



RoH

Power Operational Amplifier

FEATURES

- HIGH VOLTAGE 300 VOLTS
- HIGH OUTPUT CURRENT 1.5 AMPS
- 70 WATT DISSIPATION CAPABILITY
- 175 MHz GAIN BANDWIDTH
- 250 V/µ-SECOND SLEW RATE

APPLICATIONS

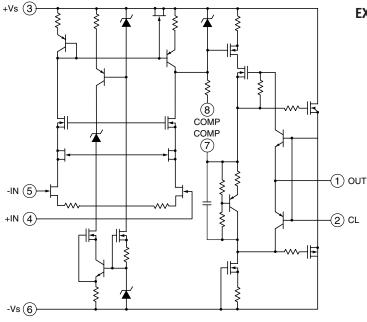
- PZT DRIVE
- MAGNETIC DEFLECTION
- PROGRAMMABLE POWER SUPPLIES
- 70V LINE AUDIO to 70W

DESCRIPTION

The PA96 is a state of the art high voltage, high current operational amplifier designed to drive resistive, capacitive and inductive loads. For optimum linearity, the output stage is biased for class A/B operation. External compensation provides user flexibility in maximizing bandwidth at any gain setting. The safe operating area (SOA) can be observed for all operating conditions by selection of user programmable current limit. For continuous operation under load, a heatsink of proper rating is required.

The hybrid integrated circuit utilizes thick film (cermet) resistors, ceramic capacitors and semiconductor chips to maximize reliability, minimize size and give top performance. Ultrasonically bonded aluminum wires provide reliable interconnections at all operating temperatures. The 8-pin TO-3 package is hermetically sealed and electrically isolated. The use of compressible isolation washers voids the warranty.

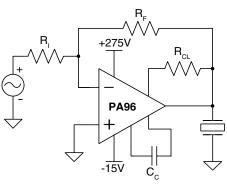
EQUIVALENT CIRCUIT DIAGRAM





8-PIN TO-3 PACKAGE STYLE CE

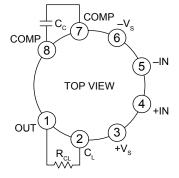
TYPICAL APPLICATION



PZT POSITION CONTROL

The MOSFET output stage of the PA96 provides superior SOA performance compared to bipolar output stages where secondary breakdown is a concern. The extended SOA is ideal in applications where the load is highly reactive and may impose simultaneously both high voltage and high current across the output stage transistors. In the figure above a piezo-electric transducer is driven to high currents and high voltages by the PA96.

