SONY

Diagonal 4.5mm (Type 1/4) CCD Image Sensor for NTSC Color Video Cameras

ICX226AZ

Description

The ICX226AZ is an interline CCD solid-state image sensor suitable for NTSC color video cameras. Compared with the current product ICX206AZ, smear charactristics are improved drastically and power consumption is reduced.

Ye, Cy, Mg, and G complementary color mosaic filters are used. High sensitivity and high saturation signal are achieved by Super HAD CCD technology.

This chip features a field period readout system and an electronic shutter with variable charge-storage time. The package is a 10mm-square 14-pin DIP (Plastic).

Features

- ◆ Low smear (-105dB Typ. at F5.6)
- ◆ Low power consumption (-34% compared with ICX206AZ)
- ◆ High sensitivity (+2.5dB at F1.2 compared with ICX206AZ)
- High saturation signal
- ◆ Supply voltage: 12V
- ◆ Horizontal register: 3.3V drive
- ◆ Reset gate: 3.3V drive
- No voltage adjustment (Reset gate and substrate bias need no adjustment.)
- ◆ Low dark current
- ◆ Excellent antiblooming characteristics
- ◆ Continuous variable-speed shutter
- ◆ Recommended range of exit pupil distance: -20 to -100mm
- ◆ Ye, Cy, Mg, and G complementary color mosaic filters on chip

Package

14-pin DIP (Plastic)

Super HAD CCD TM

* "Super HAD CCD" is a trademark of Sony Corporation. The "Super HAD CCD" is a version of Sony's high performance CCD HAD (Hole-Accumulation Diode) sensor with sharply improved sensitivity by the incorporation of a new semiconductor technology developed by Sony Corporation.

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- 1 - E01223B8Y-CR

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Device Structure

◆ Interline CCD image sensor

◆ Image size : Diagonal 4.5mm (Type 1/4)

Number of effective pixels : 510 (H) × 492 (V) approx. 0.25M pixels
 Total number of pixels : 537 (H) × 505 (V) approx. 0.27M pixels

♦ Chip size : 4.34mm (H) × 3.69mm (V) ♦ Unit cell size : 7.15μm (H) × 5.55μm (V)

◆ Optical black : Horizontal (H) direction: Front 2 pixels, rear 25 pixels

Vertical (V) direction : Front 12 pixels, rear 1 pixel

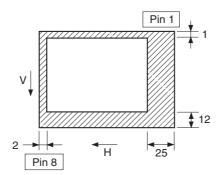
◆ Number of dummy bits : Horizontal: 16

Vertical: 1 (even fields only)

◆ Substrate material : Silicon

Optical Black Position

(Top View)



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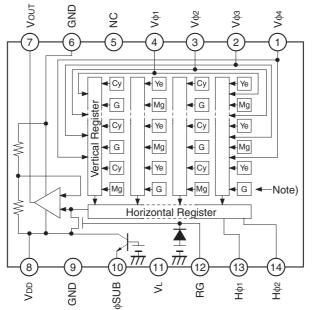
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Block Diagram and Pin Configuration

(Top View)



Note) : Photo sensor

Pin Description

Pin No.	Symbol	Description	Pin No.	Symbol	Description
1	Vф4	Vertical register transfer clock	8	VDD	Supply voltage
2	Vфз	Vertical register transfer clock	9	GND	GND
3	V ф2	Vertical register transfer clock	10	φSUB	Substrate clock
4	V ₀ 1	Vertical register transfer clock	11	VL	Protective transistor bias
5	NC		12	RG	Reset gate clock
6	GND	GND	13	Нф1	Horizontal register transfer clock
7	Vout	Signal output	14	Нф2	Horizontal register transfer clock

Absolute Maximum Ratings

	Item	Ratings	Unit	Remarks
	VDD, VOUT, RG – фSUB	-32 to +12	V	
Against JCLID	Vφ1, Vφ3 – φSUB	-40 to +15	V	
Against φSUB	Vφ2, Vφ4, VL – φSUB	-40 to +0.3	V	
	Hφ1, Hφ2, GND – φSUB	-32 to +0.3	V	
	VDD, VOUT, RG – GND	-0.3 to +17	V	
Against GND	Vφ1, Vφ2, Vφ3, Vφ4 – GND	-7 to +14	V	
	Hφ1, Hφ2 – GND	-7 to +4.2	V	
Against \/	Vφ1, Vφ3 – VL	-0.3 to +21	V	
Against V∟	Vφ2, Vφ4, Hφ1, Hφ2, GND – VL	-0.3 to +12	V	
	Voltage difference between vertical clock input pins	to +12	V	*1
Between input clock pins	Hφ1 – Hφ2	−5 to +5	V	
	Hφ1, Hφ2 – Vφ4	-12 to +12	V	
Storage temperature	-30 to +80	°C		
Operating temperature	-10 to +60	°C		

^{*1 +21}V (Max.) when clock width < 10μ s, clock duty factor < 0.1%.

