May 2006

SEMICONDUCTOR

FAN5078 DDR/ACPI Regulator Combo

Features

- PWM regulator for VDDQ (2.5V or 1.8)
- Linear LDO regulator generates VTT = VDDQ/2, 1.5A Peak sink/source capability
- AMT / M-state support
- Control to generate 5V USB
- ACPI drive and control for 5V DUAL generation
- 3.3V internal LDO for 3V-ALW generation
- 300 kHz fixed frequency switching
- \blacksquare R_{DS(ON)} current sensing or optional current sense resistor for precision over-current detect
- Internal synchronous boot diode
- Common Power Good signal for all voltages
- Input under-voltage lockout (UVLO)
- Thermal shutdown
- Latched multi-fault protection
- Precision reference output for ULDO controllers
- 24-pin 5 x 5 MLP package

Applications

- **DDR VDDQ and VTT vullage generation with ACPI** support
- Desktop PC's
- Server

Description

The FAN5078 DDR memory require to combines a highefficiency Pulse-Width Modulated (PM) controller to generate the memory sup, voltage, VDDQ, and a linear regulator to generate tentionation voltage (VTT).

Synchronous rectification provides high efficiency over a range of load currents. Efficiency is further entity is using the low-side \overline{OSFST} 's \overline{PS} is \overline{OS} frement.

The VD^r Ω P_W \rightarrow 1 regulator is a sampled current mode control with $ex \rightarrow be$ ensation to achieve fast load-transient response in provide system design optimization.

The VTT regulator derives its reference and takes its power in the VDDQ PWM regulator, or tput. The VTT termination gu tor is capable of sourcing or sinking 1.5A peak currents.

In S5 M1 mode, the VDDC switcher, VTT regulator, and the 3.3V regulators and only one of the S3 mode keeps these regulators on, but also turns on an external P-Channel to provide 5V USB.

A s_{ingle} soft-s_{tart} capacitor enables controlled slew rates for **buth PDQ and 3.3V-ALW outputs.**

BOC becomes true in S0 only after all regulators have ieved stable outputs.

In S5 (EN = 0), the 3.3V internal LDO stays on while the other regulators are powered down.

Ord ring Information

© 2006 Fairchild Semiconductor Corporation www.fairchildsemi.com FAN5078 Rev. 1.0.0 • 05/09/06

Table 1. BOM for Figure 1

Contact a Fairchild representative for complete reference design and / or evaluation board.

Bypass Capacitor Notes:

- 1. Input capacitor C_{IN} is typically chosen based on the ripple current requirements. C_{OUT} is typically selected based on both current ripple rating and ESR requirement. See AN-6006 for these calculations.
- 2. C7, C12, and C15 selection is largely determined by ESR and load transient response requirements. In each case, the number of capacitors required depends on the capacitor technology chosen. Oscons can meet the requirements with less space, but higher cost, than using low-ESR electrolytics.

FAN5078 Rev. 1.0.0 • 05/11/06

FAN5078 DDR/ACPI Regulator Combo **FAN5078 DDR/ACPI Regulator Combo**

Pin Configuration SBUSB# $S4$ S $T#$ \sim SBSW 5V MAIN | ≏ VTT SNS|ഗ VTT OUT|∞ **P1 = GND** \rightarrow $\overline{\epsilon}$ 7 8 9 10 11 12 긃 EN <u>귀</u> S3#I _{ಹೆ}| S3#O <u>ਜ਼ੇ</u> 3.3 ALW $\frac{1}{4}$ VCC 13 PGOOD 24 23 22 21 20 19 VDDQ_{IN} BOOT HDRV $\overline{\mathsf{s}}$ ISNS $\overline{\mathsf{B}}$ REF IN \mathbf{f} COMP SS $\underline{\mathbb{N}}$ GND

Pin Definitions

Pin Definitions (Continued)

Absolute Maximum Ratings

The Absolute Maximum Ratings are those values beyond which the safety of the device cannot be guaranteed. The device should not be operated at these limits. The parametric values defined in the Electrical Characteristics tables are not guaranteed at the absolute maximum ratings. The Recommended Operating Conditions table defines the conditions for actual device operation.

