14-stage ripple-carry binary counter/divider and oscillatorRev. 7 — 16 November 2011Product data sheet

### 1. General description

The HEF4060B is a 14-stage ripple-carry binary counter/divider and oscillator with three oscillator terminals (RS, REXT and CEXT), ten buffered outputs (Q3 to Q9 and Q11 to Q13) and an overriding asynchronous master reset input (MR).

The oscillator configuration allows design of either RC or crystal oscillator circuits. The oscillator may be replaced by an external clock signal at input RS. The clock input's Schmitt-trigger action makes it highly tolerant to slower clock rise and fall times. The counter advances on the negative-going transition of RS. A HIGH level on MR resets the counter (Q3 to Q9 and Q11 to Q13 = LOW), independent of other input conditions.

It operates over a recommended  $V_{DD}$  power supply range of 3 V to 15 V referenced to  $V_{SS}$  (usually ground). Unused inputs must be connected to  $V_{DD}$ ,  $V_{SS}$ , or another input.

### 2. Features and benefits

- Tolerant of slow clock rise and fall times
- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- Inputs and outputs are protected against electrostatic effects
- Specified from –40 °C to +85 °C
- Complies with JEDEC standard JESD 13-B

## 3. Ordering information

	Table 1.	Orderina	information
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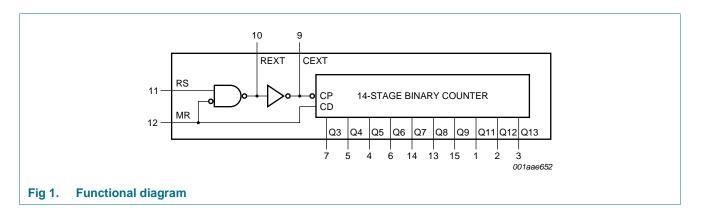
All types operate from -40 °C to +85 °C.

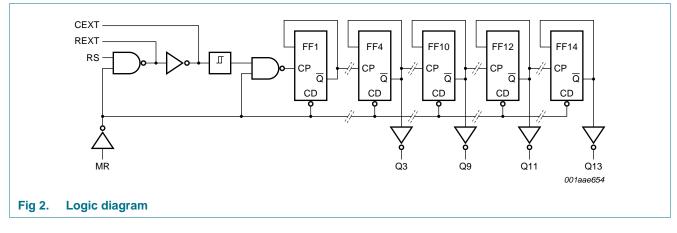
Type number	Package	Package								
	Name	Description	Version							
HEF4060BP	DIP16	plastic dual in-line package; 16 leads (300 mil)	SOT38-4							
HEF4060BT	SO16	plastic small outline package; 16 leads; body width 3.9 mm	SOT109-1							



#### 14-stage ripple-carry binary counter/divider and oscillator

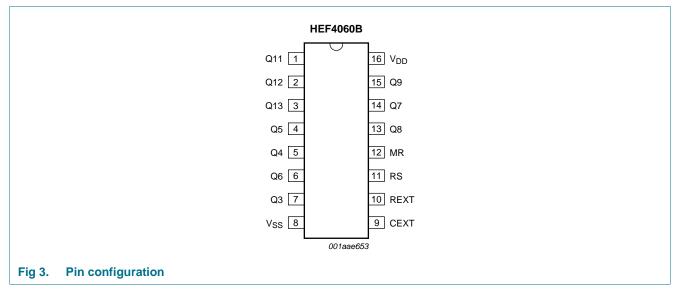
## 4. Functional diagram





## 5. Pinning information





### 5.2 Pin description

Table 2. Pin	description	
Symbol	Pin	Description
Q11 to Q13	1, 2, 3	counter output
Q3 to Q9	7, 5, 4, 6, 14, 13, 15	counter output
V <sub>SS</sub>	8	ground supply voltage
CEXT	9	external capacitor connection
REXT	10	oscillator pin
RS	11	clock input/oscillator pin
MR	12	master reset
V <sub>DD</sub>	16	supply voltage

## 6. Functional description

Table 3.	Function table <sup>[1]</sup>		
Input			Output
RS		MR	Q3 to Q9 and Q11 to Q13
$\uparrow$		L	no change
$\downarrow$		L	count
Х		Н	L

[1] H = HIGH voltage level; L = LOW voltage level;  $\uparrow = LOW$ -to-HIGH clock transition;  $\downarrow HIGH$ -to-LOW clock transition.

