

AUTOMOTIVE CURRENT TRANSDUCER HAH1DR 300-S/SP1





Introduction

The HAH1DR family is for the electronic measurement of DC, AC or pulsed currents in high power automotive applications with galvanic isolation between the primary circuit (high power) and the secondary circuit (electronic circuit).

The HAH1DR family gives you the choice of having different current measuring ranges in the same housing (from \pm 200 A up to \pm 900 A).

Features

- Open Loop transducer using the Hall effect
- Unipolar + 5 V DC power supply
- Primary current measuring range up to ± 300 A
- Maximum RMS primary current limited by the busbar, the magnetic core or the ASIC temperature T° < + 150°C
- Operating temperature range: 40°C < T° < + 125°C
- Output voltage: full ratiometric (in sensitivity and offset)
- · Compact design.

Advantages

- Excellent accuracy
- Very good linearity
- Very low thermal offset drift
- Very low thermal sensitivity drift
- Wide frequency bandwidth
- No insertion losses.

Automotive applications

- Battery monitoring
- Starter Generators
- Inverters
- HEV application
- EV application.



The open loop transducers uses a Hall effect integrated circuit. The magnetic flux density B, contributing to the rise of the Hall voltage, is generated by the primary current ${\bf I}_{\rm p}$ to be measured.

The current to be measured $I_{\rm p}$ is supplied by a current source i.e. battery or generator (Fig. 1).

Within the linear region of the hysteresis cycle, B is proportional to:

B
$$(\mathbf{I}_{p})$$
 = constant (a) x \mathbf{I}_{p}

The Hall voltage is thus expressed by:

$$\mathbf{V}_{H} = (\mathbf{R}_{H}/\mathbf{d}) \times \mathbf{I} \times \text{constant}$$
 (a) $\times \mathbf{I}_{P}$

Except for $\mathbf{I}_{\mathrm{p}}\text{,}$ all terms of this equation are constant. Therefore:

$$\mathbf{V}_{H}$$
 = constant (b) x \mathbf{I}_{P}

The measurement signal $\mathbf{V}_{\rm H}$ amplified to supply the user output voltage or current.

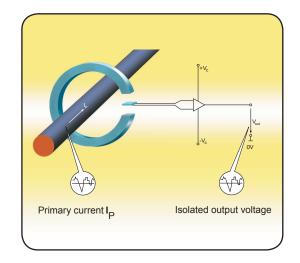
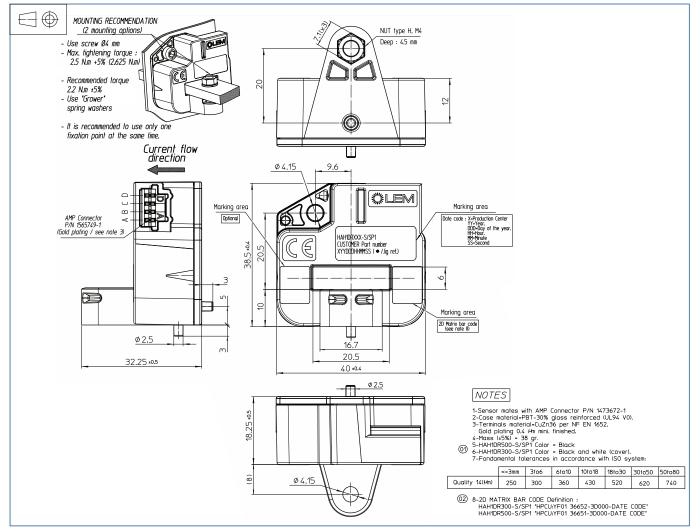


Fig. 1: Principle of the open loop transducer



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Dimensions HAH1DR family (in mm.)



Bill of materials

- Plastic case
- PBT GF 30 Iron silicon alloy
- Magnetic corePins

Brass gold plated 38 g

- System architecture (example)
- \mathbf{R}_{l} > 10 k Ω optional resistor for signal line diagnostic

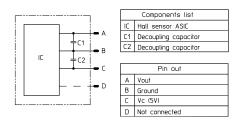
V _{OUT}	Diagnosis
Open circuit	$\mathbf{V}_{\text{IN}} = \mathbf{V}_{\text{C}}$
Short GND	V _{IN} = OV

Remarks

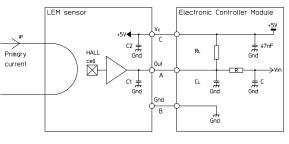
Mass

• $V_{OUT} > \frac{V_c}{2}$ when I_p flows in the direction of the arrow.

