

# AS1543/44

## 8/4-Channel, 1 Msps, 12-Bit ADC with Sequencer

### 1 General Description

The AS1543/44 is a 12-bit high-speed, low-power, 8/4-channel, successive-approximation ADC that operates from a single 2.7 to 5.25V supply. The device features high throughput rates (1Msps) and a low-noise, wide-bandwidth track-and-hold amplifier that can handle input frequencies in excess of 1 MHz.

The AS1543 features 8 single-ended or 4 fully differential analog inputs while the AS1544 offers 4 single-ended or 2 fully differential analog inputs. Both include a channel sequencer to allow a programmed selection of channels to be converted sequentially. The conversion time is determined by the SCLK frequency (also used as the master clock to control the conversion).

The conversion process and data acquisition are controlled using a chip select pin and a serial clock signal, allowing the device to easily interface with microprocessors or DSPs. The input signal is sampled on the falling edge of CSN and conversion is also initiated at this point. There are no pipeline delays associated with the device.

The AS1543/44 uses advanced design techniques to achieve very low power dissipation at high throughput rates. At maximum throughput rates, the AS1543/44 consumes just 2.8mA (@3.6V), and 3.5mA (@5.25V).

By using internal control register, single-ended or fully-differential conversion mode with different input ranges can be used with either straight binary or twos complement output coding.

The device is available in a QFN(4x4)-20 pin package.

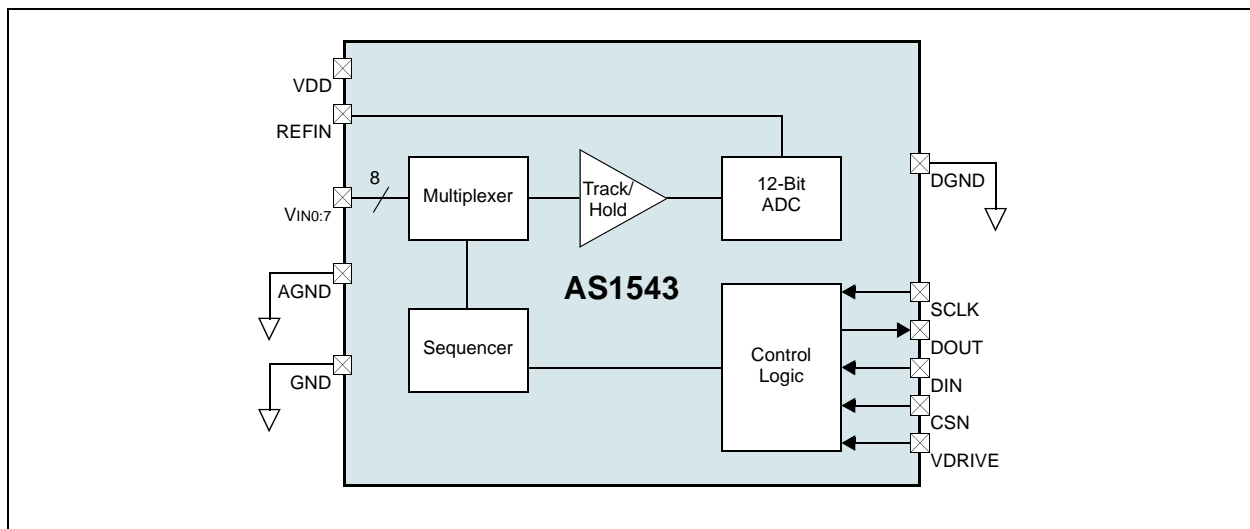
### 2 Key Features

- Single Supply Operation with VDRIVE Function: 2.7 to 5.25V
- Fast Throughput Rate: 1 Msps
- Sequencer & Channel Counter
- Software-Configurable Analog Input Types:
  - 8/4-Channel Single-Ended
  - 4/2-Channel Fully-Differential
- Software-Configurable Input Range
- Low Power Consumption at Max Throughput Rates:
  - 10.1mW @ 1Msps (3.6V Supply)
  - 18.4mW @ 1Msps (5.25V Supply)
- Shutdown Mode Current: 0.5µA
- Flexible Power/Serial Clock Speed Management
- Wide Input Bandwidth: 71dB SNR @ 50 kHz Input Frequency
- No Pipeline Delays
- High Speed SPI/QSPI/Microwire/DSP Interface
- QFN(4x4)-20 Package

### 3 Applications

The devices are ideal for remote sensors, data-acquisition and data-logging devices, pen-digitizers, process control, or any other space-limited A/D application with low power-consumption requirements.

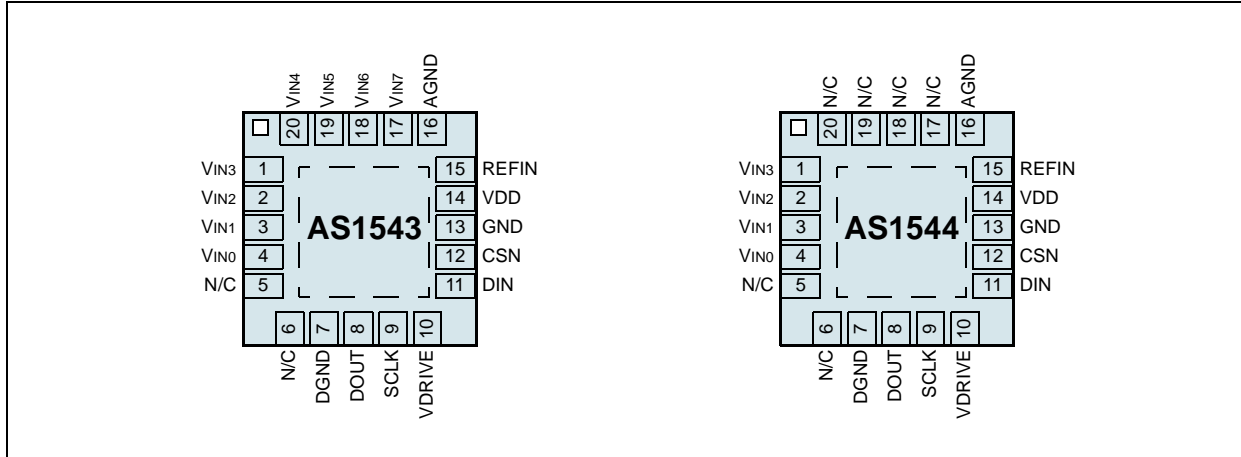
Figure 1. AS1543 - Block Diagram



## 4 Pinout

### Pin Assignments

Figure 2. Pin Assignments (Top View)



### Pin Descriptions

Table 1. Pin Descriptions

Pin Number	Pin Name	Description
(see Figure 2)	VINX	<b>Analog Inputs.</b> 8/4 single-ended or 4/2 fully-differential analog input channels that are multiplexed into the track-and-hold circuitry. Input channels are selected by using address bits <a href="#">ADDR3:ADDR0 (page 13)</a> of the control register. The address bits in conjunction with bits <a href="#">SEQ (page 13)</a> and <a href="#">SHADOW (page 13)</a> allow the sequence register to be programmed. The bit <a href="#">SE/FDN (page 13)</a> of the control register selects single-ended or fully-differential conversion mode. In case of single-ended mode the input range can extend from [0V to VREFIN] or [0V to 2 x VREFIN]. In case of fully-differential mode the differential input range can extend from [-VREFIN/2 to +VREFIN/2] or [-VREFIN to +VREFIN]. <b>Note:</b> Unused inputs should be connected to AGND to avoid noise.
	REFIN	<b>Reference Input.</b> An external reference must be applied to this input. The voltage range for the external reference is 2.5V ±1% for specified performance.
	SCLK	<b>Serial Clock.</b> Provides the serial clock for accessing data from the part. This clock input is also used as the clock source for the ADC conversion process
	VDD	<b>2.7 to 5.25V Supply Input.</b> For the [0V to 2 x VREFIN] range, VDD must be between 4.75 and 5.25V
	VDRIVE	<b>Logic Power Supply Input.</b> The voltage supplied at this pin determines the operating voltage of the AS1543/44 serial interface. VDRIVE ≤ VDD required.
	DOUT	<b>Digital Output.</b> The ADC conversion result is provided serially on this output. Data bits are clocked out on the falling edge of SCLK. The data stream consists of four address bits indicating the corresponding conversion channel, followed by 12 bits of conversion data (MSB first). Output coding may be selected as straight binary or two's complement depending on the setting of bit <a href="#">CODING (page 13)</a> .
	DIN	<b>Digital Input.</b> Data is clocked into to the AS1543/44 control register on this input (see <a href="#">Control Register on page 12</a> ).
	CSN	<b>Chip Select.</b> Active low input. Initiates conversions and also is used to frame the serial data transfer.
	AGND	<b>Analog Ground.</b> Ground reference point for all analog circuitry. All analog input signals and any external reference signal should be referenced to pin AGND. <b>Note:</b> AGND, GND and DGND pins must be connected together.
	DGND	<b>Digital Logic Ground.</b> Ground reference point for the VDRIVE logic power supply input. VDRIVE should be decoupled to pin DGND.
	GND	<b>Supply Ground.</b> Ground reference point for the VDD supply input. The supply input VDD should be decoupled to pin GND.

## 5 Absolute Maximum Ratings

Stresses beyond those listed in [Table 2](#) may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in [Electrical Characteristics on page 4](#) is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Table 2. Absolute Maximum Ratings

Parameter	Min	Max	Units	Comments
<b>Electrical Parameters</b>				
VDD to GND/ AGND/ DGND	-0.3	+7	V	
VDRIVE to GND/ AGND/ DGND	-0.3	VDD + 0.3	V	
VINx, REFIN to GND/ AGND/ DGND	-0.3	VDD + 0.3	V	
CSN, SCLK, DIN, DOUT to GND/ AGND/ DGND	-0.3	VDRIVE + 0.3	V	
Input Current (latch-up immunity) @ any pin except VDD and VINx	-100	+100	mA	Norm: JEDEC 78
<b>Electrostatic Discharge</b>				
Human Body Model		1	kV	Norm: MIL 883 E method 3015
<b>Temperature Ranges and Storage Conditions</b>				
Storage Temperature Range	-65	+150	°C	
Junction Temperature (T <sub>J-MAX</sub> )		+150	°C	
Package Body Temperature		+260	°C	The reflow peak soldering temperature (body temperature) specified is in accordance with IPC/JEDEC J-STD-020 "Moisture/Reflow Sensitivity Classification for Non-Hermetic Solid State Surface Mount Devices". The lead finish for Pb-free leaded packages is matte tin (100% Sn).
Humidity non-condensing	5	85	%	
Moisture Sensitive Level		1		Represents a max. floor life time of unlimited

## 6 Electrical Characteristics

$V_{DD} = V_{DRIVE} = 2.7$  to  $5.25V$ ,  $V_{REFIN} = 2.5V$ ,  $f_{SCLK} = 20MHz$  (50% Duty cycle),  $V_{CMIN} = V_{REFIN}/2$  (when  $SE/FDN = 0$ ), typical values at  $T_{AMB} = +25^{\circ}C$  and  $V_{DD} = V_{DRIVE} = 5.25V$  (unless otherwise specified). All limits are guaranteed. The parameters with min and max values are guaranteed with production tests or SQC (Statistical Quality Control) methods.

