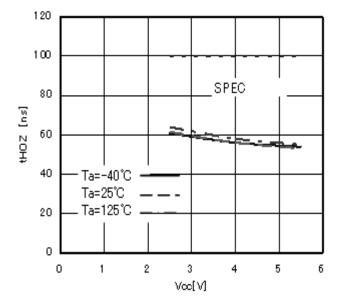


Fig.28 Time from HOLDB to output High-Z tHOZ

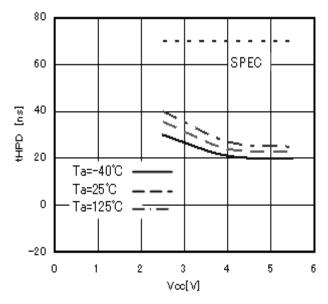


Fig.29 Time from HOLDB to output change tHPD

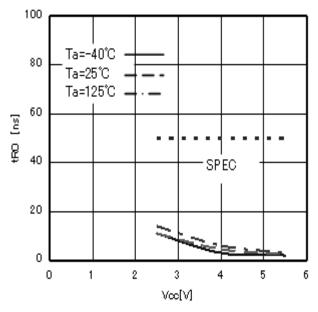


Fig.30 Output rise time tRO

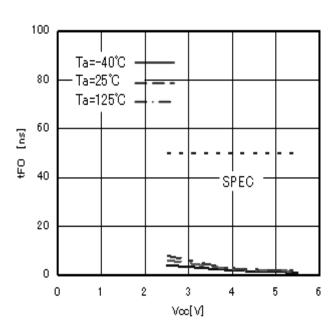


Fig.31 Output fall time tFO

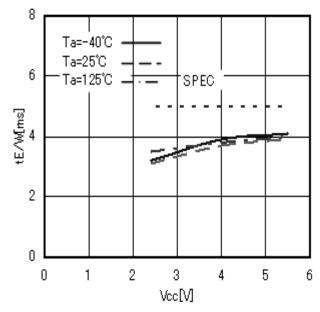


Fig.32 Write cycle time tE/W

#### Features

# OStatus registers

This IC has status registers. The status registers are of 8 bits and express the following parameters.

BP0 and BP1 can be set by write status register command. These 2 bits are memorized into the EEPROM, therefore are valid even when power source is turned off.

Rewrite characteristics and data hold time are same as characteristics of the EEPROM.

WEN can be set by write enable command and write disable command. WEN becomes write disable status when power source is turned off.  $\overline{R}/B$  is for write confirmation, therefore cannot be set externally.

The value of status register can be read by read status command.

Status Registers

Product number	bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
BR25H010-WC								
BR25H020-WC	1	1	1	1	BP1	BP0	WEN	R/B
BR25H040-WC								
BR25H080-WC								
BR25H160-WC	WPEN	0	0	0	BP1	BP0	WEN	R/B
BR25H320-WC								

bit	Memory location	Function	Contents
WPEN	EEPROM	WPB pin enable / disable designation bit  WPEN=0=invalid  WPEN=1=valid	This enables / disables the functions of WPB pin.
BP1 BP0	EEPROM	EEPROM write disable block designation bit	This designates the write disable area of EEPROM. Write designation areas of product numbers are shown below.
WEN	Register	Write and write status register write enable / disable status confirmation bit WEN=0=prohibited WEN=1=permitted	
Ē/B	Register	Write cycle status (READY / BUSY) status confirmation bit  \(\overline{R}/B=0=READY\)  \(\overline{R}/B=1=BUSY\)	

Write Disable Block Setting

		•					
BP1	BP0			Write disa	ble block		
DF I	BFU	BR25H010-WC	BR25H020-WC	BR25H040-WC	BR25H080-WC	BR25H160-WC	BR25H320-WC
0	0	None	None	None	None	None	None
0	1	60h-7Fh	C0h-FFh	180h-1FFh	300h-3FFh	600h-7FFh	C00h-FFFh
1	0	40h-7Fh	80h-FFh	100h-1FFh	200h-3FFh	400h-7FFh	800h-FFFh
1	1	00h-7Fh	00h-FFh	000h-1FFh	000h-3FFh	000h-7FFh	000h-FFFh

# OWPB pin

By setting WPB=LOW, write command is prohibited. As for BR25H080/160/320-WC, only when WPEN bit is set "1", the WPB pin functions become valid. And the write command to be disabled at this moment is WRSR. As for BR25H010/020/040-WC, both WRITE and WRSR commands are prohibited.

However, when write cycle is in execution, no interruption can be made.

Product number	WRSR	WRITE	
BR25H010-WC	Prohibition	Prohibition	
BR25H020-WC	possible	possible	
BR25H040-WC	possible	possible	
BR25H080-WC	Drobibition possible	Prohibition	
BR25H160-WC	Prohibition possible but WPEN bit "1"	impossible	
BR25H320-WC	DUL WEEN DIL 1	impossible	

# OHOLDB pin

By HOLDB pin, data transfer can be interrupted. When SCK="0", by making HOLDB from "1" into"0", data transfer to EEPROM is interrupted. When SCK = "0", by making HOLDB from "0" into "1", data transfer is restarted.