Recommended Operating Conditions

Electrical Specifications

Recommended operating conditions; component values per Figure 1, unless otherwise noted.

Electrical Specifications (Continued)

Notes:

1. Guaranteed by design and characterization, not tested in production.

Circuit Description

Overview

The FAN5078 provides five functions:

- 1. A general purpose PWM regulator, typically used to generate VDDQ for DDR Memory.
- 2. A low-dropout linear VTT regulator capable of sinking and sourcing 1.5A peak.
- 3. Control to generate 5V DUAL using an external Nchannel to supply power from 5V MAIN in S0 and an external P-Channel to provide power from 5V Standby (5VSB) in S3.
- 4. Drive to generate 5V USB. This signal drives a P-Channel MOSFET to connect 5V USB to +5VSB in S3.
- 5. An internal LDO that regulates 3.3V-ALW in S3 mode from VCC (5VSB). In S3 or S5, this regulator is capable of 1.25A peak currents with average currents limited by the thermal design of the PCB.

At initial power-up, or when transitioning from S5, the PWM regulator is disabled until 5V MAIN is above its UVLO threshold.

Table 2. ACPI states

Regulator Sequencing

The VCC pin provides power to all logic and analog control functions of the regulator, including:

- 1. Power for the 3.3V regulator
- 2. LDRV gate driver current
- 3. HDRV boot diode charging current
- 4. The regulator analog control and logic.

This pin must be decoupled with a X5R ceramic capacitor $(1\mu$ F or larger recommended) as close as possible to the VCC pin. After VCC is above UVLO, the start-up sequence begins (see Figure 8).

UVLO on VCC discharges SS and resets the IC.

T0 to T3: After initial power-up, the IC ignores logic inputs for a period (T3-T0) of approximately:

$$
T3 - T0 \approx 1.7 \bullet C_{SS}
$$
 (1)

where T3-T0 is in mS if C_{SS} is in nF. At T2 (about 2/3 of the way from T1 to T3), the 3.3V-ALW LDO is in regulation. The 3.3V LDO's slew rate is limited by the discharge slope of CSS. If 3.3V MAIN has come up prior to this time, the 3.3V-ALW node is already pre-charged through the body diode of Q5 (see Figure 1).

T3 to T4: The IC starts VDDQ only if 5V MAIN is above its UVLO threshold (5V MAIN OK). Provided 5V MAIN is up before T3, the IC waits about 100μS before initiating soft-start on VDDQ to allow CSS time to fully discharge. The IC is in

"SLEEP" or S5 state when EN is low. In S5, only the 3.3V LDO is on. If the IC is in S5 at T4, CSS is held to 0V.

T4 to T5: After VDDQ is stabilized (when C_{SS} is at about ~1.3V), an internal VDDQ OK is generated that allows the VTT LDO to start. To ensure that the VDDQ output is not subjected to large transient currents, the VTT slew rate is limited by the slew rate of the SS cap. In addition, the VTT regulator is current limited. VTT is in regulation once Css reaches about 3.8V.

S0 to S3 or S5 M1: The system signals this transition by dropping the S3#I signal. When this occurs, S3#O goes low, and the 3.3V LDO turns on. SBSW pulls low to turn on the P-Channel 5V DUAL switch. SBUSB# pulls low to turn on Q6 when S4ST# is high.

S3 or S5 M1 to S0: The system signals this transition by raising the S3#I signal. S0 mode is not entered until 5V MAIN OK, then the following occurs:

- S3#O releases
- SBSW and SBUSB# both pull high to turn off their P-Channel switches
- The 3.3V LDO turns off.

In most systems, the ATX power supply is enabled when S3#I goes from high. At that time, 5V and 3.3V MAIN starts to rise. When the FAN5078's 5V MAIN pin is above its UVLO threshold, Q3 and Q5 turn on. This can cause about a 10% "dip" in both 5V DUAL and 3.3V ALW when Q3 and Q5 turn on, since at that point, 5V MAIN and 3.3V MAIN are at 90% of their regulation value.