Table 3. Electrical Characteristics

Symbol	Parameter	Condition		Min	Typ	Max	Unit
TAMB	Operating Temperature Range			-40		+85	°C
<b>DC Accuracy</b>							
	Resolution					12	Bits
INL	Integral Nonlinearity					±1	LSB
DNL	Differential Nonlinearity	Straight Binary Output Coding; Guaranteed No Missed Codes to 12 Bits		-0.95		+1.2	LSB
	Offset Error	Bit SE/FDN = 1, bit CODING = 1	Bit RANGE = 1			±4	LSB
	Offset Error Match				±0.5		LSB
	Gain Error					±4	LSB
	Gain Error Match				±0.6		LSB
	Offset Error	Bit SE/FDN = 0, bit CODING = 0	Bit RANGE = 0			±4	LSB
	Offset Error Match				±0.5		LSB
	Gain Error					±4	LSB
	Gain Error Match				±0.6		LSB
	Zero Code Error	Bit SE/FDN = 0, bit CODING = 0	Bit RANGE = 1			±0.6	LSB
	Zero Code Error Match				±0.5		LSB
	Gain Error					±4	LSB
	Gain Error Match				±0.5		LSB
	Zero Code Error	Bit SE/FDN = 0, bit CODING = 0	Bit RANGE = 0			±0.6	LSB
	Zero Code Error Match				±0.5		LSB
	Gain Error					±4	LSB
	Gain Error Match				±0.5		LSB
<b>Dynamic Specifications</b> 50kHz sinewave input							
SINAD	Signal to Noise + Distortion Ratio	Bit RANGE = 1, bit SE/FDN = 1			71.2		dB
SNR	Signal-to-Noise Ratio				71.8		dB
THD	Total Harmonic Distortion				-82		dB
SFDR	Spurious-Free Dynamic Range				84		dB
SINAD	Signal to Noise + Distortion	Bit RANGE = 0, bit SE/FDN = 0, bit CODING = 0		68	71		dB
SNR	Signal-to-Noise Ratio			68.5	71.5		dB
THD	Total Harmonic Distortion				-83	-71	dB
SFDR	Spurious-Free Dynamic Range			73	85		dB
IMD	Intermodulation Distortion	$f_A = 40.1kHz$ , $f_B = 41.5kHz$	Second Order Terms		-83		dB
			Third Order Terms		-91		
	Channel-to-Channel Isolation	$f_{IN} = 400kHz$			-79		dB
	Full Power Bandwidth	@ 3dB			35		MHz
		@ 0.1dB			3.6		

Table 3. Electrical Characteristics (Continued)

Symbol	Parameter	Condition	Min	Typ	Max	Unit
<b>Conversion Rate</b>						
t <sub>CONV</sub>	Conversion Time	16 SCLK Cycles, SCLK = 20MHz			800	ns
	Track-and-Hold Acquisition Time				300	ns
	Throughput Rate				1	MSPS
	Aperture Delay			4		ns
	Aperture Jitter			50		ps
<b>Analog Input</b>						
V <sub>INx</sub>	Input Voltage Ranges	Bit SE/FDN = 1	Bit RANGE = 1	0	V <sub>REFIN</sub>	V
			Bit RANGE = 0	0	2 x V <sub>REFIN</sub>	
V <sub>INx</sub> - V <sub>INy</sub>	Differential Input Voltage Ranges	Bit SE/FDN = 0	Bit RANGE = 1	-V <sub>REFIN</sub> /2	V <sub>REFIN</sub> /2	V
			Bit RANGE = 0	-V <sub>REFIN</sub>	V <sub>REFIN</sub>	
V <sub>CMIN</sub>	Input Common Mode Voltage	Bit SE/FDN = 0	Bit RANGE = 1	V <sub>REFIN</sub> /2	V <sub>DD</sub> - V <sub>REFIN</sub> /2	V
			Bit RANGE = 0	V <sub>REFIN</sub>	V <sub>DD</sub> - V <sub>REFIN</sub>	
	DC Leakage Current			-1	+1	μA
	Input Capacitance				20	pF
<b>Reference Input</b>						
	REFIN Input Voltage <sup>1</sup>	2.5V ±1% for Specified Performance		1	V <sub>DD</sub>	V
	DC Leakage Current				±1	μA
	REFIN Input Impedance	f <sub>SAMPLE</sub> = 1MSPS		44		kΩ
<b>Digital Inputs: CSN, SCLK, DIN</b>						
V <sub>IH</sub>	Input High Voltage			0.7 x V <sub>DRIVE</sub>		V
V <sub>IL</sub>	Input Low Voltage				0.3 x V <sub>DRIVE</sub>	V
I <sub>IN</sub>	Input Current,	V <sub>IN</sub> = 0V or V <sub>DRIVE</sub>		-1	+1	μA
C <sub>IN</sub>	Input Capacitance				5	pF
<b>Digital Output: DOUT</b>						
V <sub>OH</sub>	Output High Voltage	I <sub>SOURCE</sub> = 200μA; V <sub>DD</sub> = 2.7 to 5.25V	V <sub>DRIVE</sub> - 0.2			V
V <sub>OL</sub>	Output Low Voltage	I <sub>SINK</sub> = 200μA			0.4	V
	Floating-State Leakage Current	Bit WEAK/TRIN (page 13) set to 0	-1		+1	μA
	Floating-State Output Capacitance	Bit WEAK/TRIN set to 0		10		pF
	Output Coding	Bit CODING (page 13) set to 1	Straight (natural) binary			
		Bit CODING set to 0	Two's complement			
<b>Power Requirements</b>						
V <sub>DD</sub>	Input Supply Range		2.75		5.25	V
V <sub>DRIVE</sub>	DRIVE Range	V <sub>DRIVE</sub> ≤ V <sub>DD</sub>	2.75		5.25	V

Table 3. Electrical Characteristics (Continued)

Symbol	Parameter	Condition	Min	Typ	Max	Unit	
IDD	Input Current	Normal Mode (Static)	VDD = 2.7 to 5.25V, SCLK On or Off		1.8		mA
		Normal Mode (Operational); fs = Max Throughput	VDD = 4.75 to 5.25V, fsCLK = 20 MHz		3.0	3.5	mA
			VDD = 2.7 to 3.6V, fsCLK = 20 MHz		2.4	2.8	mA
		Auto Shutdown Mode	fsAMPLE = 250ksps		1.4	1.6	mA
			Static		0.01	0.5	μA
	Power Dissipation (see Power vs. Throughput Rate on page 22).	Normal Mode (Operational); fsCLK = 20MHz	VDD = 4.75 to 5.25V			18.4	mW
			VDD = 2.7 to 3.6V			10.1	mW
		Auto Shutdown Mode (Static)	VDD = 4.75 to 5.25V			2.5	μW
			VDD = 2.7 to 3.6V			1.5	μW

1. When bit RANGE = 0 and bit SE/FDN = 1, VREFIN must not be larger than VDD/2.

### Timing Specifications

$V_{DD} = 2.7$  to  $5.25V$ ,  $V_{DRIVE} \leq V_{DD}$ ,  $REFIN = 2.5V$ ;  $T_{AMB} = -40$  to  $+85^{\circ}C$  (unless otherwise specified). Specifications based on load circuit shown in Figure 3 on page 7.

Table 4.

Symbol	Min	Typ	Max	Unit	Description
fSCLK	0.01		20	MHz	SCLK frequency
tCP	50			ns	SCLK periode
tQUIET	50			ns	Minimum quiet time required between bus relinquish and next conversion start.
tCSS	10			ns	CSN Fall to SCLK Fall Setup
tCSDOE			20	ns	CSN Fall to DOUT Enabled.
tCSDOV			40	ns	CSN Fall to DOUT Valid.
tCL	0.4 tCP			ns	SCLK Pulse Width Low.
tCH	0.4 tCP			ns	SCLK Pulse Width High.
tDOH	10			ns	SCLK Fall to DOUT Hold.
tDOV			50	ns	SCLK Fall to DOUT Valid.
tDOD	15		50	ns	SCLK Fall to DOUT Disable.
tDS	20			ns	DIN to SCLK Fall Setup.
tDH	5			ns	DIN to SCLK Fall Hold.
tCSH	20			ns	Sixteenth SCLK Fall to CSN Rise Hold.
tWAKEUP			1	$\mu s$	Power-up time from auto shutdown mode.

Figure 3. Load Circuit for Digital Output Timing Specifications

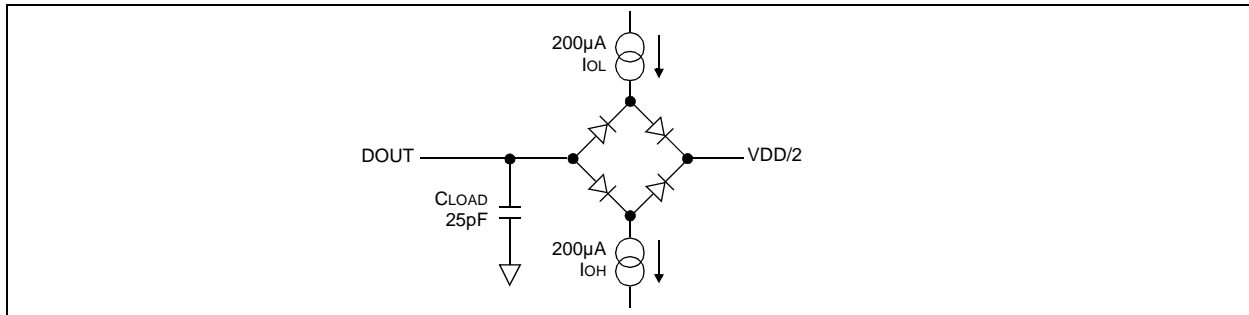
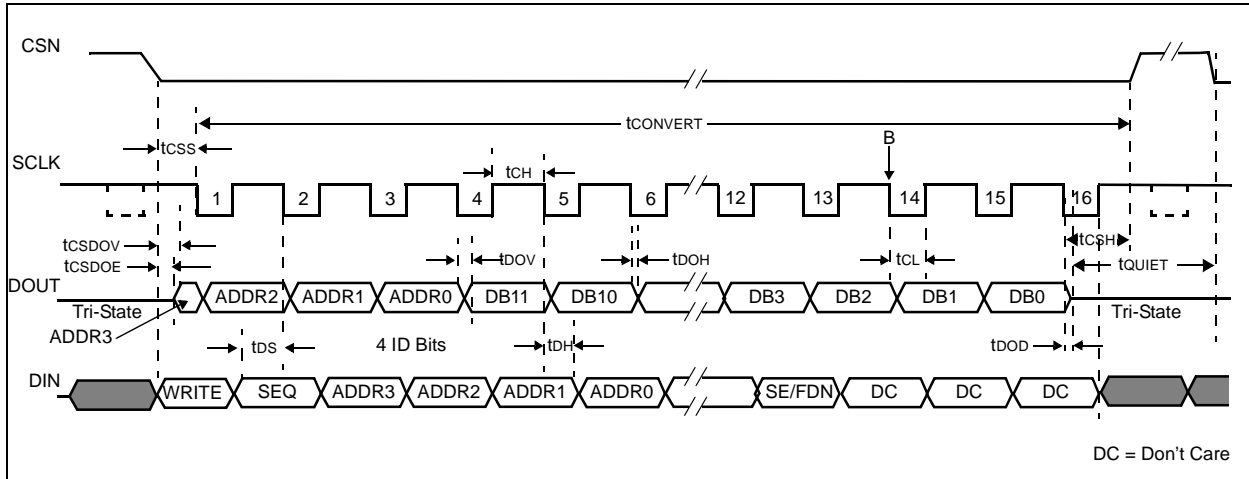


Figure 4. Serial Interface Timing Diagram



## 7 Typical Operating Characteristics

$V_{DD} = 5.25V$ ;  $V_{REF} = 2.5V$ ,  $C_{REF} = 4.7\mu F$ ,  $RANGE=1$ ,  $SE/FDN=1$ ,  $T_{AMB} = +25^{\circ}C$  (unless otherwise specified).