Bias Conditions

Item	Symbol	Min.	Тур.	Max.	Unit	Remarks
Supply voltage	VDD	11.64	12.0	12.36	V	
Protective transistor bias	VL		*1			
Substrate clock	φSUB		*2			
Reset gate clock	φRG		*2			

^{*1} VL setting is the VvL voltage of the vertical transfer clock waveform, or the same power supply as the VL power supply for the V driver should be used.

DC Characteristics

Item	Symbol	Min.	Тур.	Max.	Unit	Remarks
Supply current	Idd		2.5	5	mA	

^{*2} Do not apply a DC bias to the substrate clock and reset gate clock pins, because a DC bias is generated within the CCD.

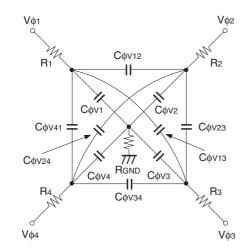


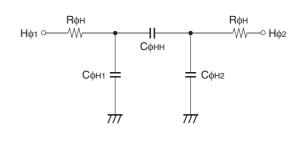
Clock Voltage Conditions

Item	Symbol	Min.	Тур.	Max.	Unit	Waveform diagram	Remarks
Readout clock voltage	Vvт	11.64	12.0	12.36	٧	1	
	Vvh1, Vvh2	-0.05	0	0.05	V	2	VvH = (VvH1 + VvH2)/2
	VvH3, VvH4	-0.2	0	0.05	V	2	
	VVL1, VVL2, VVL3, VVL4	-5.5	-5.0	-4.5	٧	2	VVL = (VVL3 + VVL4)/2
Vertical transfer	Vφv	4.3	5.0	5.55	٧	2	$V\phi V = VVHN - VVLN$ (n = 1 to 4)
clock voltage	V vнз — V vн	-0.25		0.1	V	2	
	Vvh4 – Vvh	-0.25		0.1	V	2	
	Vvнн			0.3	V	2	High-level coupling
	VVHL			0.3	V	2	High-level coupling
	VVLH			0.3	V	2	Low-level coupling
	VVLL			0.3	V	2	Low-level coupling
Horizontal transfer	Vфн	3.0	3.3	3.6	V	3	
clock voltage	VHL	-0.05	0	0.05	V	3	
Reset gate	VþRG	3.0	3.3	3.6	٧	4	Input through 0.1μF capacitance
clock voltage	VRGLH – VRGLL			0.4	V	4	Low-level coupling
	VRGL - VRGLm			0.5	V	4	Low-level coupling
Substrate clock voltage	VþsuB	16.14	17.0	17.86	V	5	

Clock Equivalent Circuit Constants

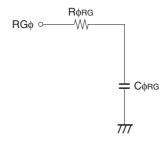
Item	Symbol	Min.	Тур.	Max.	Unit	Remarks
Capacitance between vertical transfer clock	СфV1, СфV3		560		pF	
and GND	Сф∨2, Сф∨4		270		pF	
	СфV12, СфV34		180		pF	
Canaditanes between vertical transfer clocks	СфV23, СфV41		100		pF	
Capacitance between vertical transfer clocks	СфV13		100		pF	
	СфV24		100		pF	
Capacitance between horizontal transfer clock and GND	Сфн1, Сфн2		33		pF	
Capacitance between horizontal transfer clocks	Сфнн		15		pF	
Capacitance between reset gate clock and GND	СфRG		5		pF	
Capacitance between substrate clock and GND	Сфѕив		110		pF	
Vertical transfer clock series resistor	R1, R2, R3, R4		110		Ω	
Vertical transfer clock ground resistor	RGND		15		Ω	
Horizontal transfer clock series resistor	Rфн		15		Ω	
Reset gate clock series resistor	Rørg		39		Ω	