Figure 4. S3 to S0 Transition: 5V DUAL

This dip can also occur in 5V USB and 3.3V-ALW if 5V and 3.3V are not fully charged before the 5V MAIN pin exceeds its threshold. To eliminate the dip, add delay to the 5V MAIN pin, as shown below. The 5V MAIN pin on the FAN5078 does not supply power to the IC; it is only used to monitor the voltage level of the 5V MAIN supply. The pin does have a pull-down resistor impedance of about 62K and therefore requires a low value RDLY resistor (see Figure 5 below).

Figure 5. Adding Delay to 5V MAIN

Another method to eliminate the potential for this dip is to instead connect the ATX power supply's PWR_OK signal to the 5V MAIN pin. Some systems cannot tolerate the long delay for PWR_OK (>100mS) to assert, hence the solution in Figure 5 may be preferable.

If the PWR OK signal is used, the voltage at the 5V MAIN pin must reach the 5V MAIN threshold. Since the internal pulldown resistance of the 5V MAIN pin is 62K, a low value pullup should be used. A lower current solution can also be used by employing the 12V supply to provide adequate pull-up capability. The circuit in Figure 6 requires that PWR_OK, 12V, and +5MAIN from the ATX are all up before allowing the IC to go to S0.

Figure 6. Using PWR_OK to Enable 5V MAIN

Care should also be taken to ensure that 3.3V-ALW does not glitch during the transition to S0. As shown in Figure 7, the 3.3V internal regulator turns off as soon as 5V MAIN crosses its rising threshold, releasing S3#O. While the gate capacitances of Q5, Q7, and Q3 charge sufficiently to turn Q5 on, the load current on 3.3-ALW is supplied by C12. There is an initial "ESR step" of $I_{3,3}$ x ESR_{C12}, where $I_{3,3}$ is the 3.3-ALW load current. This is followed by a discharge of C12 whose

slope is proportional to $\frac{3.3}{C12}$ $\frac{I_{3.3}}{24.3}$. To ensure that the drop in 3.3-

ALW during this transition does not cause system problems, use sufficiently low ESR capacitors and a sufficiently low value for R4 to ensure that 3.3-ALW remains inside the required system tolerance.

Figure 7. 3.3V-ALW Transition to S0

S5 to S5 M1 or S3: During S5 to S3 transition, the IC pulls SBSW (or SBUSB# if enabled by S4ST#) low with a 500nA current sink to limit inrush in Q4 if 5V MAIN is below its UVLO threshold. At that time, 5V DUAL and 5V USB are discharged. The limited gate drives control the inrush current through Q4 or Q6 as they charge their respective load capacitances on 5V DUAL and 5V USB respectively. Depending on the C_{GD} of Q4 and Q6, the current available from 5VSB, and the size of C_{IN} and C15, C13 and C14 may be omitted.

$$
I_{\text{Q4(INRUSH)}} = \frac{\text{CIN} \cdot 5 \times 10^{-7}}{\text{C13} + \text{C}_{\text{GD(Q4)}}}
$$

$$
I_{\text{Q6(INRUSH)}} = \frac{\text{C15} \cdot 5 \times 10^{-7}}{\text{C14} + \text{C}_{\text{GD(Q6)}}}
$$
 (2)

If 5V MAIN is above its UVLO threshold, SBSW (or SBUSB# if enabled by S4ST#) is pulled down with an impedance of ~150Ω. VDDQ and VTT do not start until 5V MAIN OK is true.

PWM Regulator

A PSPICE model and spreadsheet calculator are available in Application Note AN-6006 for the VDDQ PWM regulator to select external components and verify loop stability. The topics covered below provide the explanation behind the calculations in the spreadsheet.

Setting the Output Voltage

The output voltage of the PWM regulator can be set in the range of 0.9V to 80% of its power input by an external resistor divider.

The internal reference is 0.9V. The output is divided down by an external voltage divider to the FB pin (for example, R1 and R2 in Figure 1). There is also a 1.3μA current sourced out of FB to ensure that if the pin is open, VDDQ remains low. The output voltage therefore is:

$$
\frac{0.9V}{R2} = \frac{V_{OUT} - 0.9V}{R1} + 1.3\,\mu\text{A}
$$
 (3a)

To minimize noise pickup on this node, keep the resistor to GND (R2) below 2K. In the example below, R2 is 1.82K and R1 is calculated:

$$
R1 = \frac{R2 \cdot (V_{\text{OUT}} - 0.9)}{0.9 - 1.3 \,\mu\text{A}} =
$$
\n
$$
1.815K \approx 1.82K
$$
\n(3b)

The synchronous buck converter is optimized for 5V input operation. The PWM modulator uses an average current mode control for simplified feedback loop compensation.