Figure 5. Integral Nonlinearity vs. Digital Output Code

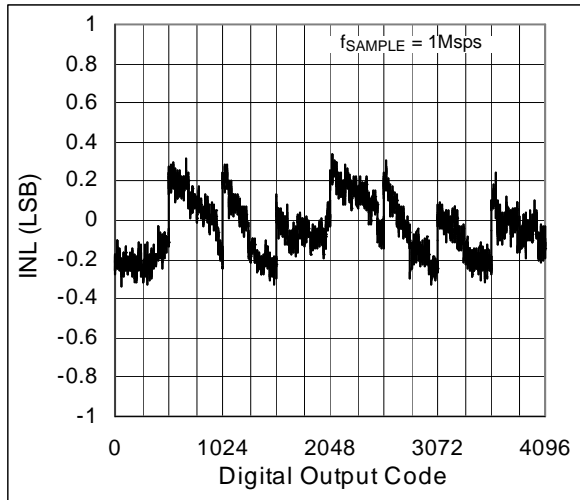


Figure 6. Differential Nonlinearity vs. Digital Output Code

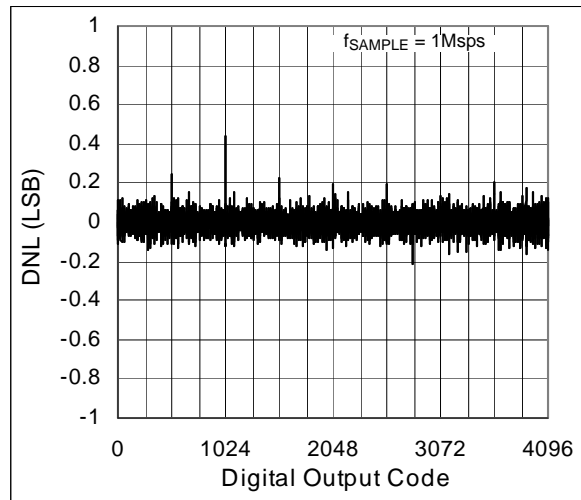


Figure 7. FFT @ 50kHz; RANGE=1, SE/FDN=1

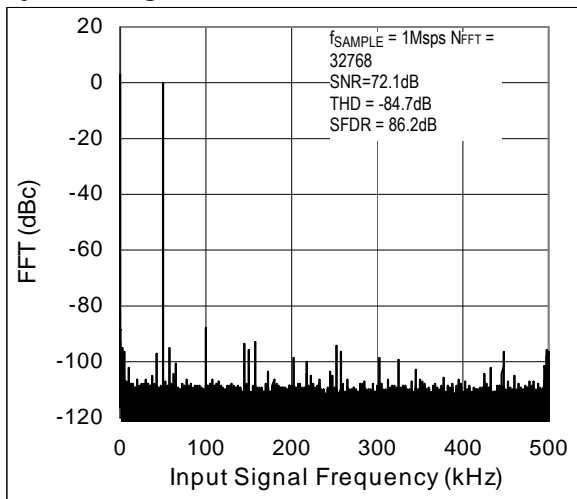


Figure 8. FFT @ 50kHz; RANGE=1, SE/FDN=0

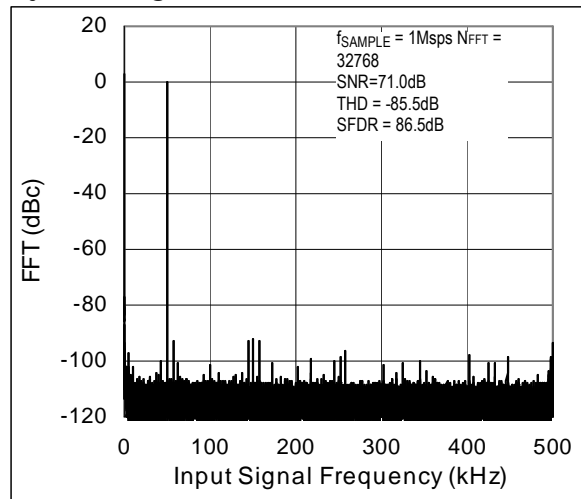


Figure 9. ENOB vs.  $V_{REFIN}$ ; RANGE=1, SE/FDN=1

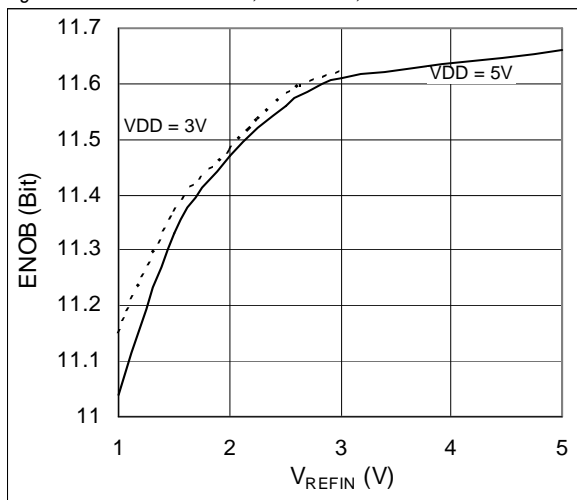


Figure 10. ENOB vs. Input Signal Frequency

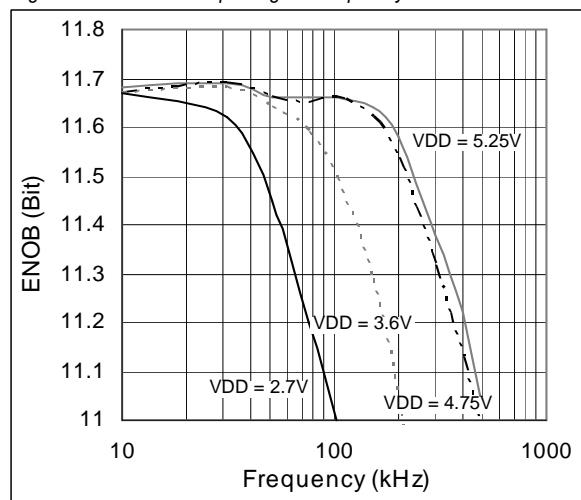




Figure 11. THD vs. Input Signal Frequency

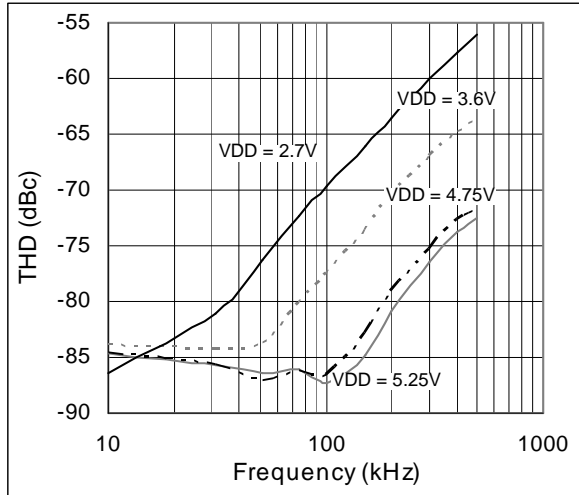


Figure 12. SINAD vs. Input Signal Frequency

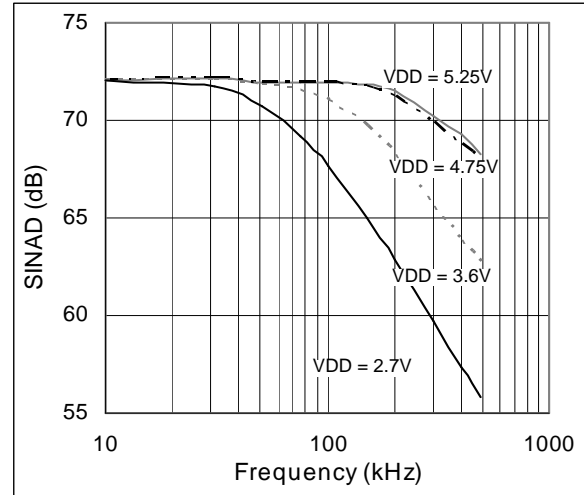


Figure 13. THD vs. Input Signal Frequency

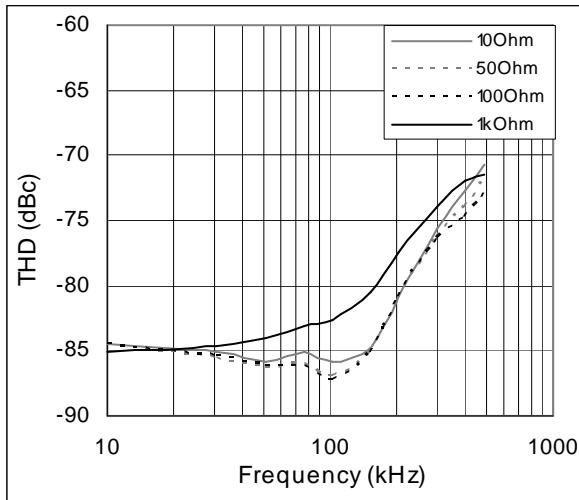


Figure 14. SINAD vs. Input Signal Frequency

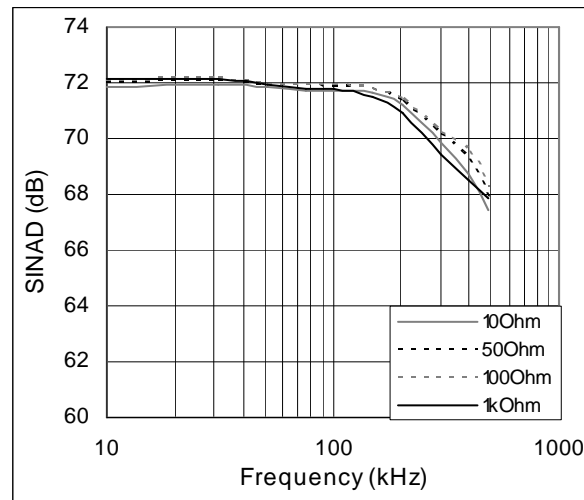


Figure 15. Supply Current vs. Supply Voltage

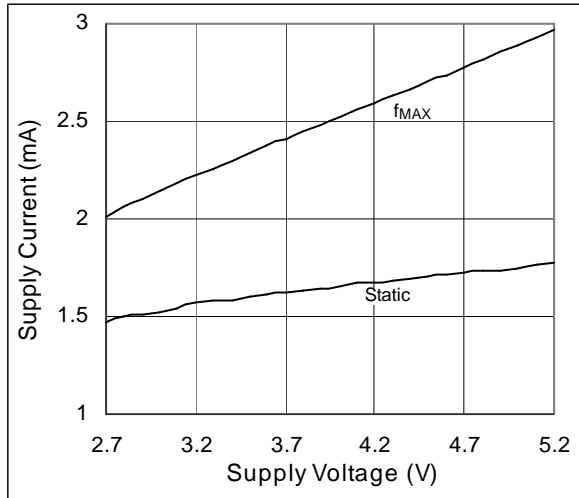


Figure 16. Supply Current vs. Temperature

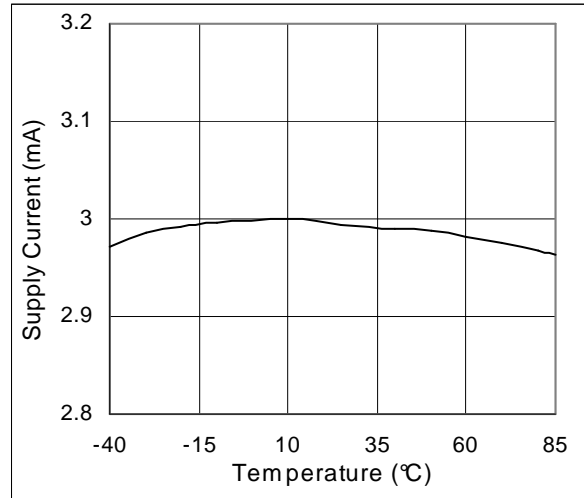


Figure 17. Shutdown Supply Current vs. VDD

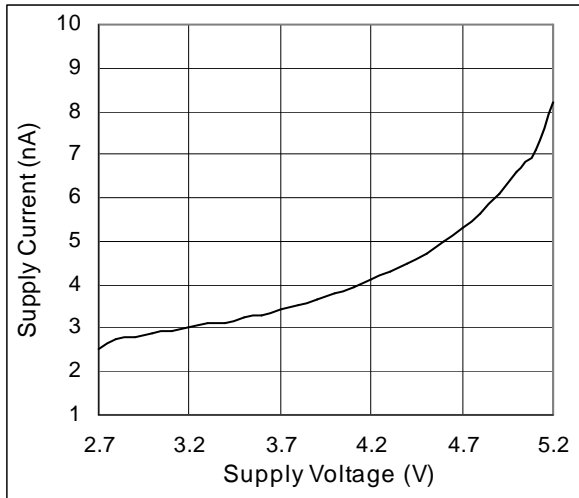


Figure 18. Shutdown Supply Current vs. Temp.