Vertical transfer clock equivalent circuit

Horizontal transfer clock equivalent circuit

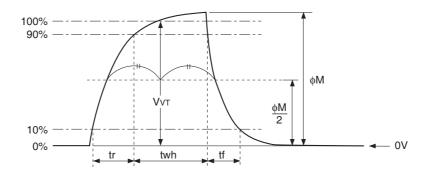


Reset gate clock equivalent circuit

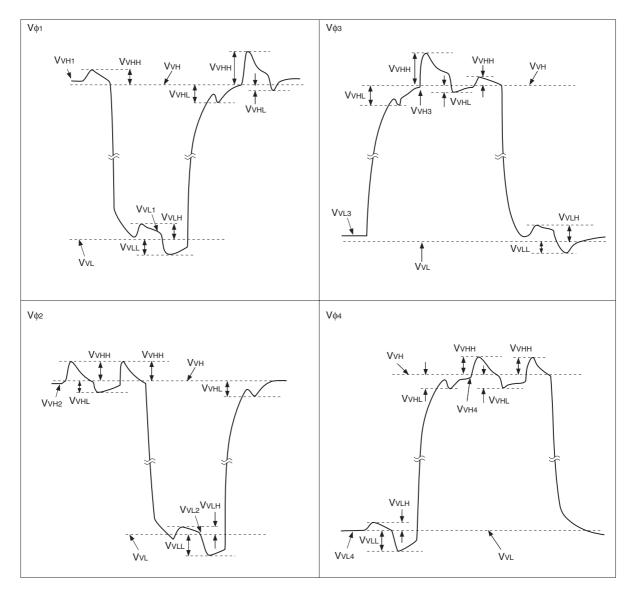
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Drive Clock Waveform Conditions

1. Readout clock waveform



2. Vertical transfer clock waveform



 $V_{VH} = (V_{VH1} + V_{VH2})/2$

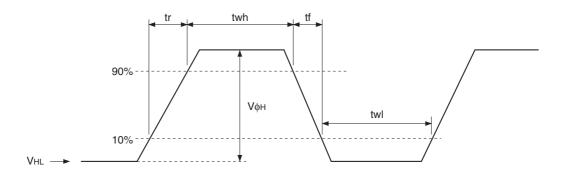
 $V_{VL} = (V_{VL3} + V_{VL4})/2$

 $V\phi V = VVHN - VVLN (n = 1 to 4)$

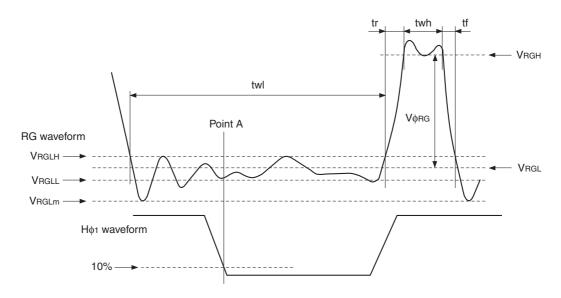
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3. Horizontal transfer clock waveform



4. Reset gate clock waveform



 VRGLH is the maximum value and VRGLL is the minimum value of the coupling waveform during the period from Point A in the above diagram until the rising edge of RG.

In addition, VRGL is the average value of VRGLH and VRGLL.

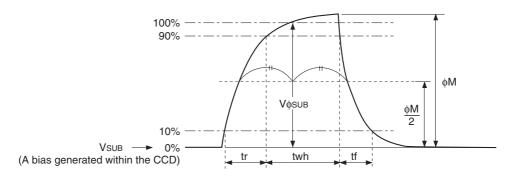
VRGL = (VRGLH + VRGLL)/2

Assuming VRGH is the minimum value during the interval twh, then:

 $V\phi RG = VRGH - VRGL$

Negative overshoot level during the falling edge of RG is VRGLm.

5. Substrate clock waveform





Clock Switching Characteristics

	Item	Symbol	twh		twl		tr		tf			Unit	Remarks			
	цет	Symbol	Min.	Тур.	Max.	Min.	Тур.	Мах.	Min.	Тур.	Мах.	Min.	Тур.	Max.	Offic	Nemarks
Rea	dout clock	VT	2.3	2.5						0.1			0.1		μS	During readout
Vert	ical transfer clock	Vφ1, Vφ2, Vφ3, Vφ4										5		250	ns	*1
er clock	During imaging	Нф	41	46		41	46			6.5	9.5		6.5	9.5	ns	*2
al transf	During parallel-serial conversion	Нф1		5.6						0.007			0.007		6	
Horizontal transfer		Нф2					5.6			0.007			0.007		μS	
Res	et gate clock	φRG	11	14		76	80			6.0			5.0		ns	
Sub	strate clock	φSUB	1.5	1.65							0.5			0.5	μS	When draining charge

^{*1} When vertical transfer clock driver CXD1267AN is used.