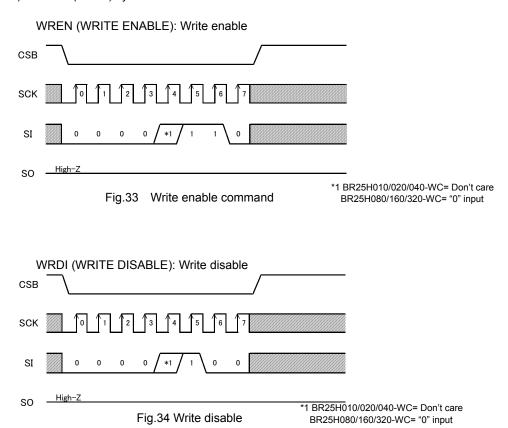
#### ●Command Mode

Command					Ope code			
				010-WC 020-WC	BR25H040-W(:		BR25H080-WC BR25H160-WC BR25H320-WC	
WREN	Write enable	Write enable command	0000	*110	0000	*110	0000	0110
WRDI	Write disable	Write disable command	0000	*100	0000	*100	0000	0100
READ	Read	Read command	0000	*011	0000	A8011	0000	0011
WRITE	Write	Write command	0000	*010	0000	A8010	0000	0010
RDSR	Read status register	Status register read command	0000	*101	0000	*101	0000	0101
WRSR	Write status register	Status register write command	0000	*001	0000	*001	0000	0001

<sup>\*=</sup>Don't Care Bit.

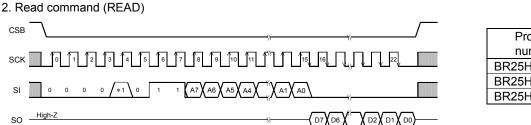
# Timing Chart

1. Write enable (WREN) / disable (WRDI) cycle



OThis IC has write enable status and write disable status. It is set to write enable status by write enable command, and it is set to write disable status by write disable command. As for these commands, set CSB LOW, and then input the respective ope codes. The respective commands accept command at the 7-th clock rise. Even with input over 7 clocks, command becomes valid.

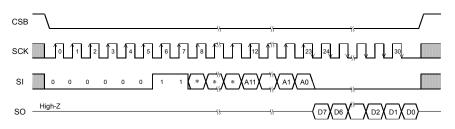
When to carry out write and write status register command, it is necessary to set write enable status by the write enable command. If write or write status register command is input in the write disable status, commands are cancelled. And even in the write enable status, once write and write status register command is executed, it gets in the write disable status. After power on, this IC is in write disable status.



Product	Address
number	length
BR25H010-WC	A6-A0
BR25H020-WC	A7-A0
BR25H040-WC	A8-A0

Fig.35 Read command (BR25H010/020/040-WC)

\*1 BR25H010/020-WC=Don't care BR25H040-WC=A8



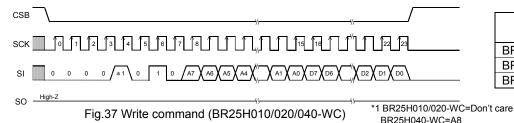
Product	Address
number	length
BR25H080-WC	A9-A0
BR25H160-WC	A10-A0
BR25H320-WC	A11-A0

Fig.36 Read command (BR25H080/160/320-WC)

By read command, data of EEPROM can be read. As for this command, set CSB LOW, then input address after read ope code. EEPROM starts data output of the designated address. Data output is started from SCK fall of 15/23<sup>\*1</sup> clock, and from D7 to D0 sequentially. This IC has increment read function. After output of data for 1 byte (8bits), by continuing input of SCK, data of the next address can be read. Increment read can read all the addresses of EEPROM. After reading data of the most significant address, by continuing increment read, data of the most insignificant address is read.

#### 3. Write command (WRITE)

SO High-Z



Product	Address
number	length
BR25H010-WC	A6-A0
BR25H020-WC	A7-A0
BR25H040-WC	A8-A0

CSB
SCK 1 1 2 3 4 5 6 7 8 1 3 2 2 1 3 3 3 3 3 1
SI 0 0 0 0 0 0 1 0 * X * X * X * X * A11 X * A0 X D7 X D6 X * X D2 X D1 X D0 X

Product	Address
number	length
BR25H080-WC	A9-A0
BR25H160-WC	A10-A0
BR25H320-WC	A11-A0

Fig.38 Write command (BR25H080/160/320-WC)

By write command, data of EEPROM can be written. As for this command, set CSB LOW, then input address and data after write ope code. Then, by making CSB HIGH, the EEPROM starts writing. The write time of EEPROM requires time of tE/W (Max 5ms). During tE/W, other than status read command is not accepted. Start CSB after taking the last data (D0), and before the next SCK clock starts. At other timing, write command is not executed, and this write command is cancelled. This IC has page write function, and after input of data for 1 byte (8 bits), by continuing data input without starting CSB, data up to 16/32<sup>\*1</sup>bytes can be written for one tE/W. In page write, the insignificant 4/5<sup>\*2</sup> bit of the designated address is incremented internally at every time when data of 1 byte is input and data is written to respective addresses. When data of the maximum bytes or higher is input, address rolls over, and previously input data is overwritten.