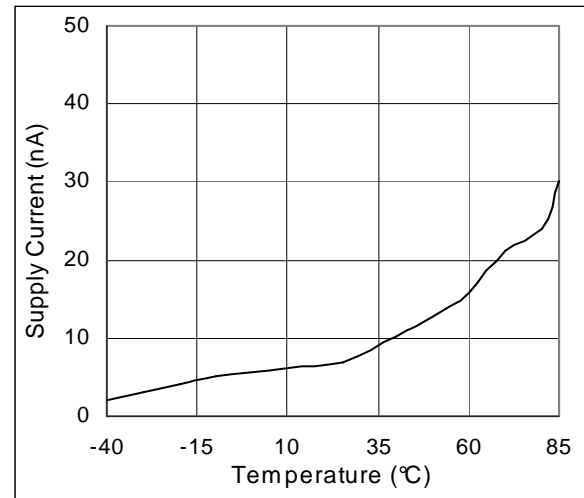


Figure 19. Supply Current vs. Throughput Rate

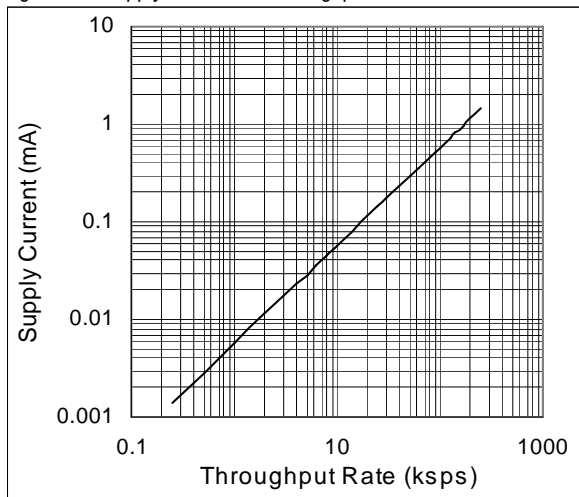
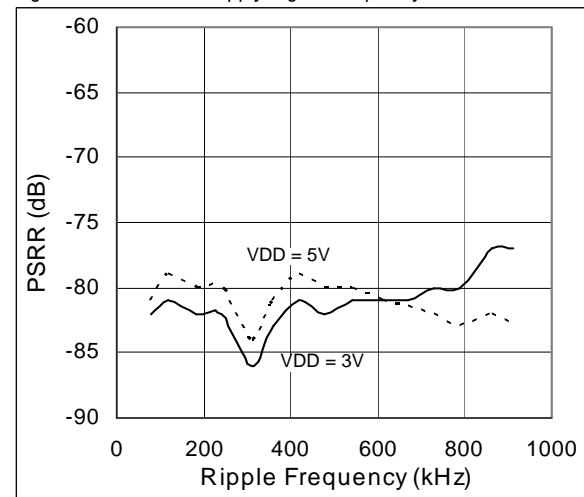


Figure 20. PSRR vs. Supply Signal Frequency



## 8 Detailed Description

The AS1543/44 is a fast, 8/4-channel, 12-bit, single-supply, A/D converter, which can be operated from a 2.7 to 5.25V supply. The AS1543/44 is capable of throughput rates of up to 1Msps when provided with a 20MHz clock. The AS1543/44 features on-chip track/hold, A/D converter, sequencer and a serial interface in a QFN(4x4)-20 package.

The AS1543/44 has 8/4 single-ended or 4/2 fully-differential input channels with a channel sequencer, allowing the selection of the sequence of channels the ADC can cycle through on (each consecutive CSN falling edge). The serial clock input accesses data from the AS1543/44, controls the transfer of data written to the ADC, and provides the clock source for the successive-approximation A/D converter.

The analog input range for the AS1543/44 is [0 to VREFIN] or [0V to 2 x VREFIN] for 8/4 single ended input channels or [-VREFIN/2 to +VREFIN/2] or [-VREFIN to +VREFIN] for 4/2 fully differential input channels depending on the setting of bit **RANGE** (page 13) and **SE/FDN** (page 13). For the [0V to 2 x VREFIN] mode, the device must be operated from a 4.75 to 5.25V supply.

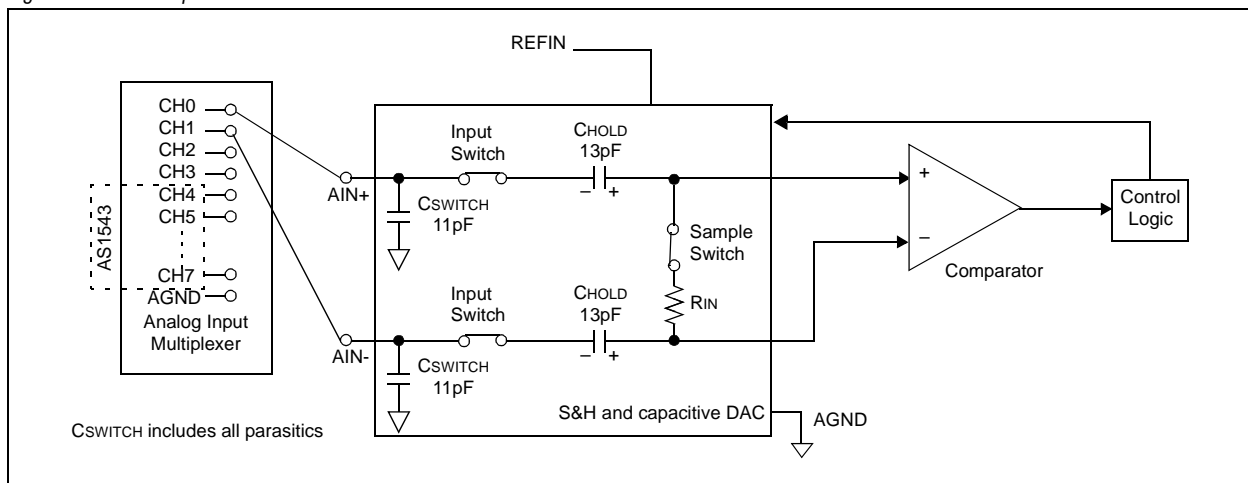
The AS1543/44 provides flexible power management options (see bits **PM1**, **PM0** (page 13) of the control register) for the best power performance for a given throughput rate.

### Converter Operation

The AS1543/44 is a 12-bit successive approximation analog-to-digital converter based around a capacitive DAC. The AS1543/44 can convert analog input signals in the range [0V to VREFIN] or [0V to 2 x VREFIN] or [-VREFIN/2 to +VREFIN/2] or [-VREFIN to +VREFIN] .

Figure 21 and Figure 22 show simplified diagrams of the ADC operation. The ADC circuitry is made up of control logic, SAR, and a capacitive DAC, which are used to redistribute fixed amounts of charge with the capacitive DAC to bring the comparator back into a balanced condition. Figure 21 shows the ADC during its acquisition phase. Sample switch and input switch are closed. The comparator is held in a balanced condition and the sampling capacitors **CHOLD** acquires the signal on the selected **VINx** channel.

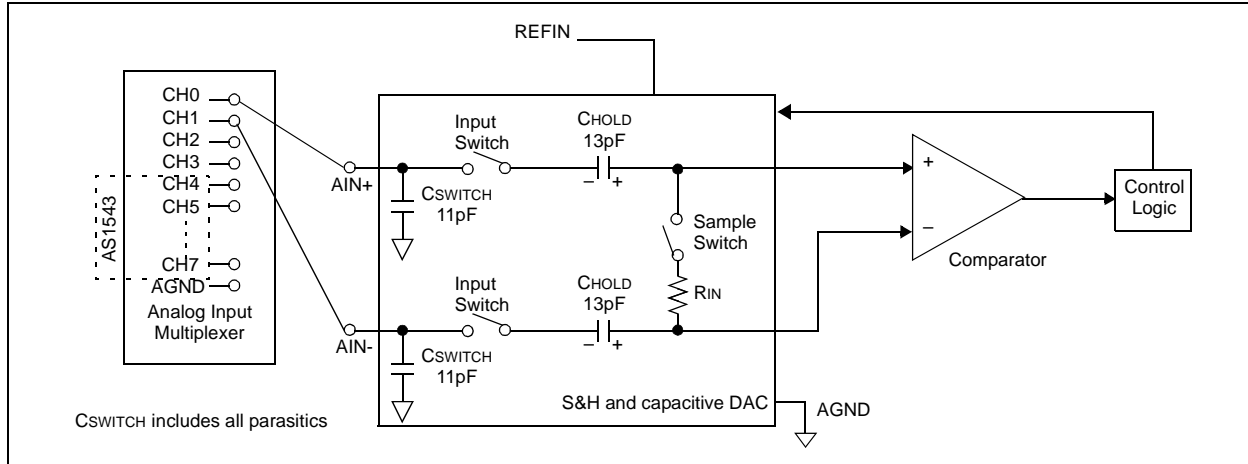
Figure 21. Data Acquisition



When a conversion is started (see Figure 22), sample switch and input switch opens causing the comparator to become unbalanced. The control logic and the capacitive DAC are used to redistribute fixed amounts of charge from the sampling capacitor to bring the comparator back into a balanced condition. When the comparator is re-balanced, the conversion is complete. Control logic generates the ADC output code.

See page 15 for the ADC transfer functions.

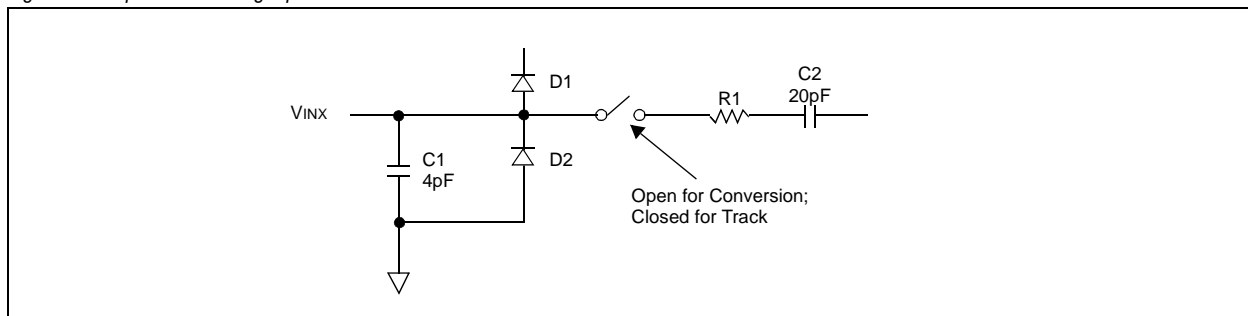
Figure 22. Data Conversion



## Analog Input

Figure 23 shows an equivalent circuit of one analog input. The two diodes, D1 and D2, provide ESD protection for the analog inputs. Care should be taken to ensure that the analog input signal never exceeds the supply rails by more than 300mV. This will cause these diodes to become forward biased and start conducting current into the substrate. 10mA is the maximum current these diodes can conduct without causing irreversible damage to the AS1543/44.