^{*2} When V ϕ H = 3.0V. tf \geq tr – 2ns, and the cross-point voltage (VcR) for the H ϕ 1 rising side of the H ϕ 1 and H ϕ 2 waveforms must be at least V ϕ H/2 [V].

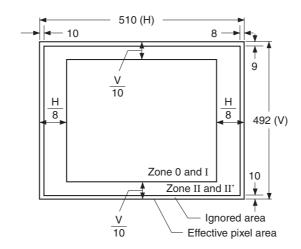


Image Sensor Characteristics

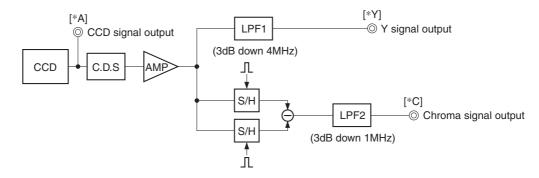
(Ta = 25°C)

Item	Symbol	Min.	Тур.	Max.	Unit	Measurement method	Remarks
Sensitivity	S	680	900		mV	1	
Consistivity ratio	RMgG	0.93		1.35		2	
Sensitivity ratio	RYeCy	1.15		1.48		2	
Saturation signal	Ysat	900			mV	3	Ta = 60°C
Smear	Sm		-105	-95	dB	4	
				20	%	5	Zone 0 and zone I
Video signal shading	SHy			25	%	5	Zone 0, zone I, zone II and zone II'
Uniformity between	ΔSr			10	%	6	
video signal channels	ΔSb			10	%	6	
Dark signal	Ydt			2	mV	7	Ta = 60°C
Dark signal shading	ΔYdt			1	mV	8	Ta = 60°C
Flicker Y	Fy			2	%	9	
Flicker R – Y	Fcr			5	%	9	
Flicker B – Y	Fcb			5	%	9	
Line crawl R	Lcr			3	%	10	
Line crawl G	Lcg			3	%	10	
Line crawl B	Lcb			3	%	10	
Line crawl W	Lcw			3	%	10	
Lag	Lag			0.5	%	11	

Zone Definition of Video Signal Shading



Measurement System



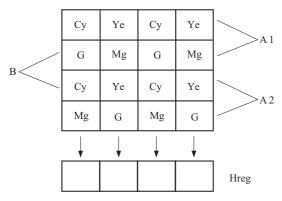
Note) Adjust the amplifier gain so that the gain between [*A] and [*Y], and between [*A] and [*C] equals 1.

Image Sensor Characteristics Measurement Method

Measurement conditions

- 1. In the following measurements, the device drive conditions are at the typical values of the bias and clock voltage conditions.
- 2. In the following measurements, spot pixels are excluded and, unless otherwise specified, the optical black level (OB) is used as the reference for the signal output, which is taken as the value of Y signal output or chroma signal output of the measurement system.

Color coding of this image sensor & Composition of luminance (Y) and chroma (color difference) signals



As shown in the left figure, fields are read out. The charge is mixed by pairs such as A1 and A2 in the A field. (pairs such as B in the B field)

As a result, the sequence of charges output as signals from the horizontal shift register (Hreg) is, for line A1, (G + Cy), (Mg + Ye), (G + Cy), and (Mg + Ye).

Color Coding Diagram

These signals are processed to form the Y signal and chroma (color difference) signal. The Y signal is formed by adding adjacent signals, and the chroma signal is formed by subtracting adjacent signals. In other words, the approximation:

$$Y = {(G + Cy) + (Mg + Ye)} \times 1/2$$

= 1/2 {2B + 3G + 2R}

is used for the Y signal, and the approximation:

$$R - Y = \{(Mg + Ye) - (G + Cy)\}\$$

= $\{2R - G\}$

is used for the chroma (color difference) signal. For line A2, the signals output from Hreg in sequence are (Mg + Cy), (G + Ye), (Mg + Cy), (G + Ye)

The Y signal is formed from these signals as follows:

$$Y = \{(G + Ye) + (Mg + Cy)\} \times 1/2$$

= 1/2 {2B + 3G + 2R}

This is balanced since it is formed in the same way as for line A1.

In a like manner, the chroma (color difference) signal is approximated as follows:

$$-(B-Y) = \{(G + Ye) - (Mg + Cy)\}\$$

= $-\{2B - G\}$

In other words, the chroma signal can be retrieved according to the sequence of lines from R-Y and -(B-Y) in alternation. This is also true for the B field.