<sup>\*1</sup> BR25H010/020/040-WC=15 clocks BR25H080/160/320-WC=23 clocks

<sup>\*1</sup> BR25H010/020/040-WC=16 bytes at maximum BR25H080/160/320-WC=32 bytes at maximum

<sup>&</sup>lt;sup>\*</sup>2 BR25H010/020/040-WC=Insignificant 4 bits BR25H080/160/320-WC=Insignificant 5 bits

#### 4. Status register write / read command

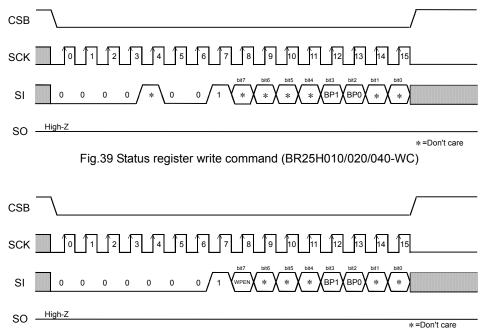


Fig.40 Status register write command (BR25H080/160/320-WC)

Write status register command can write status register data. The data can be written by this command are 2 bits 1, that is, BP1 (bit3) and BP0 (bit2) among 8 bits of status register. By BP1 and BP0, write disable block of EEPROM can be set. As for this command, set CSB LOW, and input ope code of write status register, and input data. Then, by making CSB HIGH, EEPROM starts writing. Write time requires time of tE/W as same as write. As for CSB rise, start CSB after taking the last data bit (bit0), and before the next SCK clock starts. At other timing, command is cancelled. Write disable block is determined by BP1 and BP0, and the block can be selected from 1/4 of memory array, 1/2, and entire memory array. (Refer to the write disable block setting table.) (Refer to the write disable block setting table.)
To the write disabled block, write cannot be made, and only read can be made.

\*1 3bits including BR25H080/160/320-WC WPEN (bit7)

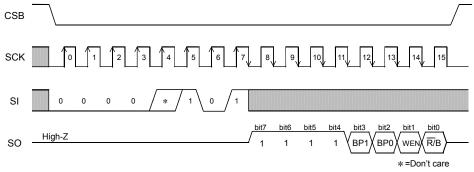


Fig.41 Status register read command (BR25H010/020/040-WC)

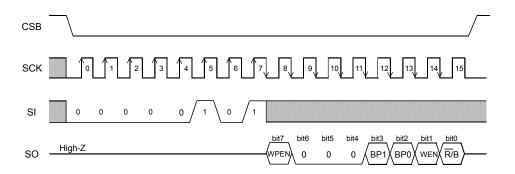


Fig.42 Status register read command (BR25H080/160/320-WC)

#### At Standby

#### OCurrent at standby

Set CSB "H", and be sure to set SCK, SI, WPB, HOLDB input "L" or "H". Do not input intermediate electric potantial.

#### **OTiming**

As shown in Fig.43, at standby, when SCK is "H", even if CSB is fallen, SI status is not read at fall edge. SI status is read at SCK rise edge after fall of CSB. At standby and at power ON/OFF, set CSB "H" status.

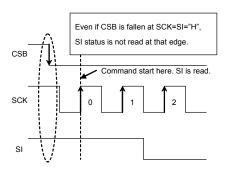


Fig.43 Operating timing

#### ■WPB Cancel Valid Area

WPB is normally fixed to "H" or "L" for use, but when WPB is controlled so as to cancel write status register command and write command, pay attention to the following WPB valid timing.

While write or write status register command is executed, by setting WPB = "L" in cancel valid area, command can be cancelled. The area from command ope code before CSB rise at internal automatic write start becomes the cancel valid area. However, once write is started, any input cannot be cancelled. WPB input becomes Don't Care, and cancellation becomes invalid.

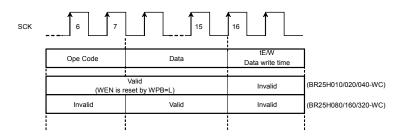


Fig.44 WPB valid timing (WRSR)

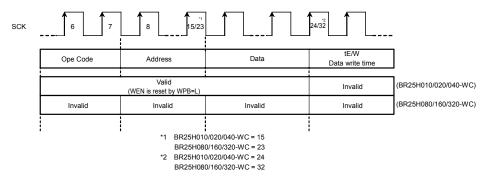


Fig.45 WPB valid timing (WRITE)

# ●HOLDB Pin

By HOLDB pin, command communication can be stopped temporarily (HOLD status). The HOLDB pin carries out command communications normally when it is HIGH. To get in HOLD status, at command communication, when SCK=LOW, set the HOLDB pin LOW. At HOLD status, SCK and SI become Don't Care, and SO becomes high impedance (High-Z). To release the HOLD status, set the HOLDB pin HIGH when SCK=LOW. After that, communication can be restarted from the point before the HOLD status. For example, when HOLD status is made after A5 address input at read, after release of HOLD status, by starting A4 address input, read can be restarted. When in HOLD status, leave CSB LOW. When it is set CSB=HIGH in HOLD status, the IC is reset, therefore communication after that cannot be restarted.

#### Method to Cancel Each Command

#### **OREAD**

• Method to cancel: cancel by CSB = "H"



Fig.46 READ cancel valid timing

#### **ORDSR**

Method to cancel: cancel by CSB = "H"

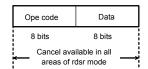


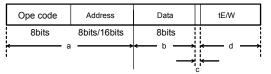
Fig.47 RDSR cancel valid timing

# OWRITE, PAGE WRITE

- a : Ope code, address input area. Cancellation is available by CSB="H"
- b : Data input area (D7 to D1 input area) Cancellation is available by CSB="H"
- c : Data input area (D0 area) When CSB is started, write starts.