Figure 23. Equivalent Analog Input Circuit



Capacitor C1 in Figure 23 is typically about 4pF and can primarily be attributed to pin capacitance. The resistor R1 is a lumped component made up of the on-resistance of a switch (track/hold switch) and also includes the on-resistance of the input multiplexer. The total resistance is typically about 400Ω. Capacitor C2 is the ADC sampling capacitor and typically has a capacitance of 20pF.

## Track/Hold

The Track/Hold stage enters hold mode on the falling edge of CSN. For AC applications, removing high frequency components from the analog input signal is recommended by use of an R/C low-pass filter on the relevant analog input pin. In applications where harmonic distortion and signal-to-noise ratio are critical, the analog input should be driven from a low impedance source. Large source impedances will significantly affect the ac performance of the ADC. This may necessitate the use of an input buffer amplifier. The choice of the op-amp will be a function of the particular application.

When no amplifier is used to drive the analog input, the source impedance should be limited to low values. The maximum source impedance will depend on the amount of total harmonic distortion that can be tolerated. The THD will increase as the source impedance increases, and performance will degrade (see Figure 13 on page 9).

## Control Register

The AS1543/44 control register is a 13-bit, write-only register. Data is loaded into the register from pin DIN on the falling edge of the SCLK signal. Data is transferred on pin DIN at the same time as the conversion result is read from the device. The data transferred on pin DIN corresponds to the AS1543/44 configuration for the next conversion. This requires 16 serial clocks for every data transfer.

Only the information provided on the first 13 falling clock edges (after CSN falling edge) is loaded to the control register. The control register bits are defined in [Table 6](#).

Table 5. 12-Bit Control Register Format

12 (MSB)	11	10	9	8	7	6	5	4	3	2	1	0 (LSB)
WRITE	SEQ	ADDR3	ADDR2	ADDR1	ADDR0	PM1	PM0	SHADOW	WEAK/TRIN	RANGE	CODING	SE/FDN

Table 6. Control Register Bit Definitions

Bit Number	Bit Name	Description
12	WRITE	Determines if the subsequent 12 bits will be loaded to the control register. 1 = The subsequent 12 bits will be written to the control register. 0 = The subsequent 12 bits are not loaded to the control register and its contents are unchanged.
11	SEQ	This bit is used in conjunction with the SHADOW bit to control the sequencer ( <a href="#">see Table 11 on page 16</a> ) and access the shadow register ( <a href="#">see page 17</a> ).
10:7	ADDR3:ADDR0	These four address bits and the bit SE/FDN are loaded at the end of the present conversion sequence, and select which single analog input or pair of input channels is to be converted in the next serial transfer. The selected input channel is decoded as shown in <a href="#">Table 8 on page 14</a> . These bits also may select the final channel in a consecutive sequence as described in <a href="#">Table 11 on page 16</a> . The address bits corresponding to the conversion result are also output on DOUT prior to the 12 bits of data ( <a href="#">see Serial Interface on page 19</a> ). The next channel to be converted on will be selected by the multiplexer on the 14th SCLK falling edge.
6, 5	PM1, PM0	These two power management bits set the mode of operation of the AS1543/44 ( <a href="#">see Table 10 on page 16</a> ).
4	SHADOW	This bit is used in conjunction with the SEQ bit to control the sequencer ( <a href="#">see Table 11 on page 16</a> ) and access the shadow register ( <a href="#">see page 17</a> ).
3	WEAK/TRIN	This bit selects the state of pin DOUT upon completion of the current serial transfer. 1 = DOUT will be weakly driven to the channel address specified by bit ADDR3 of the subsequent conversion. 0 = DOUT will return to tri-state at the end of the serial transfer ( <a href="#">see Serial Interface on page 19</a> ).
2	RANGE	This bit selects the analog input range to be used for the subsequent conversion. This results in conjunction with bit SE/FDN in 4 possible analog input ranges, as explained in <a href="#">Table 7 on page 14</a> .
1	CODING	This bit selects the type of output coding to be used for the conversion result. 1 = The output coding for the next conversion is straight binary. 0 = The output coding for the next conversion is twos complement.
0	SE/FDN	This bit selects in conjunction with the address bits ADDR3:ADDR0 the input channels to be used ( <a href="#">see Table 8 on page 14</a> ). 1 = 8/4 single-ended input channels 0 = 4/2 fully-differential channels

## Analog Input Configuration

Table 7. Analog Input Configuration via bits RANGE and SE/FDN

Analog Input Configuration	RANGE	SE/FDN	Comments
8/4-channel single-ended	1	1	VINx from [0V to VREFIN]
	0	1	VINx from [0V to 2xVREFIN]
4/2-channel fully-differential	1	0	VINx - VINy from [-VREFIN/2 to +VREFIN/2]
	0	0	VINx - VINy from [-VREFIN to +VREFIN]

**Note:** If bit RANGE = 0 and bit SE/FDN = 1 VDD must be at least two times larger than VREFIN.

## Input Channel Selection

The input channels for conversion are selected using control register bits ADDR3:ADDR0 and bit SE/FDN.

Table 8. Channel Selection via Bits ADDR3:ADDR0 and SE/FDN, AS1544

	ADDR3	ADDR2	ADDR1	ADDR0	Analog Input Channel SE/FDN = 1 (Single-Ended)	Analog Input Channel SE/FDN = 0 (Fully-Differential)
AS1544	X	X	0	0	VIN0	VIN0 - VIN1
	X	X	0	1	VIN1	VIN1 - VIN0
	X	X	1	0	VIN2	VIN2 - VIN3
	X	X	1	1	VIN3	VIN3 - VIN2

Table 9. Channel Selection via Bits ADDR3:ADDR0 and SE/FDN, AS1543

	ADDR3	ADDR2	ADDR1	ADDR0	Analog Input Channel SE/FDN = 1 (Single-Ended)	Analog Input Channel SE/FDN = 0 (Fully-Differential)
AS1543	X	0	0	0	VIN0	VIN0 - VIN1
	X	0	0	1	VIN1	VIN1 - VIN0
	X	0	1	0	VIN2	VIN2 - VIN3
	X	0	1	1	VIN3	VIN3 - VIN2
	X	1	0	0	VIN4	VIN4 - VIN5
	X	1	0	1	VIN5	VIN5 - VIN4
	X	1	1	0	VIN6	VIN6 - VIN7
	X	1	1	1	VIN7	VIN7 - VIN6

**Transfer Functions**

Output coding and transfer function depend on the control register bits [RANGE](#) (page 13), [SE/FDN](#) (page 13) and [CODING](#) (page 13).

Figure 24. Straight Binary Transfer Function for SE/FDN = 1 and CODING = 1

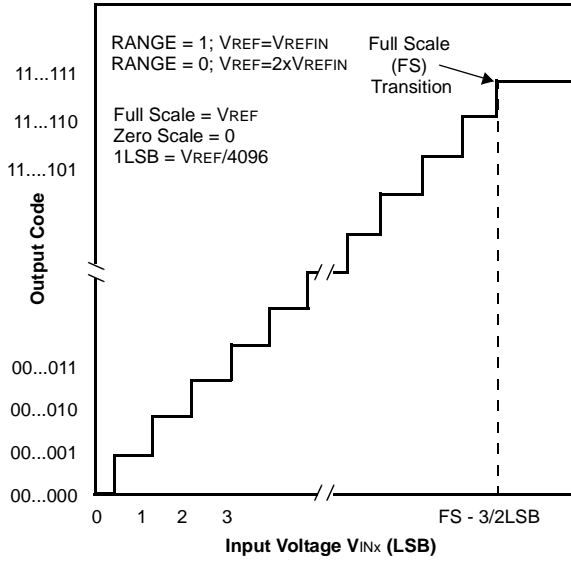


Figure 25. Straight Binary Transfer Function for SE/FDN = 0 and CODING = 1

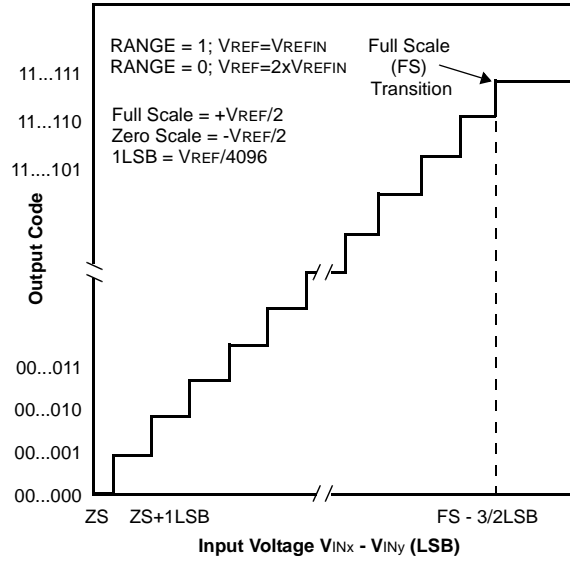


Figure 26. Two's Complement Transfer Function for SE/FDN = 1 and CODING = 0

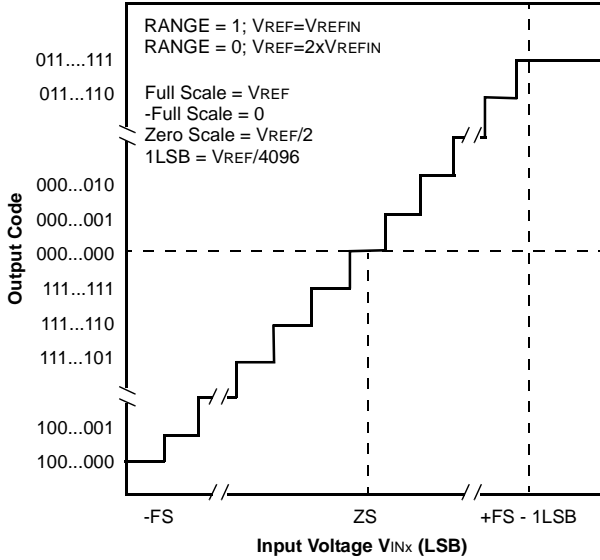
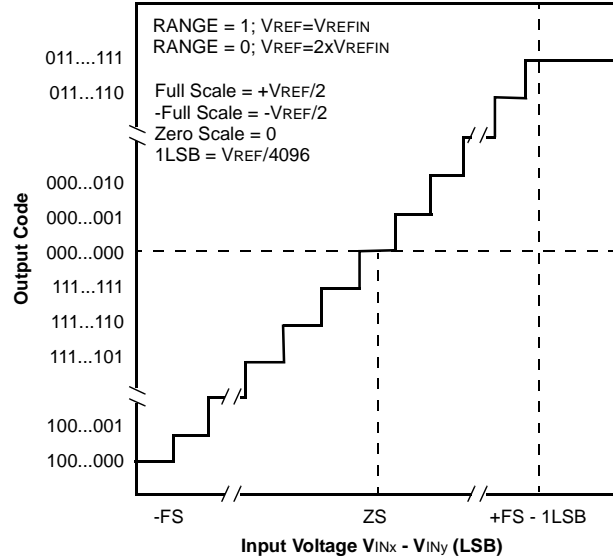


Figure 27. Two's Complement Transfer Function for SE/FDN = 0 and CODING = 0



## Power Mode Selection

Control register bits PM1 and PM0 are used to configure the AS1543/44 power mode.