Definition of Standard Imaging Conditions

Standard imaging condition I:

Use a pattern box (luminance: 706cd/m², color temperature of 3200K halogen source) as a subject. (Pattern for evaluation is not applicable.) Use a testing standard lens with CM500S (t = 1.0mm) as an IR cut filter and image at F5.6. The luminous intensity to the sensor receiving surface at this point is defined as the standard sensitivity testing luminous intensity.

◆ Standard imaging condition II:

Image a light source (color temperature of 3200K) with a uniformity of brightness within 2% at all angles. Use a testing standard lens with CM500S (t = 1.0mm) as an IR cut filter. The luminous intensity is adjusted to the value indicated in each testing item by the lens diaphragm.

Standard imaging condition III:

Image a light source (color temperature of 3200K) with a uniformity of brightness within 2% at all angles. Use a testing standard lens (exit pupil distance –33mm) with CM500S (t = 1.0mm) as an IR cut filter. The luminous intensity is adjusted to the value indicated in each testing item by the lens diaphragm.

1. Sensitivity

Set to standard imaging condition I. After selecting the electronic shutter mode with a shutter speed of 1/250s, measure the Y signal (Ys) at the center of the screen and substitute the value into the following formula

$$S = Ys \times (250/60) [mV]$$

2. Sensitivity ratio

Set to standard imaging condition II. Adjust the luminous intensity so that the average value of the Y signal output is 200 mV, and then measure the Mg signal output (S_{Mg} [mV]) and G signal output (S_{G} [mV]), and Ye signal output (S_{Ye} [mV]) and Cy signal output (S_{Cy} [mV]) at the center of the screen with frame readout method. Substitute the values into the following formula.

$$RMgG = SMg/SG$$

 $RYeCy = SYe/SCy$

3. Saturation signal

Set to standard imaging condition II. After adjusting the luminous intensity to 10 times the intensity with average value of the Y signal output, 200mV, measure the minimum value of the Y signal.

4. Smear

Set to standard imaging condition II. With the lens diaphragm at F5.6 to F8, adjust the luminous intensity to 500 times the intensity with average value of the Y signal output, 200mV. When the readout clock is stopped and the charge drain is executed by the electronic shutter at the respective H blankings, measure the maximum value (YSm [mV]) of the Y signal output and substitute the value into the following formula.

Sm =
$$20 \times \log \{(YSm/200) \times (1/500) \times (1/10)\} [dB] (1/10V method conversion value)$$

5. Video signal shading

Set to standard imaging condition III. With the lens diaphragm at F5.6 to F8, adjust the luminous intensity so that the average value of the Y signal output is 200mV. Then measure the maximum (Ymax [mV]) and minimum (Ymin [mV]) values of the Y signal and substitute the values into the following formula.

SHy =
$$(Ymax - Ymin)/200 \times 100 [\%]$$

6. Uniformity between video signal channels

Set to standard imaging condition II. Adjust the luminous intensity so that the average value of the Y signal output is 200 mV, and then measure the maximum (Crmax, Cbmax [mV]) and minimum (Crmin, Cbmin [mV]) values of the R – Y and B – Y channels of the chroma signal and substitute the values into the following formula.

$$\Delta Sr = | (Crmax - Crmin)/200 | \times 100 [\%]$$

 $\Delta Sb = | (Cbmax - Cbmin)/200 | \times 100 [\%]$

7. Dark signal

Measure the average value of the Y signal output (Ydt [mV]) with the device ambient temperature 60°C and the device in the light-obstructed state, using the horizontal idle transfer level as a reference.

8. Dark signal shading

After measuring 7, measure the maximum (Ydmax [mV]) and minimum (Ydmin [mV]) values of the Y signal output and substitute the values into the following formula.

$$\Delta Ydt = Ydmax - Ydmin [mV]$$

9. Flicker

(1) Fy

Set to standard imaging condition II. Adjust the luminous intensity so that the average value of the Y signal output is 200mV, and then measure the difference in the signal level between fields (Δ Yf [mV]). Then substitute the value into the following formula.

$$Fy = (\Delta Yf/200) \times 100 [\%]$$

(2) Fcr, Fcb

Set to standard imaging condition II. Adjust the luminous intensity so that the average value of the Y signal output is 200mV, insert an R or B filter, and then measure both the difference in the signal level between fields of the chroma signal (Δ Cr, Δ Cb) as well as the average value of the chroma signal output (CAr, CAb). Substitute the values into the following formula.