  After CSB rise, cancellation cannot be made by any means.

  d : tE/W area.
  - Cancellation is available by CSB = "H". However, when write starts (CSB is started) in the area c, cancellation cannot be made by any means. And by inputting on SCK clock, cancellation cannot be made. In page write mode, there is write enable area at every 8 clocks.



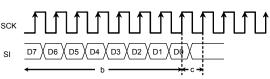


Fig.48 WRITE cancel valid timing

- Note 1) If  $V_{CC}$  is made OFF during write execution, designated address data is not guaranteed, therefore write it once again.
- Note 2) If CSB is started at the same timing as that of the SCK rise, write execution / cancel becomes unstable, therefore, it is recommended to fall in SCK = "L" area. As for SCK rise, assure timing of tCSS / tCSH or higher.

#### **OWRSR**

- a : From ope code to 15 rise. Cancel by CSB ="H".
- b : From 15 clock rise to 16 clock rise (write enable area).When CSB is started, write starts.After CSB rise, cancellation cannot be made by any means.
- c : After 16 clock rise.

  Cancel by CSB="H". However, when write starts (CSB is started) in the area b, cancellation cannot be made by any means.

  And, by inputting on SCK clock, cancellation cannot be made.

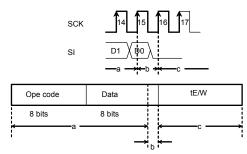


Fig.49 WRSR cancel valid timing

Note 1) If V<sub>CC</sub> is made OFF during write execution, designated address data is not guaranteed, therefore write it once again Note 2) If CSB is started at the same timing as that of the SCK rise, write execution / cancel becomes unstable, therefore, it is recommended to fall in SCK = "L" area. As for SCK rise, assure timing of tCSS / tCSH or higher.

#### OWREN/WRDI

- a: From ope code to 7-th clock rise, cancel by CSB = "H".
- b : Cancellation is not available when CSB is started after 7-th clock.

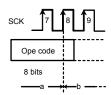


Fig.50 WREN/WRDI cancel valid timing

# High Speed Operation

In order to realize stable high speed operations, pay attention to the following input / output pin conditions.

#### Olnput pin pull up, pull down resistance

When to attach pull up, pull down resistance to EEPROM input pin, select an appropriate value for the microcontroller VOL. IOL from VIL characteristics of this IC.

#### OPull up resistance

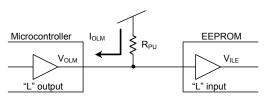


Fig.51 Pull up resistance

 $R_{PU} \ge \frac{V_{CC} - V_{OLM}}{I_{OLM}} \cdots$   $V_{OLM} \le V_{ILE} \cdots$ 

Example) When Vcc=5V,  $V_{ILE}$ =1.5V,  $V_{OLM}$ =0.4V,  $I_{OLM}$ =2mA, from the equation ①,

$$R_{PU} \ge \frac{5-0.4}{2 \times 10^{-3}}$$

$$\therefore R_{PU} \ge 2.3[k\Omega]$$

With the value of Rpu to satisfy the above equation,  $V_{OLM}$  becomes 0.4V or lower, and with  $V_{ILE}$  (=1.5V), the equation ② is also satisfied.

- $V_{\text{ILE}}\,$  :EEPROM  $V_{\text{IL}}$  specifications
- V<sub>OLM</sub>: Microcontroller V<sub>OL</sub> specifications
- · I<sub>OLM</sub> :Microcontroller I<sub>OL</sub> specifications

And, in order to prevent malfunction, mistake write at power ON/OFF, be sure to make CSB pull up.

#### OPull down resistance

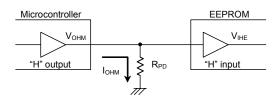


Fig.52 Pull down resistance

$$R_{PD} \ge \frac{V_{OHM}}{I_{OHM}} \cdots 3$$

$$V_{OHM} \ge V_{IHE} \cdots 4$$

Example) When  $V_{CC}$ =5V,  $V_{OHM}$ = $V_{CC}$ -0.5V,  $I_{OHM}$ =0.4mA,  $V_{IHE}$ = $V_{CC}$ ×0.7V, from the equation③,

$$R_{PD} \ge \frac{5-0.5}{0.4 \times 10^{-3}}$$

$$\therefore R_{PU} \ge 11.3[k\Omega]$$

Further, by amplitude VIHE, VILE of signal input to EEPROM, operation speed changes. By inputting signal of amplitude of  $V_{CC}$  / GND level to input, more stable high speed operations can be realized. On the contrary, when amplitude of  $0.8V_{CC}$  /  $0.2V_{CC}$  is input, operation speed becomes slow.<sup>\*1</sup>

In order to realize more stable high speed operation, it is recommended to make the values of  $R_{PU}$ ,  $R_{PD}$  as large as possible, and make the amplitude of signal input to EEPROM close to the amplitude of  $V_{CC}$  / GND level. (\*1 At this moment, operating timing guaranteed value is guaranteed.)

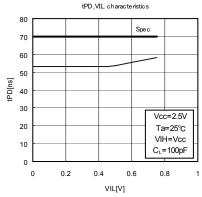


Fig.53 VIL dependency of data output delay time tPD

# OSO load capacity condition

Load capacity of SO output pin affects upon delay characteristic of SO output. (Data output delay time, time from HOLDB to High-Z) In order to make output delay characteristic into higher speed, make SO load capacity small. In concrete, "Do not connect many devices to SO bus", "Make the wire between the controller and EEPROM short", and so forth.