Table 10. Power Mode Selection via Bits PM1 and PM0

PM1	PM0	Mode	Description
1	1	Normal Operation	In this mode, the AS1543/44 remains in full power mode regardless of the status of any of the logic inputs. This mode allows the fastest possible throughput rate.
0	X	Auto Shutdown	In this mode, the AS1543/44 automatically enters shutdown mode at the end of each conversion when the control register is updated. Wake-up time from shutdown is 1 $\mu$ s. <b>Note:</b> Ensure that 1 $\mu$ s has elapsed before attempting to perform a valid conversion in this mode.

## Sequencer Operation

The setting of control register bits SEQ and SHADOW sets the sequencer operation and also selects the shadow register for programming.

Table 11. Sequencer Configuration via Bits SEQ and SHADOW

SEQ	SHADOW	Description
0	0	These settings indicate that the sequencer is not used. The analog input channel selected for each individual conversion is determined by the contents of the channel address bits ADDR3:ADDR0 (page 13) in each prior write operation. This mode of operation reflects the normal operation of a multi-channel ADC (without the sequencer) where each write to the AS1543/44 specifies the next input channel for conversion (see Figure 28 on page 17).
0	1	These settings select the shadow register for programming. After a write to the control register, the following write operation will load the contents of the shadow register. This will program the sequence of channels to be repeatedly converted each successive valid CSN falling edge (see Table 12 on page 17 and Figure 29 on page 18). <b>Note:</b> The specified input channels need not be consecutive.
1	0	With these settings, the sequencer will not be interrupted upon completion of a write operation. This allows other bits of the control register (PM1, PM0, WEAK/TRIN, RANGE, CODING and SE/FDN) to be altered while in a sequence without terminating the cycle.
1	1	These settings are used in conjunction with the channel address bits ADDR3:ADDR0 to program continuous conversions on a consecutive sequence of channels (channel 0 ... channel $n$ ) as determined by the address bits ADDR3:ADDR0 (page 13) of the control register (see Figure 30 on page 19).



## Shadow Register

The shadow register is a 16-bit, write-only register. Data is loaded from pin DIN of the AS1543/44 on the falling edge of SCLK. The data is transferred on pin DIN at the same time as a conversion result is read from the device. This requires 16 serial falling edges for the data transfer.

The information is clocked into the shadow register (provided bits **SEQ** (page 13) and **SHADOW** (page 13) were set to 0, 1 respectively), in the previous write to the control register.

Each bit represents one of the input channels (VIN0 through VIN3/VIN7). Multiple channels can be selected for continuous cycling on each consecutive CSN falling edge after a write to the shadow register. To select a sequence of channels, the associated bit must be set for each analog input channel.

The AS1543/44 will continuously cycle through the selected channels in ascending order, beginning with the lowest channel, until a write operation occurs (i.e., bit **WRITE** (page 13) is set to 1) with bits **SEQ** and **SHADOW** configured in any way except 1, 0 (see Table 11 on page 16).

Table 12. 16-Bit Shadow Register Format, AS1543

15 (MSB)	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0 (LSB)
VIN0	VIN1	VIN2	VIN3	VIN4	VIN5	VIN6	VIN7	VIN0	VIN1	VIN2	VIN3	VIN4	VIN5	VIN6	VIN7

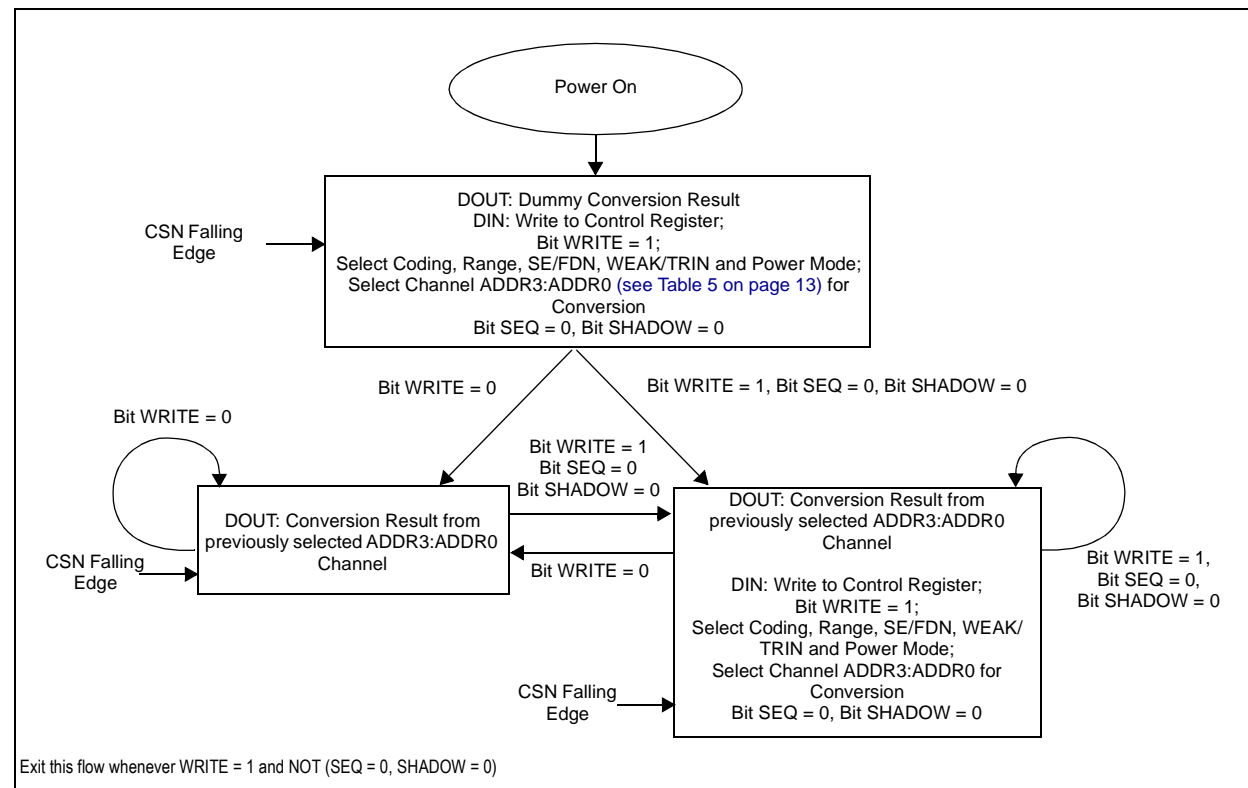
Table 13. 16-Bit Shadow Register Format, AS1544

15 (MSB)	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0 (LSB)
VIN0	VIN1	VIN2	VIN3	VIN0	VIN1	VIN2	VIN3	VIN0	VIN1	VIN2	VIN3	VIN0	VIN1	VIN2	VIN3

### Direct Conversion (SEQ = 0, SHADOW = 0)

Figure 28 shows the normal flow of an ADC with multiple input channels selected, where each serial transfer selects the next channel for conversion. In this mode of operation, the sequencer function is not used.

Figure 28. Bit SEQ = 0, Bit SHADOW = 0 Flowchart

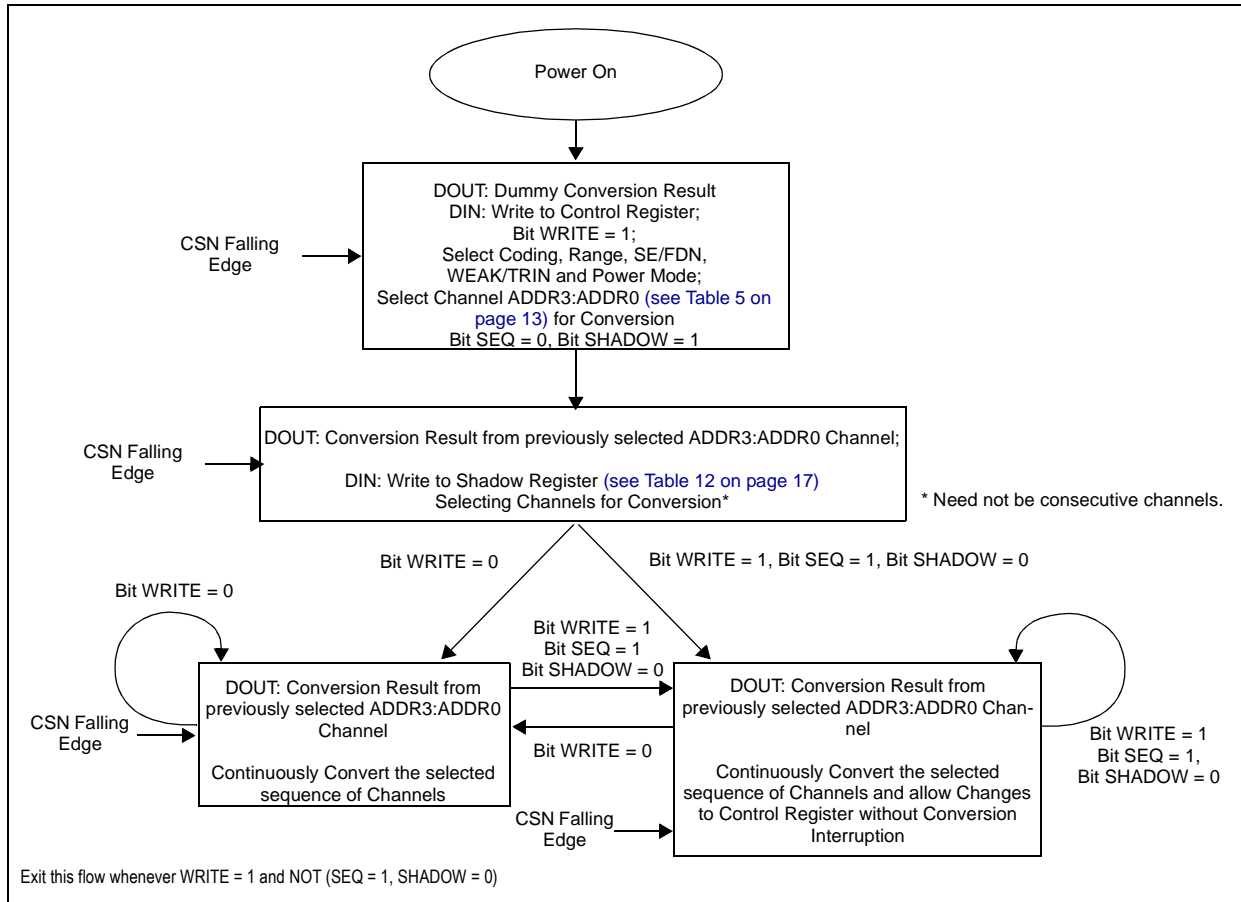


### Shadow Register Conversion (SEQ = 0, SHADOW = 1)

Figure 29 shows how to program the AS1543/44 to continuously convert from a particular sequence of channels. To exit this mode of operation and revert back to the normal mode of operation of a multi-channel ADC (as outlined in Figure 28), verify bit **WRITE** (page 13) = 1 and bits **SEQ** and **SHADOW** = 0 on the next serial transfer.

**Note:** If all 0s are written into the Shadow Register (see Table 12 on page 17) channel 3/7 will be chosen by default.