Fci =
$$(\Delta Ci/CAi) \times 100 [\%] (i = r, b)$$

10. Line crawls

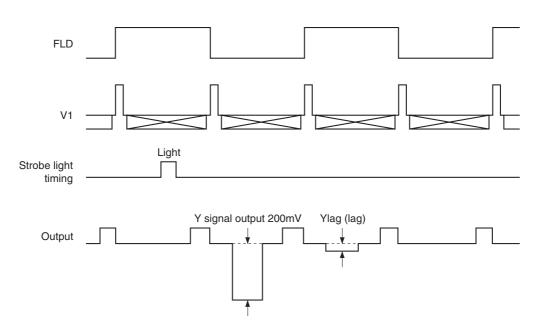
Set to standard imaging condition II. Adjust the luminous intensity so that the average value of the Y signal output is 200mV, and then insert a white subject and R, G, and B filters and measure the difference between Y signal lines for the same field (Δ Ylw, Δ Ylr, Δ Ylg, Δ Ylb [mV]). Substitute the values into the following formula.

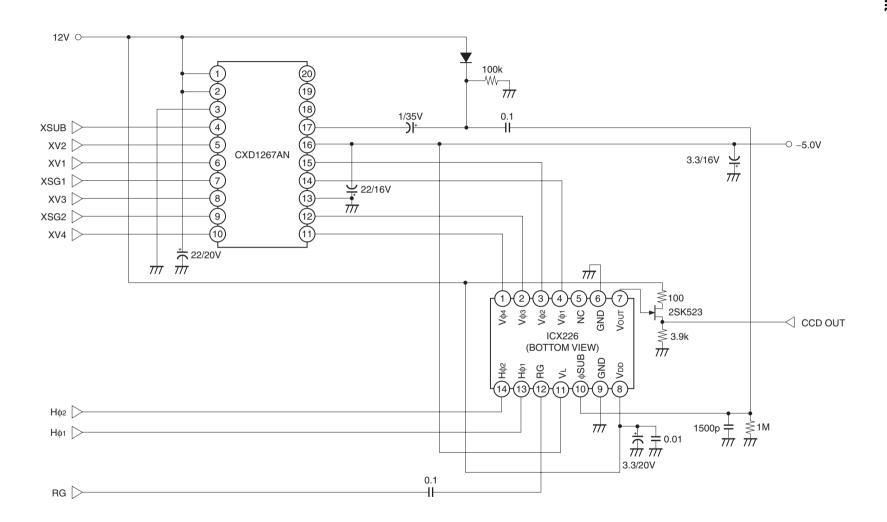
Lci =
$$(\Delta Y li/200) \times 100 [\%]$$
 (i = w, r, g, b)

11. Lag

Adjust the Y signal output value generated by strobe light to 200mV. After setting the strobe light so that it strobes with the following timing, measure the residual signal (Ylag). Substitute the value into the following formula.

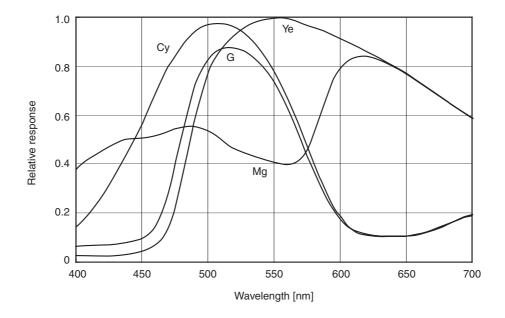
Lag = $(Ylag/200) \times 100 [\%]$



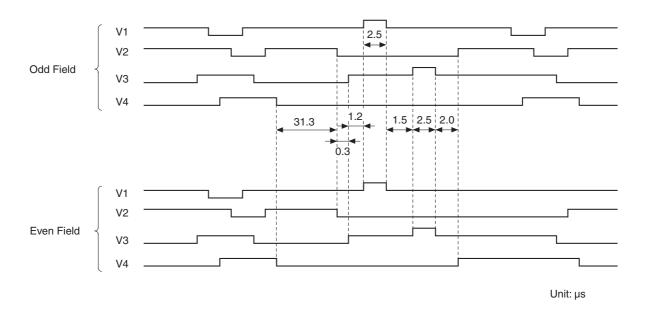


Spectral Sensitivity Characteristics

(excludes both lens characteristics and light source characteristics)