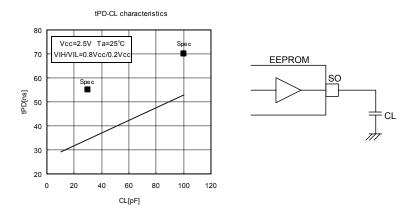


Fig.54 SO load dependency of data output delay time tPD

#### OOther cautions

Make the wire length from the microcontroller to EEPROM input signal same length, in order to prevent setup / hold violation to EEPROM, owing to difference of wire length of each input.

# ●Input / Output Circuit OOutput circuit

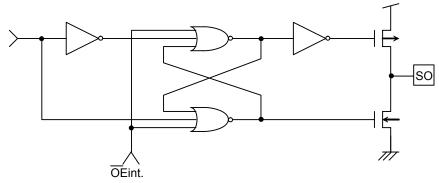


Fig.55 SO output equivalent circuit

# Olnput circuit

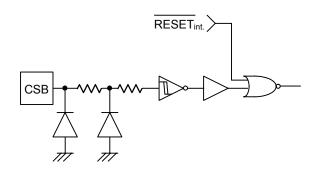


Fig.56 CSB input equivalent circuit

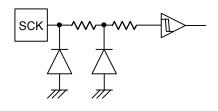


Fig.57 SCK input equivalent circuit

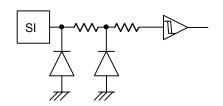


Fig.58 SI input equivalent circuit

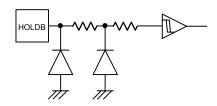


Fig.59 HOLDB input equivalent circuit

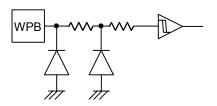


Fig.60 WPB input equivalent circuit

#### ●Notes on Power ON/OFF

OAt power ON/OFF, set CSB "H" (=V<sub>CC</sub>).

When CSB is "L", this IC gets in input accept status (active). If power is turned on in this status, noises and the likes may cause malfunction, mistake write or so. To prevent these, at power ON, set CSB "H". (When CSB is in "H" status, all inputs are canceled.)

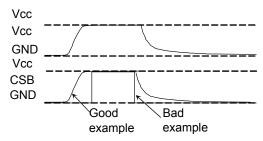


Fig.61 CSB timing at power ON/OFF

(Good example) CSB terminal is pulled up to V<sub>CC</sub>.

At power OFF, take 10ms or higher before supply. If power is turned on without observing this condition, the IC internal circuit may not be reset, which please note.

(Bad example) CSB terminal is "L" at power ON/OFF.

In this case, CSB always becomes "L" (active status), and EEPROM may have malfunction, mistake write owing to noises and the likes.

Even when CSB input is High-Z, the status becomes like this case, which please note.

#### **OLVCC** circuit

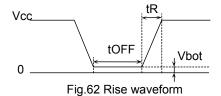
LVCC (V<sub>CC</sub>-Lockout) circuit prevents data rewrite action at low power, and prevents wrong write.

At LVCC voltage (Typ. =1.9V) or below, it prevent data rewrite.

#### OP.O.R. circuit

This IC has a POR (Power On Reset) circuit as mistake write countermeasure. After POR action, it gets in write disable status. The POR circuit is valid only when power is ON, and does not work when power is OFF. When power is ON, if the recommended conditions of the following tR, tOFF, and Vbot are not satisfied, it may become write enable status owing to noises and the likes.

Recommended conditions of  $t_{\text{R}}$ ,  $t_{\text{OFF}}$ , Vbot



tr	toff	Vbot	
10ms or below	10ms or higher	0.3V or below	
100ms or below	10ms or higher	0.2V or below	

#### ■Noise Countermeasures

OV<sub>CC</sub> noise (bypass capacitor)

When noise or surge gets in the power source line, malfunction may occur, therefore, for removing these, it is recommended to attach a bypass capacitor  $(0.1\mu F)$  between IC  $V_{CC}$  and GND. At that moment, attach it as close to IC as possible. And, it is also recommended to attach a bypass capacitor between board  $V_{CC}$  and GND.

#### OSCK noise

When the rise time (tR) of SCK is long, and a certain degree or more of noise exists, malfunction may occur owing to clock bit displacement. To avoid this, a Schmitt trigger circuit is built in SCK input. The hysterisis width of this circuit is set about 0.2V, if noises exist at SCK input, set the noise amplitude 0.2Vp-p or below. And it is recommended to set the rise time (tR) of SCK 100ns or below. In the case when the rise time is 100ns or higher, take sufficient noise countermeasures. Make the clock rise, fall time as small as possible.

#### OWPB noise

During execution of write status register command, if there exist noises on WPB pin, mistake in recognition may occur and forcible cancellation may result, which please note. To avoid this, a Schmitt trigger circuit is built in WPB input. In the same manner, a Schmitt trigger circuit is built in CSB input, SI input and HOLDB input too.

#### Notes of Use

- (1) Described numeric values and data are design representative values, and the values are not guaranteed.
- (2) We believe that application circuit examples are recommendable, however, in actual use, confirm characteristics further sufficiently. In the case of use by changing the fixed number of external parts, make your decision with sufficient margin in consideration of static characteristics and transition characteristics and fluctuations of external parts and our LSI.
- (3) Absolute maximum ratings

If the absolute maximum ratings such as impressed voltage and operating temperature range and so forth are exceeded, LSI may be destructed. Do not impress voltage and temperature exceeding the absolute maximum ratings. In the case of fear exceeding the absolute maximum ratings, take physical safety countermeasures such as fuses, and see to it that conditions exceeding the absolute maximum ratings should not be impressed to LSI.