System architecture



C_L < 100 nF EMC protection
RC Low pass filter EMC protection (optional)



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Absolute maximum ratings

	Symbol	Unit	Specification			Conditions
	Symbol	Unit	Min	Тур	Max	Conditions
Electrical Data						
Max primary current peak	I _{Pmax}				1)	
Supply continuous over voltage	v	V			7	No operating
Reverse voltage 2)	v _c	v	-0.5			1 min @ T _A = 25°C
Output over voltage (continuous)	V _{out}	V	-0.5		V _c + 0.5	
Continuous output current	I _{OUT}	mA	-10		10	
Output short-circuit duration	t	min			2	
Rms voltage for AC isolation test	V _d	kV			2	50 Hz, 1 min
Isolation resistance	R _{IS}	MΩ	500			500 V - ISO 16750-2
Electrostatic discharge voltage	V _{ESD}	kV			2	JESD22-A114-B
Ambient storage temperature	T _s	°C	-55		125	

Operating characteristics

	Ormatical Limit		Specification			Quanditi una
	Symbol Unit	Min	Тур	Max	Conditions	
			Electrica	Data		
Primary current	l _p	А	-300		300	
Calibration current	I _{CAL}	А	-300		300	@ T _A = 25°C
Supply voltage	V _c	V	4.75	5.00	5.25	
Output voltage (Analog) 3)	V _{OUT}	V	V _{OUT} = (V _c /5) × (2.5 +	+ G × I _P)	@ V _c
Sensitivity 3)	G	mV/A		6.67		@ $V_c = 5 V$
Current consumption	I _c	mA		15	20	@ $V_c = 5 V$, @ - 40°C < T° < 125°C
Load resistance	RL	kΩ	10			
Output internal resistance	R _{OUT}	Ω			10	DC to 1 kHz
Capacitive loading	C	nF	1		100	
Ambient operating temperature	T _A	°C	-40		125	Connector limited 105°C
Output drift versus power supply	V _{OUT PS}	%		0.5		
			Performan	ce Data		
Sensitivity error	ε _g	%	-1.0	± 0.5	1.0	$(\mathbf{M} \mathbf{T}_{A} = 25^{\circ} \mathbf{C} (\mathbf{M} \mathbf{I} = \mathbf{I}_{P})$
Electrical offset current	I _{OE}			± 0.8		$@ T_A = 25^{\circ}C, @ VC = 5 V$
Magnetic offset current	I _{om}	А		± 1		@ $T_{A} = 25^{\circ}C$, @ VC = 5 V, after ± I_{P}
Global offset current	I _o		-2.1		2.1	$@ T_{A} = 25^{\circ}C$
Average temperature coefficient of $V_{\text{\tiny OE}}$		mV/°C	-0.08	± 0.03	0.08	@ - 40°C < T° < 125°C
Average temperature coefficient of G	TCG _{AV}	%/°C	-0.035	± 0.02	0.035	@ - 40°C < T° < 125°C
Linearity error	٤ ₁	%	-1		1	$(0, V_{c} = 5 \lor (0, T_{A} = 25^{\circ}C, (0, I = I_{P}))$
Response time to 90 % of I _{PN} step	t,	μs		6	10	@ di/dt = 100 A/µs
Frequency bandwidth 4)	BW	kHz		30		@ -3 dB
Output clamping voltage min	V _{sz}	V			0.1	@ $V_{c} = 5 V, T_{A} = 25^{\circ}C$
Output clamping voltage max			4.9			$(\mathbf{W}_{C} = 5 \text{ V}, \mathbf{T}_{A} = 25^{\circ}\text{C}$
Output voltage noise peak-peak	V _{no pp}	mV			20	DC to 1MHz

¹⁾ Busbar temperature must be below 150°C Notes:

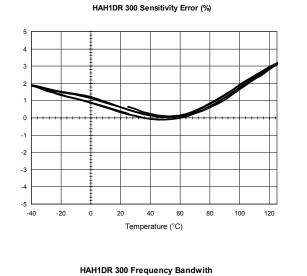
- ²⁾ Transducer not protected against reverse polarity. ³⁾ The output voltage V_{out} is fully ratiometric. The offset and sensitivity are dependent on the supply voltage V_c relative to the following formula:

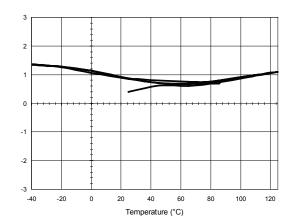
$$I_{\text{P}} = \left(V_{\text{out}} - \frac{V_{\text{c}}}{2}\right) \times \frac{1}{G} \times \frac{5}{V_{\text{c}}} \qquad \text{with } G \text{ in } (V \,/\, A)$$

⁴⁾ Tested with small signals only to avoid excessive heating of the magnetic core.