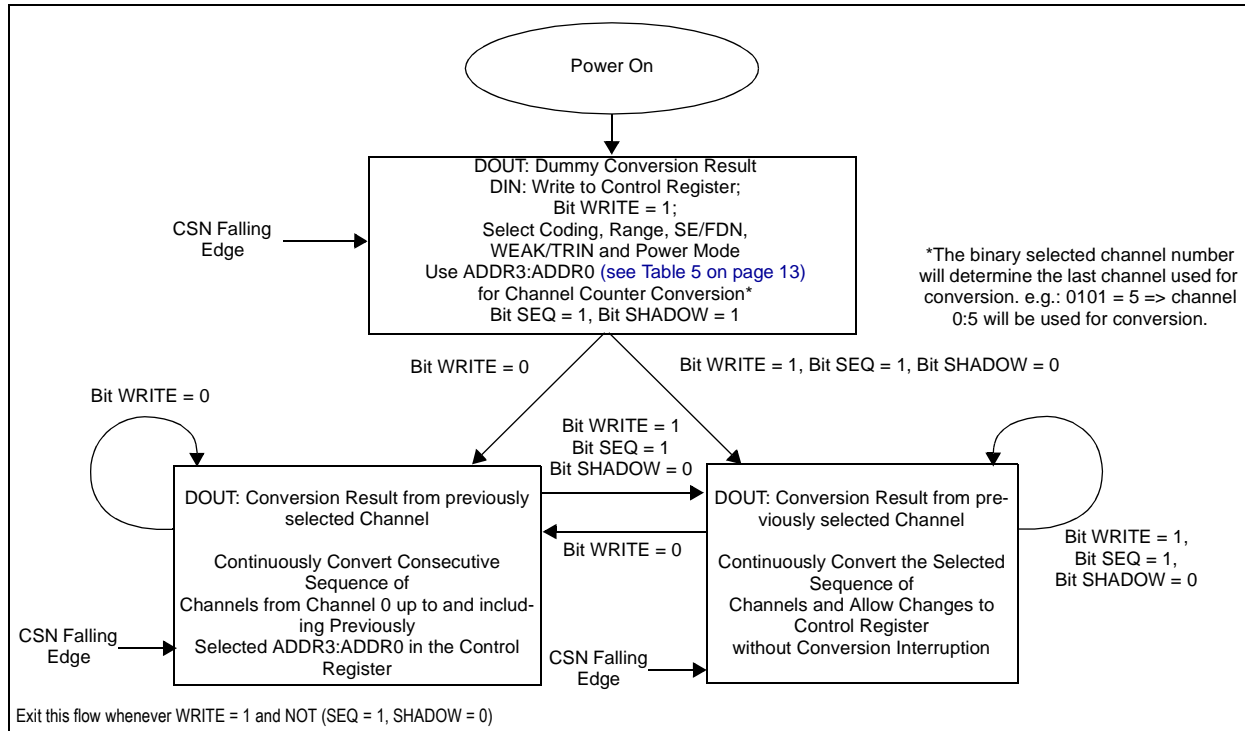
Figure 29. Bit SEQ = 0, Bit SHADOW = 1 Flowchart



### Channel Counter Conversion (SEQ = 1, SHADOW = 1)

Figure 30 shows how a sequence of consecutive channels can be converted from without having to program the shadow register or write to the part on each serial transfer. To exit this mode of operation and revert back to the normal mode of operation of a multi-channel ADC (as outlined in Figure 29), verify bit WRITE (page 13) = 1 and bits SEQ and SHADOW = 0 on the next serial transfer.

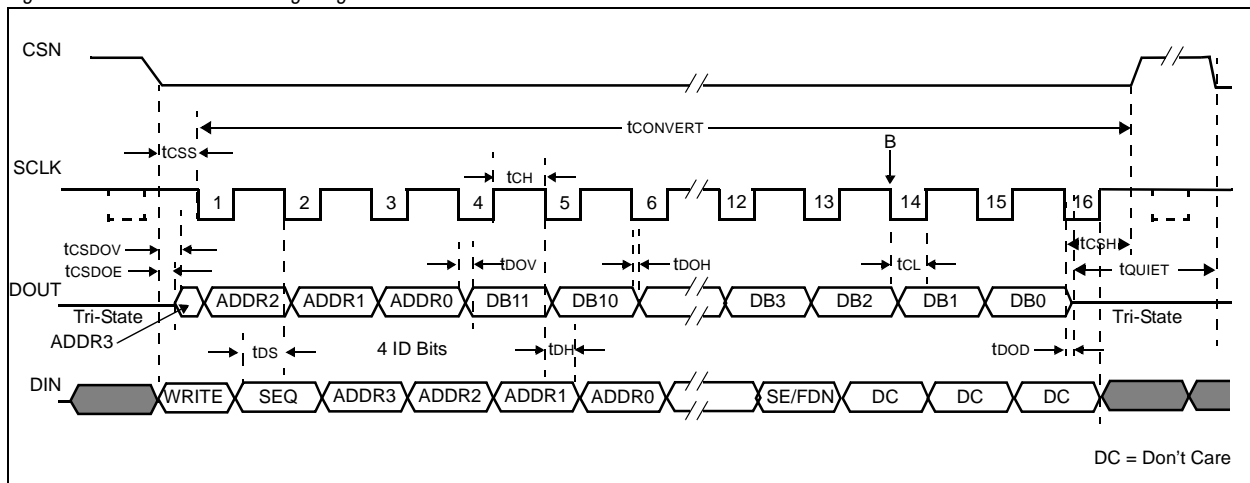
Figure 30. Bit SEQ = 1, Bit SHADOW = 1 Flowchart



### Serial Interface

Figure 31 shows the detailed timing diagram for serial interfacing to the AS1543/44. The serial clock provides the conversion clock and also controls the transfer of information to and from the AS1543/44 during each conversion.

Figure 31. Serial Interface Timing Diagram



The CSN signal initiates the data transfer and conversion process. The falling edge of CSN puts the track and hold into hold mode, takes the bus out of three-state, and the analog input is sampled at this point. The conversion is also initiated at this point and will require 16 SCLK cycles to complete.



These modes are designed to provide flexible power management options, and can be selected to optimize the power dissipation and throughput-rate ratio for differing application requirements. The mode of operation of the AS1543/44 is controlled by bits **PM1**, **PM0** (page 13) of the control register.

**Note:** When power supplies are first applied to the AS1543/44, internal power-on reset circuitry sets the device for Auto Shutdown (**PM1** = 0, **PM0** = x). The AS1543/44 remains in shutdown the first CSN falling edge is received.

### Normal Mode (**PM1** = 1, **PM0** = 1)

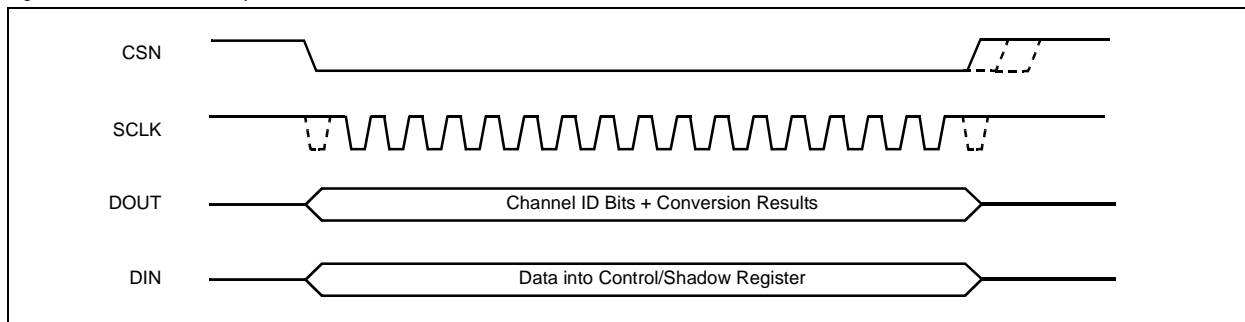
This mode is intended for the fastest throughput rate performance as the user does not have to worry about any power-up times with the AS1543/44 remaining fully powered at all times. Figure 33 shows the operation of the AS1543/44 in normal mode. Conversion is initiated on the falling edge of CSN and the track and hold will enter hold mode.

The data presented to pin DIN during the first 13 clock cycles of the data transfer is loaded to the control register (if bit **WRITE** (page 13) is set to 1). If bit **SEQ** (page 13) = 0, and bit **SHADOW** (page 13) = 1 on the previous write, data presented on pin DIN during the first 16 SCLK cycles is loaded into the shadow register. The device will remain fully powered up in normal mode at the end of the conversion as long as bits **PM1**, **PM0** (page 13) are set to 1 in the write transfer during that conversion.

To ensure continued operation in normal mode, bits **PM1** and **PM0** are loaded with 1 on every data transfer. Sixteen serial clock cycles are required to complete the conversion and access the conversion result. The track and hold will go back into track on the 14th SCLK falling edge.

Once a data transfer is complete (**DOUT** has returned to tri-state, bit **WEAK/TRIN** (page 13) = 0), another conversion can be initiated after the quiet time (**tQUIET**) has elapsed by bringing CSN low again.

Figure 33. Normal Mode Operation



#### Notes:

1. Control register data is loaded on the 1st 13 SCLK cycles.
2. Shadow register data is loaded on the 1st 16 SCLK cycles.

### Auto Shutdown (**PM1** = 0, **PM0** = X)

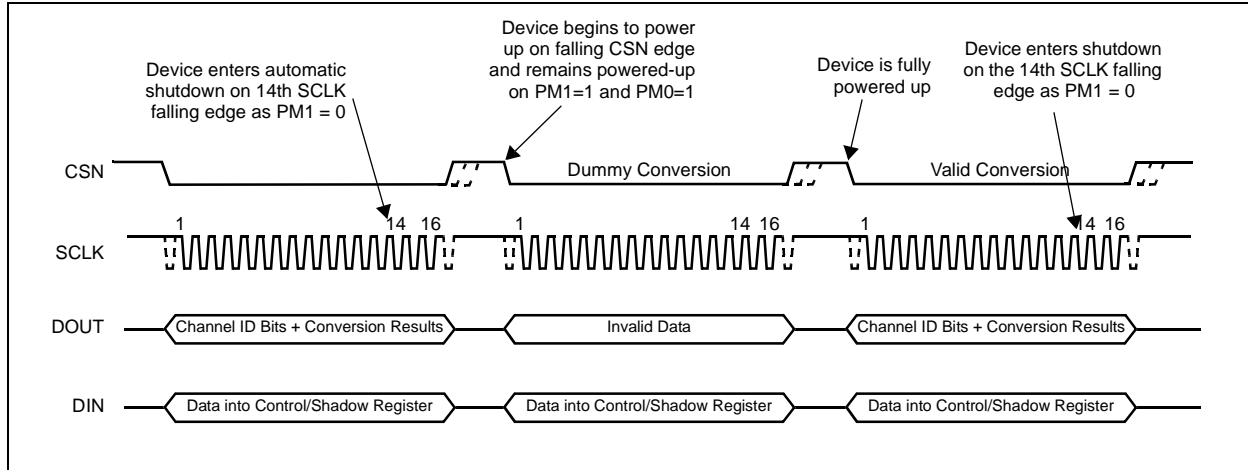
In this mode, the AS1543/44 automatically enters shutdown after the 14th SLK falling edge of each conversion is updated. When the device is in shutdown mode, the track/hold circuitry is in hold mode.

**Note:** The control register maintains its data while in shutdown mode.

Figure 34 shows the operation of the AS1543/44 when it is in automatic shutdown mode. The AS1543/44 remains in shutdown until the next CSN falling edge it receives. On this CSN falling edge, the track and hold that was in hold while the device was in shutdown will return to track.

**Note:** Wake-up time from auto shutdown is 1  $\mu$ s.

Figure 34. Auto Shutdown Mode Operation



**Notes:**

1. Control register data is loaded on the 1st 13 SCLK cycles.
2. Set control register bits PM1 = 1 and PM0 = 1 to keep the device in normal mode.