(4) GND electric potential

Set the voltage of GND terminal lowest at any action condition. Make sure that each terminal voltage is higher than that of GND terminal.

- (5) Heat design
  - In consideration of permissible dissipation in actual use condition, carry out heat design with sufficient margin.
- (6) Terminal to terminal short circuit and wrong packaging

When to package LSI onto a board, pay sufficient attention to LSI direction and displacement. Wrong packaging may destruct LSI. And in the case of short circuit between LSI terminals and terminals and power source, terminal and GND owing to foreign matter, LSI may be destructed.

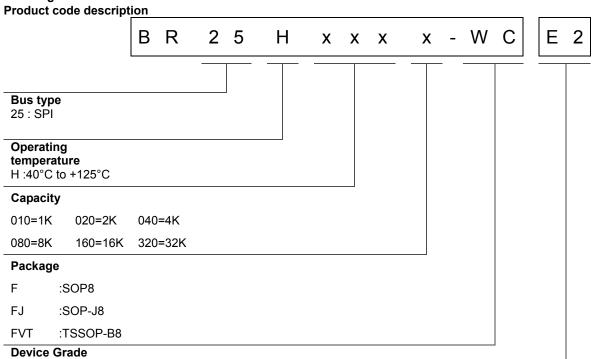
(7) Use in a strong electromagnetic field may cause malfunction, therefore, evaluate design sufficiently.

#### Status of this document

The Japanese version of this document is formal specification. A customer may use this translation version only for a reference to help reading the formal version.

If there are any differences in translation version of this document formal version takes priority.

# Ordering Information



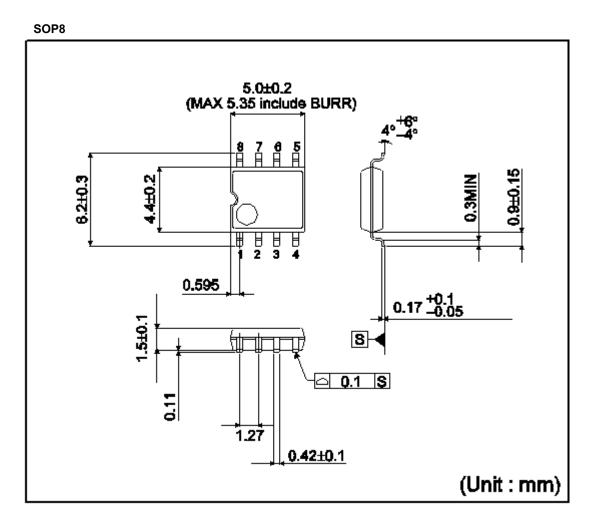
# Packaging and forming specification

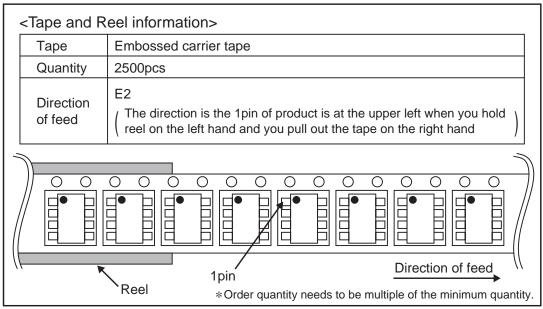
E2 :Embossed tape and reel

#### Lineup

Consoity	Package		Orderable Part Number
Capacity	Type	Quantity	Orderable Part Number
	SOP8	Reel of 2500	BR25H010F-WCE2
1K	SOP-J8	Reel of 2500	BR25H010FJ-WCE2
	TSSOP-B8	Reel of 3000	BR25H010FVT-WCE2
	SOP8	Reel of 2500	BR25H020F-WCE2
2K	SOP-J8	Reel of 2500	BR25H020FJ-WCE2
	TSSOP-B8	Reel of 3000	BR25H020FVT-WCE2
	SOP8	Reel of 2500	BR25H040F-WCE2
4K	SOP-J8	Reel of 2500	BR25H040FJ-WCE2
	TSSOP-B8	Reel of 3000	BR25H040FVT-WCE2
	SOP8	Reel of 2500	BR25H080F-WCE2
8K	SOP-J8	Reel of 2500	BR25H080FJ-WCE2
	TSSOP-B8	Reel of 3000	BR25H080FVT-WCE2
	SOP8	Reel of 2500	BR25H160F-WCE2
16K	SOP-J8	Reel of 2500	BR25H160FJ-WCE2
	TSSOP-B8	Reel of 3000	BR25H160FVT-WCE2
32K	SOP8	Reel of 2500	BR25H320F-WCE2
JZN	SOP-J8	Reel of 2500	BR25H320FJ-WCE2