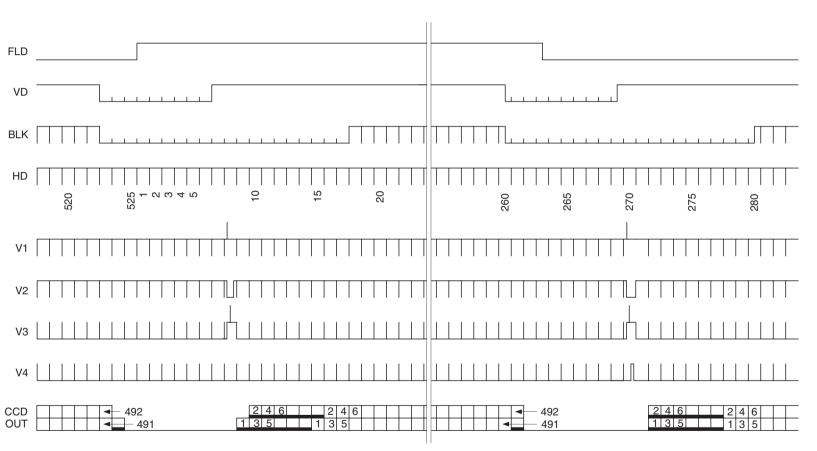


Sensor Readout Clock Timing Chart

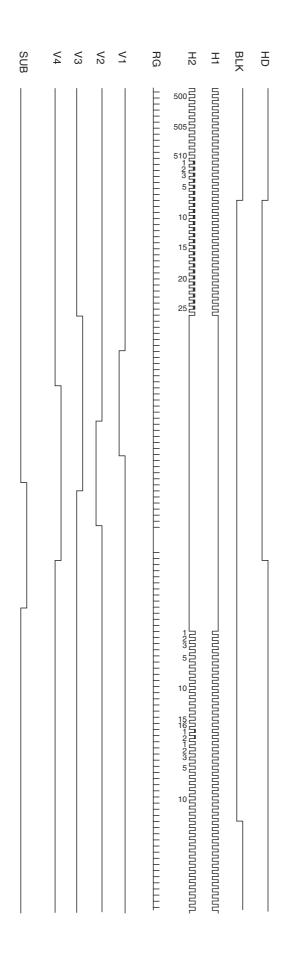


Drive Timing Chart

Vertical Sync







Horizontal Sync

Notes On Handling

1. Static charge prevention

CCD image sensors are easily damaged by static discharge. Before handling be sure to take the following protective measures.

- Either handle bare handed or use non-chargeable gloves, clothes or material.
 Also use conductive shoes.
- (2) When handling directly use an earth band.
- (3) Install a conductive mat on the floor or working table to prevent the generation of static electricity.
- (4) Ionized air is recommended for discharge when handling CCD image sensor.
- (5) For the shipment of mounted substrates, use boxes treated for the prevention of static charges.

2. Soldering

- (1) Make sure the package temperature does not exceed 80°C.
- (2) Solder dipping in a mounting furnace causes damage to the glass and other defects. Use a ground 30W soldering iron and solder each pin in less than 2 seconds. For repairs and remount, cool sufficiently.
- (3) To dismount an image sensor, do not use a solder suction equipment. When using an electric desoldering tool, use a thermal controller of the zero cross On/Off type and connect it to ground.

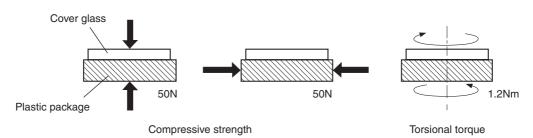
3. Dust and dirt protection

Image sensors are packed and delivered by taking care of protecting its glass plates from harmful dust and dirt. Clean glass plates with the following operation as required, and use them.

- (1) Perform all assembly operations in a clean room (class 1000 or less).
- (2) Do not either touch glass plates by hand or have any object come in contact with glass surfaces. Should dirt stick to a glass surface, blow it off with an air blower. (For dirt stuck through static electricity ionized air is recommended.)
- (3) Clean with a cotton bud and ethyl alcohol if the grease stained. Be careful not to scratch the glass.
- (4) Keep in a case to protect from dust and dirt. To prevent dew condensation, preheat or precool when moving to a room with great temperature differences.
- (5) When a protective tape is applied before shipping, just before use remove the tape applied for electrostatic protection. Do not reuse the tape.

4. Installing (attaching)

(1) Remain within the following limits when applying a static load to the package. Do not apply any load more than 0.7mm inside the outer perimeter of the glass portion, and do not apply any load or impact to limited portions. (This may cause cracks in the package.)