Oscillator

The oscillator frequency is 300Khz. The internal PWM ramp is reset on the rising clock edge.

PWM Soft Start

When the PWM regulator is enabled, the circuit waits until the VDDQ IN pin is below 100mV to ensure that the softstart cycle does not begin with a large residual voltage on the PWM regulator output.

When the PWM regulator is disabled, 40Ω is connected from VDDQ IN to PGND to discharge the output. The circuit waits until the FB pin is below 100mV to ensure that the soft-start cycle does not begin with a large residual voltage on the VDDQ regulator output.

The voltage at the positive input of the error amplifier is limited to V_{CSS} , which is charged with about 45 μ A. Once C_{SS} has charged to 0.9V, the output voltage is in regulation.

The time it takes SS to reach 0.9V, and VDDQ to achieve regulation is:

$$
T_{0.9} \approx \frac{0.9 \times C_{SS}}{45} \tag{4}
$$

where $T_{0.9}$ is in mS if C_{SS} is in nF.

CSS charges another 400mV before the PWM regulator's fault latch is enabled. When CSS reaches 1.2V, the VTT regulator begins its soft-start. After VTT is in regulation, PGOOD is allowed to go HIGH (open).

Reference Output for ULDO Controllers

The FAN5078's ILIM pin (pin 20) may be used as a precision 0.9V reference for external ULDO controllers, as shown in Figure 9. The ILIM pin is on during all ACPI states.

Figure 9. Using ILIM as a ULDO Reference

R5 in Figure 1 is the current limit setting resistor and comprises the only DC current path from the ILIM pin to GND. The circuit is configured so that the reference for the ULDO is presented at the positive terminal of U1 and draws negligible DC current. R3 and C1 filter noise that might be induced if there is significant PCB trace length. C1 should be placed as close as possible to the op-amp's input pin. R3 should be placed as close as possible to pin 20 of the FAN5078 and should be greater than 10K to isolate the ILIM pin from noise.

Recommended values for the circuit of Figure 9:

© 2006 Fairchild Semiconductor Corporation 12 www.fairchildsemi.com FAN5078 Rev. 1.0.0 • 05/11/06

Current Processing Section

The following discussion refers to Figure 10.

The current through R_{SENSE} resistor (ISNS) is sampled shortly after Q2 is turned on. That current is held and summed with the output of the error amplifier. This effectively creates a current mode control loop. R_{SENSE} sets the gain in the current feedback loop. For stable operation, the voltage induced by the current feedback at the PWM comparator input should be set to 30% of the ramp amplitude at maximum load current and line voltage.

Equation 5 estimates the recommended value of R_{SENSE} as a function of the maximum load current ($I_{\text{LOAD(MAX)}}$) and the value of the MOSFET's $R_{DS(ON)}$:

$$
R_{\text{SENSE}} = \frac{I_{\text{LOAD(MAX)}} \cdot R_{\text{DS(ON)}} \cdot 4.41 \text{K}}{30\% \cdot 0.125 \cdot V_{\text{IN(MAX)}}} - 100
$$

 (5)

where $R_{DS(ON)}$ is the maximum $R_{DS(ON)}$ of the low-side MOSFET at its maximum temperature.