When running the AS1543/44 with a 20MHz clock, one dummy cycle of 1µs (see Figure 34) (16 SCLKs plus Track&Hold aquisition time) should be sufficient to ensure the part is fully powered up.

This dummy cycle effectively halves the throughput rate, with every other conversion result being valid. In this mode, the power consumption of the part is greatly reduced with the part entering shutdown at the end of each conversion.

**Note:** The end of shutdown can be controlled by the CSN signal.

**Power vs. Throughput Rate**

By operating the AS1543/44 in auto shutdown (see page 21) the average power consumption of the ADC decreases at lower throughput rates. The Power vs. Throughput Rate graph in the Typical Operating Characteristics section shows how as the throughput rate is reduced, the part remains in its shutdown state longer and the average power consumption over time drops accordingly.

If the AS1543/44 is operated in a continuous sampling mode with a throughput rate of 100ksps and a SCLK of 20 MHz (V<sub>DD</sub> = 5V), with bit PM1 (page 13) = 0, i.e., the device is in auto shutdown mode (see page 21), then the power consumption is calculated as follows:

The maximum power dissipation during normal operation is 18.4mW (V<sub>DD</sub> = 5.25V). If the power-up time from auto shutdown is one dummy cycle (i.e., 1µs) and the remaining conversion time is another cycle (i.e., 1µs) then the AS1543/44 will dissipate approximately 18.4mW for 2µs during each conversion cycle. For the remainder of the conversion cycle (8µs), the device remains in shutdown mode. The AS1543/44 will dissipate approximately 2.5µW for the remaining 8µs of the conversion cycle. If the throughput rate is 100ksps, the cycle time is 10µs and the average power dissipated during each cycle is:

$$((2/10) \times 18.4mW) + ((8/10) \times 2.5\mu W) = 3.682mW \quad (EQ 1)$$

The Power vs. Throughput Rate graph in the Typical Operating Characteristics section shows the power vs. throughput rate when using the auto shutdown mode and auto standby mode with 5V supplies (similar power calculations can be done at 3V, although the power is decreased even more when using 3V supplies).

**VDRIVE**

VDRIVE controls the serial interface voltage. VDRIVE allows easy interface to 3V and 5V processors. For example, if the AS1543/44 were operated with a V<sub>DD</sub> of 5V, pin VDRIVE could be powered from a 3V supply. The AS1543/44 has better dynamic performance with a V<sub>DD</sub> of 5V while still being able to interface to 3V processors.

**Note:** VDRIVE must not exceed V<sub>DD</sub> by more than 0.3V (see Absolute Maximum Ratings on page 3)

## External Reference

An external reference source should be connected directly to the pin  $V_{REFIN}$  of the AS1543/44. The external reference voltage can reach from 1V to  $V_{DD}$ . The correlation between performance of the AS1543/44 and the reference voltage is shown in [Figure 9 on page 8](#). However for specified performance the reference voltage has to stay at  $2.5V \pm 1\%$ . The analog input range depends on  $V_{REFIN}$  and the setting of bit RANGE and bit SE/FDN of the control register (see [Analog Input Configuration on page 14](#)). Errors in the reference source will result in gain errors in the AS1543/44 transfer function and will add to the specified full scale errors of the device.

**Note:** A capacitor of at least  $0.1\mu F$  should be placed on pin REFIN.

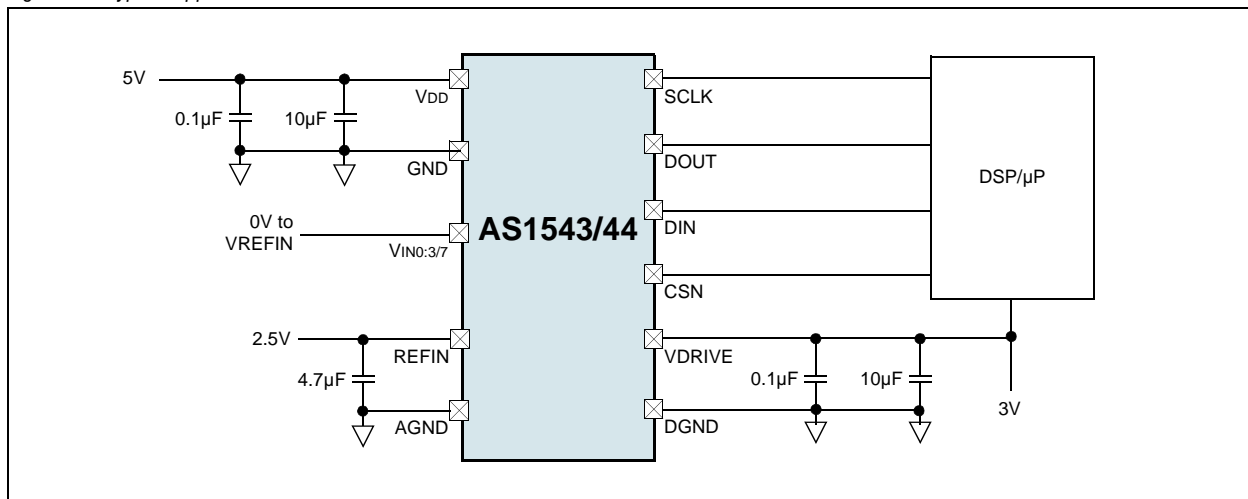
## 9 Application Information

Figure 35 shows a typical connection diagram for the AS1543/44. In this configuration, pin AGND, GND and DGND connected to the analog ground plane of the system. In Figure 35, REFIN is connected to a decoupled 2.5V reference source, to provide an analog input range of 0 to 2.5V (if RANGE (page 13) is 1 and bit SE/FDN (page 13) = 1) or 0 to 5V (if bit RANGE is 0 and bit SE/FDN = 1). In Figure 35 the AS1543/44 is connected to a VDD of 5V, however the serial interface is connected to a 3V microprocessor.

Pin VDRIVE is connected to the same 3V supply of the microprocessor to allow a 3V logic interface. The conversion result is output in a 16-bit word. This 16-bit data stream consists of four address bits indicating which channel the conversion result corresponds to, followed by the 12 bits of conversion data.

**Note:** For applications where power consumption is of concern, the power-down modes should be used between conversions or bursts of several conversions to improve power performance (see Power Modes on page 20).

Figure 35. Typical Application



**Note:** For the circuit shown in Figure 35, unused input channels should be connected to ground. For optimum performance decouple all analog input channels and the reference input voltage to the ground of AGND.

### Initialization

When power is first applied to the AS1543/44 internal power-on reset circuitry sets the device for Auto Shutdown (PM1 = 0, PM0 = X) on page 21.

**Note:** The device requires 10µs after the power supplies stabilize; no conversions should be initiated during this time.

The digital output at pin DOUT will be set to tri-state after internal power-on reset.



## Grounding and Layout Considerations

The AS1543/44 has excellent immunity to noise on the power supplies as can be seen by the [PSRR vs. Supply Signal Frequency graph on page 10](#), however, the following should be considered regarding grounding and PCB layout:

- The PCB should be designed such that the analog and digital sections are confined to separate areas of the board. This facilitates the use of ground planes that can be separated easily. A minimum etch technique is generally best for ground planes as it gives the best shielding.
- Pins AGND and GND should be tied to the analog ground plane. Pin DGND should be tied to the digital ground plane.
- Digital and analog ground planes should be joined at only one place. If the AS1543/44 is in a system where multiple devices require an AGND-to-DGND connection, the connection should be made at one point – a star ground point which should be established as close as possible to the AS1543/44.
- Avoid running digital lines under the device as these will couple noise onto the die.
- The analog ground plane should be allowed to run under the AS1543/44 to avoid noise coupling.
- The power supply lines to the AS1543/44 should use as large a trace as possible to provide low-impedance paths and reduce the effects of glitches on the power supply line.
- Fast-switching signals (e.g., clocks) should be shielded with digital ground to avoid radiating noise to other sections of the PCB.
- Clock signals should not be run near the analog inputs.
- Avoid crossover of digital and analog signals.
- Traces on opposite sides of the board should run at right angles to each other. This will reduce the effects of feedthrough through the board. A microstrip technique is the best but is not always possible with a double-sided board. In this technique, the component side of the board is dedicated to ground planes while signals are placed on the solder side.
- All analog input channels and the reference input voltage should be decoupled to the ground pin of AGND.
- All analog supplies should be decoupled with 10 $\mu$ F tantalum in parallel with 0.1 $\mu$ F capacitors to GND. To achieve the best from these decoupling components, they must be placed as close as possible to the device, ideally right up against the device. The 0.1 $\mu$ F capacitors should be low ESR and ESI (e.g., common ceramic or surface mount types) which provide a low impedance path to ground at high frequencies to handle transient currents due to internal logic switching.

## 10 Package Drawings and Markings

Figure 36. QFN(4x4)-20 Marking



Table 14. Packaging Code YYWWQZZ

YY	WW	Q	ZZ
last two digits of the current year	manufacturing week	plant identifier	free choice / traceability code



## 11 Ordering Information

The device is available as the standard products listed below.

Table 15. Ordering Information

Ordering Code	Marking	Description	Delivery Form	Package
AS1543-BQFT	AS1543	8/4-Channel, 1 Msps, 12-Bit ADC with Sequencer	Tape and Reel	QFN(4x4)-20
AS1544-BQFT	AS1544	8/4-Channel, 1 Msps, 12-Bit ADC with Sequencer	Tape and Reel	QFN(4x4)-20

**Note:** All products are RoHS compliant.

Buy our products or get free samples online at ICdirect: <http://www.austriamicrosystems.com/ICdirect>

Technical Support is found at <http://www.austriamicrosystems.com/Technical-Support>

For further information and requests, please contact us <mailto:sales@austriamicrosystems.com>  
or find your local distributor at <http://www.austriamicrosystems.com/distributor>

## Copyrights

Copyright © 1997-2011, austriamicrosystems AG, Tobelbaderstrasse 30, 8141 Unterpremstaetten, Austria-Europe. Trademarks Registered ®. All rights reserved. The material herein may not be reproduced, adapted, merged, translated, stored, or used without the prior written consent of the copyright owner.

All products and companies mentioned are trademarks or registered trademarks of their respective companies.

## Disclaimer

Devices sold by austriamicrosystems AG are covered by the warranty and patent indemnification provisions appearing in its Term of Sale. austriamicrosystems AG makes no warranty, express, statutory, implied, or by description regarding the information set forth herein or regarding the freedom of the described devices from patent infringement. austriamicrosystems AG reserves the right to change specifications and prices at any time and without notice. Therefore, prior to designing this product into a system, it is necessary to check with austriamicrosystems AG for current information. This product is intended for use in normal commercial applications. Applications requiring extended temperature range, unusual environmental requirements, or high reliability applications, such as military, medical life-support or life-sustaining equipment are specifically not recommended without additional processing by austriamicrosystems AG for each application. For shipments of less than 100 parts the manufacturing flow might show deviations from the standard production flow, such as test flow or test location.

The information furnished here by austriamicrosystems AG is believed to be correct and accurate. However, austriamicrosystems AG shall not be liable to recipient or any third party for any damages, including but not limited to personal injury, property damage, loss of profits, loss of use, interruption of business or indirect, special, incidental or consequential damages, of any kind, in connection with or arising out of the furnishing, performance or use of the technical data herein. No obligation or liability to recipient or any third party shall arise or flow out of austriamicrosystems AG rendering of technical or other services.



## Contact Information

### Headquarters

austriamicrosystems AG  
Tobelbaderstrasse 30  
A-8141 Unterpremstaetten, Austria

Tel: +43 (0) 3136 500 0  
Fax: +43 (0) 3136 525 01

For Sales Offices, Distributors and Representatives, please visit:

<http://www.austriamicrosystems.com/contact>