- (2) If a load is applied to the entire surface by a hard component, bending stress may be generated and the package may fracture, etc., depending on the flatness of the bottom of the package. Therefore, for installation, use either an elastic load, such as a spring plate, or an adhesive.
- (3) The adhesive may cause the marking on the rear surface to disappear, especially in case the regulated voltage value is indicated on the rear surface. Therefore, the adhesive should not be applied to this area, and indicated values should be transferred to the other locations as a precaution.

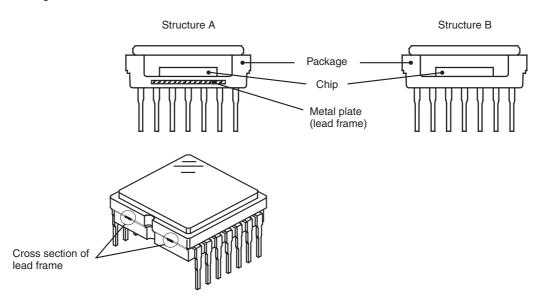
SONY ICX226AZ

(4) The notch of the package is used for directional index, and that can not be used for reference of fixing. In addition, the cover glass and seal resin may overlap with the notch of the package.

- (5) If the lead bend repeatedly and the metal, etc., clash or rub against the package, the dust may be generated by the fragments of resin.
- (6) Acrylate anaerobic adhesives are generally used to attach CCD image sensors. In addition, cyanoacrylate instantaneous adhesives are sometimes used jointly with acrylate anaerobic adhesives. (reference)

5. Others

- (1) Do not expose to strong light (sun rays) for long periods, color filters will be discolored. When high luminance objects are imaged with the exposure level control by electronic-iris, the luminance of the image-plane may become excessive and discolor of the color filter will possibly be accelerated. In such a case, it is advisable that taking-lens with the automatic-iris and closing of the shutter during the power-off mode should be properly arranged. For continuous using under cruel condition exceeding the normal using condition, consult our company.
- (2) Exposure to high temperature or humidity will affect the characteristics. Accordingly avoid storage or usage in such conditions.
- (3) The brown stain may be seen on the bottom or side of the package. But this does not affect the CCD characteristics.
- (4) This package has 2 kinds of internal structure. However, their package outline, optical size, and strength are the same.



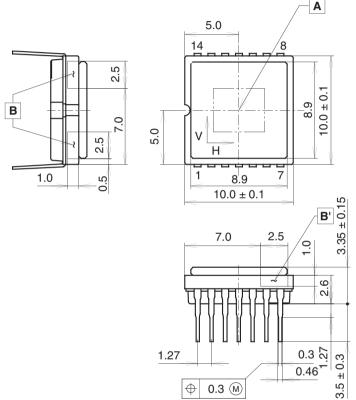
The cross section of lead frame can be seen on the side of the package for structure A.

Package Outline

(Unit: mm)

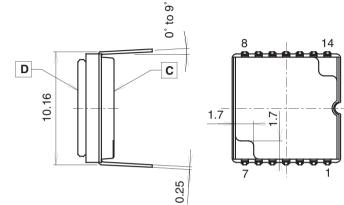
Sony Corporation

14 pin DIP (400mil)



PACKAGE STRUCTURE

PACKAGE MATERIAL	Plastic
LEAD TREATMENT	GOLD PLATING
LEAD MATERIAL	42 ALLOY
PACKAGE MASS	0.60g
DRAWING NUMBER	AS-D3-02(E)



- 1. "A" is the center of the effective image area.
- 2. The two points "B" of the package are the horizontal reference. The point "B" of the package is the vertical reference.
- 3. The bottom "C" of the package, and the top of the cover glass "D" are the height reference.
- 4. The center of the effective image area relative to "B" and "B" is $(H, V) = (5.0, 5.0) \pm 0.15$ mm.
- The rotation angle of the effective image area relative to H and V is $\pm 1\hat{u}$.
- The height from the bottom "C" to the effective image area is 1.41 ± 0.10 mm. The height from the top of the cover glass " \mathbf{D} " to the effective image area is 1.94 ± 0.15mm.
- 7. The tilt of the effective image area relative to the bottom "C" is less than 25µm. The tilt of the effective image area relative to the top "D" of the cover glass is less than 25µm.
- The thickness of the cover glass is 0.75mm, and the refractive index is 1.5.
- The notch of the package is used only for directional index, that must not be used for reference of fixing.
- 10. Cover glass defect

Edge part

Length: no matter, Width: less than 0.5mm, Depth: less than the thickness of the glass.

Length: less than 1.5mm, Depth: less than the thickness of the glass.