EXTERNAL CONNECTIONS





ABSOLUTE MAXIMUM RATINGS	SUPPLY VOLTAGE, +V _s to -V _s OUTPUT CURRENT, continuou POWER DISSIPATION, internal INPUT VOLTAGE, common mod INPUT VOLTAGE, differential TEMPERATURE, pin solder, 10 TEMPERATURE, junction ¹ TEMPERATURE RANGE, stora OPERATING TEMPERATURE,	l, DC de s age	±1: 35: 15: -6:	A, W s to –V _s	
SPECIFICATIONS	TEAT CONDITIONOS		T) (D		
PARAMETER	TEST CONDITIONS ²	MIN	TYP	MAX	UNITS
INPUT OFFSET VOLTAGE OFFSET VOLTAGE vs. temperature OFFSET VOLTAGE vs. supply BIAS CURRENT, initial BIAS CURRENT vs. supply OFFSET CURRENT, initial INPUT RESISTANCE, DC INPUT CAPACITANCE COMMON MODE VOLTAGE RANGE ³ COMMON MODE VOLTAGE RANGE ³ COMMON MODE REJECTION, DC	Full temperature range	+V _s - 13 -V _s + 13 92	1 20 100 4	5 50 200 0.1 50	mV μV/°C μV/V pA pA/V pA GΩ pF V V dB
NOISE GAIN	100KHz bandwidth, 1k Ω R _s		6		μV RMS
OPEN LOOP @ 15Hz GAIN BANDWIDTH PRODUCT @ 1MHz	$R_L = 1k\Omega$, $C_c = 100 pF$ VS = 150V, -VS = 150V, A = -100, RF = 100K	96 100	114 175		dB MHz
PHASE MARGIN	Full temperature range, using	60			0
PBW	recommended C_c for gain. 250V p-p output, 100 Ω , +150V Supplies, Cc = 0pf		100		KHz
OUTPUT VOLTAGE SWING ³ VOLTAGE SWING ³ VOLTAGE SWING ³ VOLTAGE SWING ³ CURRENT, continuous, DC SLEW RATE	$I_o = 1.5A$ $I_o = -1.5A$ $I_o = 0.1A$ $I_o = -0.1A$ $A_v = -100, \pm 150V$ Supplies, 250Ω load negative slope, Positiveslope much faster	$+V_{s} - 12$ $-V_{s} + 12$ $+V_{s} - 8$ $-V_{s} + 8$ 1.5 200	+V _s - 5.6 -V _s + 10 250		V V V A V/µS
SETTLING TIME, to 0.1% RESISTANCE, open loop	$A_v = -100$, 1V Step, $C_c = 0$ pF DC, 1A Load		2 7	10	μS Ω
THERMAL RESISTANCE, AC Junction to Case ⁴ RESISTANCE, DC Junction to Case RESISTANCE, Junction to Ambient TEMPERATURE RANGE, case	Full temperature range. f > 60Hz Full temperature range. f < 60Hz Meets full range specifications	-25	1.2 1.6 30	1.3 1.8 85	°C/W °C/W °C/W °C
POWER SUPPLY VOLTAGE CURRENT, Quiescent total CURRENT, Quiescent output stage only		±15 25	±100 30 10	±150 35	V mA mA

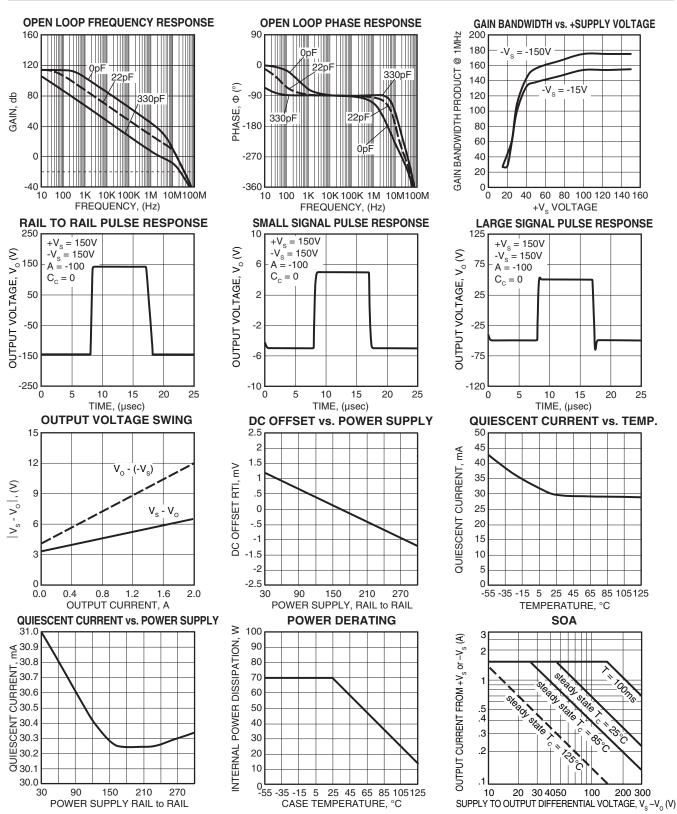
NOTES: 1. Long term operation at the maximum junction temperature will result in reduced product life. Derate power dissipation to achieve high MTTF.

The power supply voltage specified under typical (TYP) applies unless noted as a test condition.
+V_s and -V_s denote the positive and negative supply rail respectively. Total V_s is measured from +V_s to -V_s.
Rating applies if the output current alternates between both output transistors at a rate faster than 60Hz.