R_{SENSE} must, however, be kept higher than:

$$
R_{SENSE(MIN)} = \frac{I_{LOAD(MAX)} \cdot R_{DS(ON)}}{145\mu A} - 100
$$
 (6)

Setting the Current Limit

ISNS is compared to the current established when a 0.9 V internal reference drives the ILIM pin. R_{ILIM} , the $R_{DS(ON)}$ of Q2, and R_{SENSE} determine the current limit:

$$
R_{ILIM} = \frac{9.6}{I_{LIMIT}} \times \frac{(100 + R_{SENSE})}{R_{DS(ON)}}
$$
(7)

where ILIMIT is the peak inductor current. Since the tolerance on the current limit is largely dependent on the ratio of the external resistors it is fairly accurate if the voltage drop on the switching node side of R_{SENSE} is an accurate representation of the load current. When using the MOSFET as the sensing element, the variation of $R_{DS(ON)}$ causes proportional variation in the ISNS. This value not only varies from device to device, but also has a typical junction temperature coefficient of about 0.4% / °C (consult the MOSFET datasheet for actual values), so the actual current limit set point decreases proportional to increasing MOSFET die temperature. A factor of 1.6 in the current limit set point should compensate for MOSFET $R_{DS(ON)}$

variations, assuming the MOSFET's heat sinking keeps its operating die temperature below 125°C.

Current limit (I_{LIMIT}) should be set sufficiently high as to allow the inductor current to rise in response to an output load transient. Typically, a factor of 1.3 is sufficient. In addition, since I_{LIMIT} is a peak current cut-off value, multiply $I_{LOAD(MAX)}$ by the inductor ripple current (i.e. 20%). To account all of these variations, set ILIMIT as:

$$
I_{LIMIT} > I_{LOAD(MAX)} \times 1.6 \times 1.3 \times 1.2
$$
 (8)

Figure 11. Improving Current Sensing Accuracy

More accurate sensing can be achieved by using a resistor (R1) instead of the $R_{DS(ON)}$ of the FET, as shown in Figure 11. This approach causes higher losses, but greater accuracy.

Gate Drive

The adaptive gate control logic translates the internal PWM control signal into the MOSFET gate drive signals, providing necessary amplification, level shifting, and shoot-through protection. It also has functions to help optimize the IC performance over a wide range of operating conditions.

Since MOSFET switching time can vary dramatically from type to type and with the input voltage, the gate control logic provides adaptive dead time by monitoring the gate-to-source voltages of both upper and lower MOSFETs. The lower MOSFET drive is not turned on until the gate-to-source voltage of the upper MOSFET has decreased to less than approximately 1 volt. Similarly, the upper MOSFET is not turned on until the gate-to-source voltage of the lower MOSFET has decreased to less than approximately 1 volt. This allows a wide variety of upper and lower MOSFETs to be used without a concern for simultaneous conduction or shoot-through.

There must be a low-resistance, low-inductance path between the driver pin and the MOSFET gate for the adaptive deadtime circuit to work properly. Any delay along that path subtracts from the delay generated by the adaptive dead-time circuit and shoot-through may occur.

© 2006 Fairchild Semiconductor Corporation 13 www.fairchildsemi.com FAN5078 Rev. 1.0.0 • 05/11/06

Frequency Loop Compensation

The loop is compensated using a feedback network around the error amplifier.

Figure 12. Compensation Network

Figure 12 shows a complete Type 3 compensation network. A Type 2 compensation configuration eliminates R4 and C3 and is shown in Figure 1. Since the FAN5078 architecture employs summing current mode, Type 2 compensation can be used for most applications. For critical applications that require wide loop bandwidth and use very low ESR output capacitors, Type 3 compensation may be required. The PSPICE model and spreadsheet calculator of AN-6006 can be used to calculate these component values.

Transient response during a rapid decrease in I_{LOAD} can be improved by adding a pull-down resistor (> 5K) from the COMP pin to GND.

PGOOD Signal

PGOOD monitors the status of the PWM output as well as VTT. PGOOD remains low unless all of the conditions below are met:

- SS is above 3.5V
- Fault latch is cleared
- FB is between 90% and 110% of VREF
- VTT is in regulation.

Protection

The converter output is monitored and protected against extreme overload, short circuit, over-voltage and undervoltage conditions.

An internal fault latch is set for any fault intended to shut down the IC. When the fault latch is set, the IC discharges its output by driving LDRV high until VDDQ IN < 0.5V. LDRV then goes low until VDDQ IN > 0.8V. This discharges VDDQ without causing undershoot (negative output voltage).

To discharge the output capacitors, a 40Ω load resistor is switched in from VDDQ IN to PGND whenever the IC is in fault condition or when EN is low. After a latched fault,

operation can be restored by recycling power or toggling the EN pin.