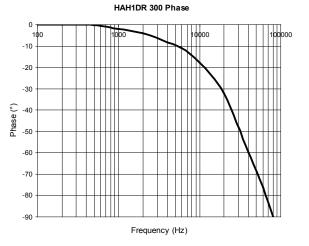


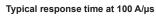
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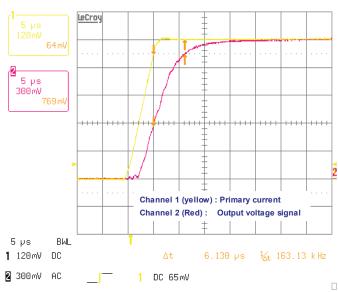




HAH1DR 300 Electrical offset Error (A)







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HAH1DR 300-S/SP1 PERFORMANCES PARAMETERS DEFINITIONS

Output noise voltage:

The output voltage noise is the result of the noise floor of the Hall elements and the linear I_{c} amplifier gain.

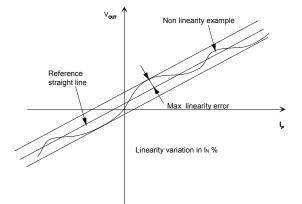
Magnetic offset:

The magnetic offset is the consequence of an over-current on the primary side. It's defined after an excursion of $I_{P_{max}}$.

Linearity:

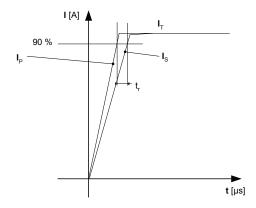
The maximum positive or negative discrepancy with a reference straight line $V_{OUT} = f(I_P)$.

Unit: linearity (%) expressed with full scale of $I_{P max}$ Linearity is measured on cycle + I_{p} , O, - I_{p} , O, + I_{p} without magnetic offset (average values used)



Response time (delay time) t.:

The time between the primary current signal and the output signal reach at 90 % of its final value



Typical:

Theorical value or usual accuracy recorded during the production.

Laser Marking:

Readability with advocated LASER reader Brand SYMBOL Model DPM DS 3408 or 3407.

Sensitivity:

The Transducer's sensitivity G is the slope of the straight line $\mathbf{V}_{out} = f(\mathbf{I}_{P})$, it must establish the relation: $V_{out}(I_{P}) = V_{C}/5 (G \times I_{P} + 2.5) (*)$

(*) For all symetrics transducers.

Offset with temperature:

The error of the offset in the operating temperature is the variation of the offset in the temperature considered with the initial offset at 25°C.

The offset variation \mathbf{I}_{oT} is a maximum variation the offset in the temperature range:

 $\mathbf{I}_{OT} = \mathbf{I}_{OE} \max - \mathbf{I}_{OE} \min$

The Offset drift $\textbf{TCI}_{\text{\tiny OEAV}}$ is the $\textbf{I}_{\text{\tiny OT}}$ value divided by the temperature range.

Sensitivity with temperature:

The error of the sensitivity in the operating temperature is the relative variation of sensitivity with the temperature considered with the initial offset at 25°C.

The sensitivity variation \mathbf{G}_{τ} is the maximum variation (in ppm or %) of the sensitivity in the temperature range:

 \mathbf{G}_{T} = (Sensitivity max - Sensitivity min) / Sensitivity at 25°C.

The sensitivity drift TCG_{AV} is the G_{T} value divided by the temperature range.

Offset voltage @ $I_{p} = 0$ A:

Is the output voltage when the primary current is null. The ideal value of $V_{\rm o}$ is $V_{\rm c}/2$ at $V_{\rm c}$ = 5 V. So, the difference of $V_{\rm o}$ - $V_{\rm c}/2$ is called the total offset voltage error. This offset error can be attributed to the electrical offset (due to the resolution of the ASIC quiescent voltage trimming), the magnetic offset, the thermal drift and the thermal hysteresis.

Environmental test specifications

Name	Standard	Conditions			
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Damp heat, steady state	JESD22-A101	85°C - 85°C / 1000h			
Isolation resistance	ISO 16750-2 § 4.10	500 V/1min			
Temperature humidity cycle test	ISO 16750-4	-10 + 85°C 10 days			
Isolation test	IEC 60664-1	2 kV/50 Hz/1min			
Mechanical tests					
Vibration test (random)	IEC 60068-2-64 ISO 16750-3 & 4.1.2.5 (2007)	20 2000 Hz Random rms (11g rms) 8h/axis			
Terminal strength test	According to LEM				
Thermal shocks	IEC 60068-214 Na	-40 + 125°C 300 cycles			
Free fall	ISO 16750-3 § 4.3	1m concrete ground			
EMC Test					
Radiated electronagnetic immunity	Directive 2004/104/CE ISO 11452-2	30 V/m 20-2000 MHz			
Bulk current injection immunity	Directive 2004/104/CE ISO 11452-4	1-400 MHz-60mA			
Radiated radio frequency electromagnetic field immunity	IEC 61000-4-3	80 MHz to 1,000 MHz-10V/m			
Electrostatic discharge immunity test	IEC 61000-4-2	Air discharge=2 kV			