CAUTION

The internal substrate contains beryllia (BeO). Do not break the seal. If accidentally broken, do not crush, machine, or subject to temperatures in excess of 850°C to avoid generating toxic fumes.







GENERAL

Please read Application Note 1 "General Operating Considerations" which covers stability, supplies, heat sinking, mounting, current limit, SOA interpretation, and specification interpretation. Visit www.apexanalog.com for design tools that help automate tasks such as calculations for stability, internal power dissipation, current limit, heat sink selection, Apex Microtechnology's Application Notes library, Technical Seminar Workbook, and Evaluation Kits.

SPECIAL PRECAUTIONS

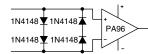
The PA96 operates with up 300V rail to rail voltage, and delivers amperes of current. Precautions should be taken for the safety of the user and the amplifier.

Although the non-operating common mode input range is rail to rail, the differential input voltage must not exceed ±15 V.

Therefore; if the feedback ratio is less than 10, even if caused by disconnecting a signal source, typical power turn on transients can destroy the amplifier.

Similarly in a voltage follower application a large differential transient can be generated if the slew rate of the input is greater than that of the voltage follower.

Therefore it is prudent to clamp the input with series back to back diodes as shown below.



If experimentally optimizing the compensation capacitor, turn off the supplies and let them bleed to low voltage before installing each new value. Otherwise internal current pulses of up to 3 amps can be induced. Also, do you want your fingers around 300V?

Essentially the full rail to rail power supply voltage may be applied to the compensation capacitor. A 400V COG or Mica capacitor is recommended.

POWER BANDWIDTH

The power bandwidth is $1/(\pi x$ the negative edge slew time). The slew time is determined by the compensation capacitor, load, and internal device capacitance; it is independent of closed loop gain. The uncompensated power bandwidth is typically 100kHz for a 250Vp-p output signal into 100 Ω . It typically increases to above 300KHz with no load.

COMPENSATION TABLE

The following table tabulates recommended compensation capacitor values vs. gain. These values will typically result in less than 2% overshoot and a -3db small signal bandwidth of greater than 1MHz, except under operating conditions where uncompensated gain bandwidth is too low to support a 1MHz bandwidth. (See gain bandwidth vs. Plus power supply curves). Note that other factors such as capacitance in parallel with the feedback resistor may reduce circuit bandwidth from that determined from the gain bandwidth curve.

Cc	Inverting Gain		
	From	То	
150pf	1	2	
51pf	2	5	
33pf	5	10	
22pf	10	20	
10pf	20	50	
5pf	50	100	
None	100	up	
-	Non-Inverting Gain		
Cc	Non-Inv	verting Gain	
Сс	Non-In From	erting Gain To	
Cc 330 pf		0	
	From	То	
330 pf	From 1	To 2	
330 pf 150pf	From 1 2	To 2 3	
330 pf 150pf 51pf	From 1 2 3	To 2 3 6	
330 pf 150pf 51pf 33pf	From 1 2 3 6	To 2 3 6 10	
330 pf 150pf 51pf 33pf 22pf	From 1 2 3 6 10	To 2 3 6 10 20	

CURRENT LIMIT

For proper operation the current limit resistor, Rcl, must be connected as shown in the external connections diagram. The minimum value is 0.2Ω , with a maximum practical value of 100Ω . For optimum reliability the resistor should be set as high as possible. The value is calculated as $I_{L} = 0.68V/Rcl$. Note that the 0.68V is reduced by 2mV every °C rise in temperature.

Also note that the current limit can be set such that the SOA is exceeded on a continuous basis. As an example if the current limit was set at 1.5A and the supply was at 150V, a short to ground would produce 225 watts internal dissipation, greatly exceeding the 83 watt steady state SOA rating.

Under some conditions of load and compensation the amplifier may oscillate at a low level when current limit is active, even though the amplifier is stable otherwise. The current will be limited to the programmed value in this situation. To minimize such occurrences, use a non-reactive resistor to program current limit.



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