Under-Voltage Shutdown

If FB stays below the under-voltage threshold for $2\mu S$, the fault latch is set. This fault is prevented from setting the fault latch during PWM soft-start (SS < 1.3V).

Over-Current Sensing

If the circuit's current limit signal (ILIM det shown in Figure 10) is high at the beginning of a clock cycle, a pulse-skipping circuit is activated and HDRV is inhibited. The circuit continues to pulse skip in this manner for the next 8 clock cycles. If, at any time from the $9th$ to the 16th clock cycle, the ILIM det is again reached, the fault latch is set. If ILIM det does not occur between cycle 9 and 16, normal operation is restored and the over-current circuit resets itself.

This fault is prevented from setting the fault latch during softstart ($SS < 1.3V$).

Figure 13. Over-Current Protection Waveforms

OVP / HS Fault / FB short to GND detection

A HS Fault is detected when there is more than 0.5V from SW to PGND 350nS after LDRV reaches 4V (same as the current sampling time).

OVP fault detection occurs if FB > 115% VREF for 16 clock cycles.

During soft-start, the output voltage could potentially "run away" if either the FB pin is shorted to GND or R1 is open. This fault is detected if the following condition persists for more than 14μS during soft-start:

- ̇ VDDQ IN (PWM output voltage) > 1V
- \blacksquare FB < 100mV

Any of these faults sets the fault latch, even during the SS time $(SS < 1.2V)$.

To ensure that FB pin open does not cause a destructive condition, a 1.3μA current source ensures that the FB pin is high if open. This causes the regulator to keep the output low and eventually results in an under-voltage fault shutdown (after PWM SS completes).

Figure 14. SS Clamp and FB Open Protection

Over-Temperature Protection

The chip incorporates an over-temperature protection circuit that shuts the chip down when a die temperature of about 150°C is reached. Normal operation is restored when the die temperature falls below 125°C with internal Power On Reset asserted, resulting in a full soft-start cycle. To accomplish this, the over-temperature comparator discharges the SS pin.

VTT Regulator Section (Figure 3)

The VTT regulator includes an internal resistor divider (50K for each resistor) from the output of the PWM regulator. If the REF IN pin is left open, the divider produces a voltage 50% of VDDQ IN. Using a low impedance external precision voltage divider produces greater accuracy.

The VTT regulator is enabled when S3#I is HIGH and the PWM regulator's internal PGOOD signal is true. The VTT regulator also includes its own PGOOD signal, which is high when VTT SNS > 90% of REF IN.

FAN5078 Design Tools

AN-6006 provides a PSPICE model and spreadsheet calculator for the PWM regulator, simplifying external component selections, and verifying loop stability.

The spreadsheet calculator can be used to calculate all external component values for the FAN5078. The spreadsheet calculates compensation components that can be verified in the PSPICE model to ensure stability.

The PSPICE model in AN-6006 simulates both loop stability (Bode Plot) and transient analysis, and can be customized for a wide variety of applications and external component configurations.

As an initial step, define:

- Output voltage
- Maximum PWM output load current
- Maximum load transient current and maximum allowable output drop during load transient
- \blacksquare R_{DS(ON)} of the low-side MOSFET (Q2)
- Maximum allowable output ripple.

Power MOSFET Selection

For a complete analysis of MOSFET selection and efficiency calculations, see Application Note *AN-6005: Synchronous Buck MOSFET Loss Calculations with Excel Mode*l.

3.3V and VTT LDO Output Capacitors

For stability, use at least 100μF for 3.3V-ALW bypass capacitor with a minimum ESR of 20mΩ.

The VTT output is typically bypassed with 820μF with at least 30mΩ ESR.

-
- 2. Dimensions are in millimeters.
3. Dimensions and tolerances pe Dimensions and tolerances per ASME y14.5-1994.

© 2006 Fairchild Semiconductor Corporation 16 www.fairchildsemi.com FAN5078 Rev. 1.0.0 • 05/11/06

FAN5078 DDR/ACPI Regulator Combo

FANSONS DDR/ACPI Regulator Compo