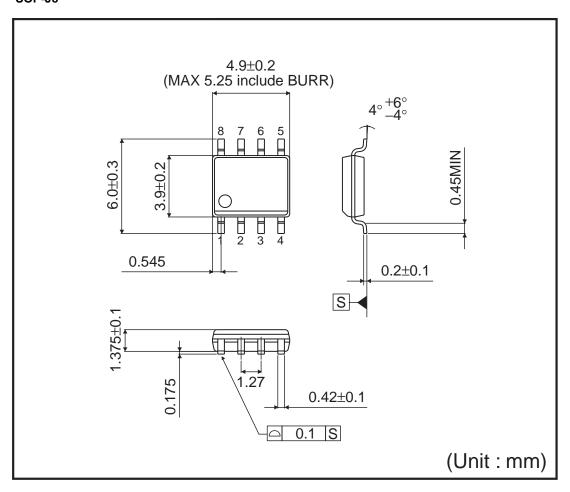
# ● Physical Dimensions Tape and Reel Information

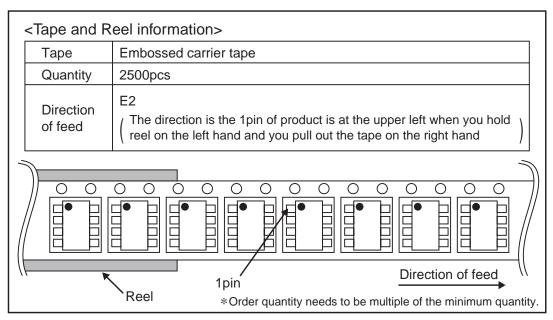




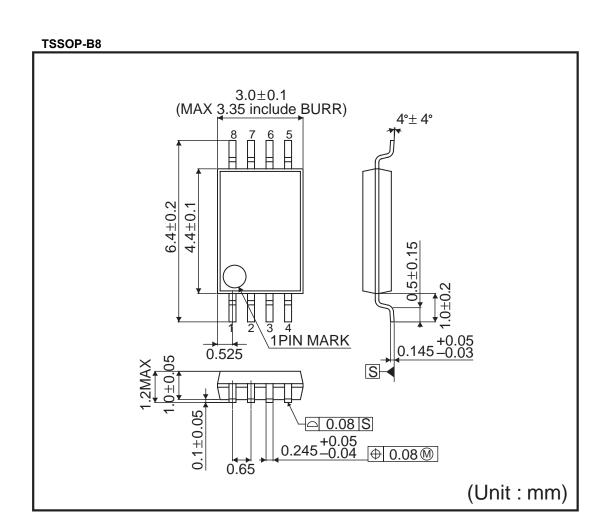
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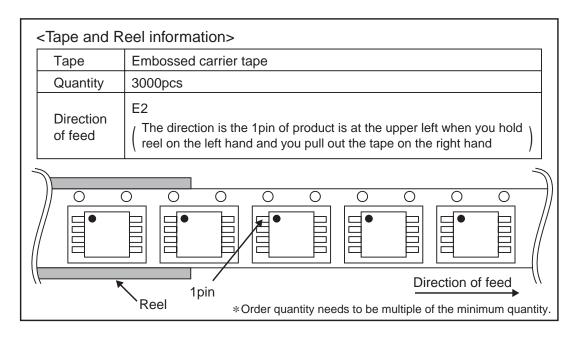
SOP-J8



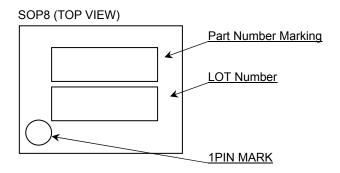


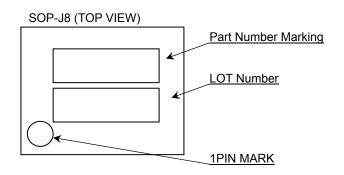
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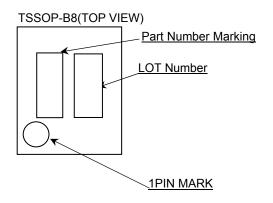




# Marking Diagrams







# Marking Information

Capacity	Product Name Marking	Package Type
		SOP8
1K	H010	SOP-J8
		TSSOP-B8
		SOP8
2K	H020	SOP-J8
		TSSOP-B8
		SOP8
4K	H040	SOP-J8
		TSSOP-B8
		SOP8
8K	H080	SOP-J8
		TSSOP-B8
		SOP8
16K	H160	SOP-J8
		TSSOP-B8
32K	HSSO	SOP8
J2N	H320	SOP-J8

# Revision History

Date	Revision	Changes
23.May.2012	001	New Release

# **Notice**

#### General Precaution

- 1) Before you use our Products, you are requested to carefully read this document and fully understand its contents. ROHM shall not be in any way responsible or liable for failure, malfunction or accident arising from the use of any ROHM's Products against warning, caution or note contained in this document.
- 2) All information contained in this document is current as of the issuing date and subject to change without any prior notice. Before purchasing or using ROHM's Products, please confirm the latest information with a ROHM sales representative.

#### Precaution on using ROHM Products

- Our Products are designed and manufactured for application in ordinary electronic equipments (such as AV equipment, OA equipment, telecommunication equipment, home electronic appliances, amusement equipment, etc.). If you intend to use our Products in devices requiring extremely high reliability (such as medical equipment, transport equipment, traffic equipment, aircraft/spacecraft, nuclear power controllers, fuel controllers, car equipment including car accessories, safety devices, etc.) and whose malfunction or failure may cause loss of human life, bodily injury or serious damage to property ("Specific Applications"), please consult with the ROHM sales representative in advance. Unless otherwise agreed in writing by ROHM in advance, ROHM shall not be in any way responsible or liable for any damages, expenses or losses incurred by you or third parties arising from the use of any ROHM's Products for Specific Applications.
- 2) ROHM designs and manufactures its Products subject to strict quality control system. However, semiconductor products can fail or malfunction at a certain rate. Please be sure to implement, at your own responsibilities, adequate safety measures including but not limited to fail-safe design against the physical injury, damage to any property, which a failure or malfunction of our Products may cause. The following are examples of safety measures:
  - [a] Installation of protection circuits or other protective devices to improve system safety
  - [b] Installation of redundant circuits to reduce the impact of single or multiple circuit failure
- 3) Our Products are designed and manufactured for use under standard conditions and not under any special or extraordinary environments or conditions, as exemplified below. Accordingly, ROHM shall not be in any way responsible or liable for any damages, expenses or losses arising from the use of any ROHM's Products under any special or extraordinary environments or conditions. If you intend to use our Products under any special or extraordinary environments or conditions (as exemplified below), your independent verification and confirmation of product performance, reliability, etc, prior to use, must be necessary:
  - [a] Use of our Products in any types of liquid, including water, oils, chemicals, and organic solvents
  - [b] Use of our Products outdoors or in places where the Products are exposed to direct sunlight or dust
  - [c] Use of our Products in places where the Products are exposed to sea wind or corrosive gases, including Cl<sub>2</sub>, H<sub>2</sub>S, NH<sub>3</sub>, SO<sub>2</sub>, and NO<sub>2</sub>
  - [d] Use of our Products in places where the Products are exposed to static electricity or electromagnetic waves
  - [e] Use of our Products in proximity to heat-producing components, plastic cords, or other flammable items
  - If Sealing or coating our Products with resin or other coating materials
  - [g] Use of our Products without cleaning residue of flux (even if you use no-clean type fluxes, cleaning residue of flux is recommended); or Washing our Products by using water or water-soluble cleaning agents for cleaning residue after soldering
  - [h] Use of the Products in places subject to dew condensation
- 4) The Products are not subject to radiation-proof design.
- 5) Please verify and confirm characteristics of the final or mounted products in using the Products.
- 6) In particular, if a transient load (a large amount of load applied in a short period of time, such as pulse) is applied, confirmation of performance characteristics after on-board mounting is strongly recommended. Avoid applying power exceeding normal rated power; exceeding the power rating under steady-state loading condition may negatively affect product performance and reliability.
- 7) De-rate Power Dissipation (Pd) depending on Ambient temperature (Ta). When used in sealed area, confirm the actual ambient temperature.
- 8) Confirm that operation temperature is within the specified range described in the product specification.
- 9) ROHM shall not be in any way responsible or liable for failure induced under deviant condition from what is defined in this document.

#### Precaution for Mounting / Circuit board design

- 1) When a highly active halogenous (chlorine, bromine, etc.) flux is used, the residue of flux may negatively affect product performance and reliability.
- 2) In principle, the reflow soldering method must be used; if flow soldering method is preferred, please consult with the ROHM representative in advance.

For details, please refer to ROHM Mounting specification

#### Precautions Regarding Application Examples and External Circuits

- If change is made to the constant of an external circuit, please allow a sufficient margin considering variations of the characteristics of the Products and external components, including transient characteristics, as well as static characteristics.
- You agree that application notes, reference designs, and associated data and information contained in this document are presented only as guidance for Products use. Therefore, in case you use such information, you are solely responsible for it and you must exercise your own independent verification and judgment in the use of such information contained in this document. ROHM shall not be in any way responsible or liable for any damages, expenses or losses incurred by you or third parties arising from the use of such information.

#### Precaution for Electrostatic

This Product is electrostatic sensitive product, which may be damaged due to electrostatic discharge. Please take proper caution in your manufacturing process and storage so that voltage exceeding the Products maximum rating will not be applied to Products. Please take special care under dry condition (e.g. Grounding of human body / equipment / solder iron, isolation from charged objects, setting of lonizer, friction prevention and temperature / humidity control).

#### Precaution for Storage / Transportation

- 1) Product performance and soldered connections may deteriorate if the Products are stored in the places where:
  - [a] the Products are exposed to sea winds or corrosive gases, including Cl2, H2S, NH3, SO2, and NO2
  - [b] the temperature or humidity exceeds those recommended by ROHM
  - [c] the Products are exposed to direct sunshine or condensation
  - [d] the Products are exposed to high Electrostatic
- 2) Even under ROHM recommended storage condition, solderability of products out of recommended storage time period may be degraded. It is strongly recommended to confirm solderability before using Products of which storage time is exceeding the recommended storage time period.
- 3) Store / transport cartons in the correct direction, which is indicated on a carton with a symbol. Otherwise bent leads may occur due to excessive stress applied when dropping of a carton.
- 4) Use Products within the specified time after opening a humidity barrier bag. Baking is required before using Products of which storage time is exceeding the recommended storage time period.

# ●Precaution for Product Label

QR code printed on ROHM Products label is for ROHM's internal use only.

#### Precaution for Disposition

When disposing Products please dispose them properly using an authorized industry waste company.

# ● Precaution for Foreign Exchange and Foreign Trade act

Since our Products might fall under controlled goods prescribed by the applicable foreign exchange and foreign trade act, please consult with ROHM representative in case of export.

#### Precaution Regarding Intellectual Property Rights

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#### Other Precaution

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