## 7. Limiting values

#### Table 4.Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit
V <sub>DD</sub>	supply voltage		-0.5	+18	V
I <sub>IK</sub>	input clamping current	$V_{\rm I} < -0.5$ V or $V_{\rm I} > V_{\rm DD}$ + 0.5 V	-	±10	mA
VI	input voltage		-0.5	V <sub>DD</sub> + 0.5	V
I <sub>OK</sub>	output clamping current	$V_{\rm O}$ < –0.5 V or $V_{\rm O}$ > $V_{\rm DD}$ + 0.5 V	-	±10	mA
I <sub>I/O</sub>	input/output current		-	±10	mA
I <sub>DD</sub>	supply current		-	50	mA
T <sub>stg</sub>	storage temperature		-65	+150	°C
T <sub>amb</sub>	ambient temperature		-40	+85	°C
P <sub>tot</sub>	total power dissipation	T <sub>amb</sub> −40 °C to +85 °C			
		DIP16 package	<u>[1]</u> -	750	mW
		SO16 package	[2] _	500	mW
Р	power dissipation	per output	-	100	mW

[1] For DIP16 package:  $P_{tot}$  derates linearly with 12 mW/K above 70 °C.

[2] For SO16 package: P<sub>tot</sub> derates linearly with 8 mW/K above 70 °C.

## 8. Recommended operating conditions

	Recommended operating con					
Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V <sub>DD</sub>	supply voltage		3	-	15	V
VI	input voltage		0	-	$V_{DD}$	V
T <sub>amb</sub>	ambient temperature	in free air	-40	-	+85	°C
Δt/ΔV	input transition rise and fall	input MR				
	rate	$V_{DD} = 5 V$	-	-	3.75	μs/V
		V <sub>DD</sub> = 10 V	-	-	0.5	μs/V
		V <sub>DD</sub> = 15 V	-	-	0.08	μs/V

## 9. Static characteristics

#### Table 6. Static characteristics

 $V_{SS} = 0$  V;  $V_{I} = V_{SS}$  or  $V_{DD}$  unless otherwise specified.

Symbol	Parameter	Conditions	V <sub>DD</sub>	T <sub>amb</sub> =	–40 °C	T <sub>amb</sub> =	25 °C	T <sub>amb</sub> =	85 °C	Unit
				Min	Max	Min	Max	Min	Max	
V <sub>IH</sub>	HIGH-level	I <sub>O</sub>   < 1 μA	5 V	3.5	-	3.5	-	3.5	-	V
	input voltage		10 V	7.0	-	7.0	-	7.0	-	V
			15 V	11.0	-	11.0	-	11.0	-	V
V <sub>IL</sub>	LOW-level	$ I_0  < 1 \ \mu A$	5 V	-	1.5	-	1.5	-	1.5	V
	input voltage		10 V	-	3.0	-	3.0	-	3.0	V
			15 V	-	4.0	-	4.0	-	4.0	V
V <sub>OH</sub>	HIGH-level	I <sub>O</sub>   < 1 μA	5 V	4.95	-	4.95	-	4.95	-	V
	output voltage		10 V	9.95	-	9.95	-	9.95	-	V
			15 V	14.95	-	14.95	-	14.95	-	V
V <sub>OL</sub> LOW-level output voltage		I <sub>O</sub>   < 1 μA	5 V	-	0.05	-	0.05	-	0.05	V
	output voltage		10 V	-	0.05	-	0.05	-	0.05	V
			15 V	-	0.05	-	0.05	-	0.05	V
I <sub>OH</sub>	HIGH-level	$V_{O} = 2.5 V$	5 V	-	-1.7	-	-1.4	-	-1.1	mA
	output current	$V_{O} = 4.6 V$	5 V	-	-0.52	-	-0.44	-	-0.36	mA
		$V_{O} = 9.5 V$	10 V	-	-1.3	-	-1.1	-	-0.9	mA
		V <sub>O</sub> = 13.5 V	15 V	-	-3.6	-	-3.0	-	-2.4	mA
I <sub>OL</sub>	LOW-level	$V_{O} = 0.4 V$	5 V	0.52	-	0.44	-	0.36	-	mA
	output current	$V_{O} = 0.5 V$	10 V	1.3	-	1.1	-	0.9	-	mA
		$V_{O} = 1.5 V$	15 V	3.6	-	3.0	-	2.4	-	mA
I <sub>I</sub>	input leakage current		15 V	-	±0.3	-	±0.3	-	±1.0	μΑ
I <sub>DD</sub>	supply current	I <sub>O</sub> = 0 A	5 V	-	20	-	20	-	150	μΑ
			10 V	-	40	-	40	-	300	μΑ
			15 V	-	80	-	80	-	600	μΑ
CI	input capacitance		-	-	-	-	7.5	-	-	pF

## **10.** Dynamic characteristics

#### Table 7. Dynamic characteristics

 $T_{amb} = 25 \text{ °C}; V_{SS} = 0 \text{ V}; C_L = 50 \text{ pF}; t_r = t_f \le 20 \text{ ns}; \text{ unless otherwise specified.}$ 

Symbol	Parameter	Conditions	$V_{DD}$		Extrapolation formula <sup>[1]</sup>	Min	Тур	Max	Uni	
pd	propagation delay	$RS \rightarrow Q3;$	5 V	[2]	183 ns + (0.55 ns/pF) C <sub>L</sub>	-	210	420	ns	
		see Figure 4	10 V		69 ns + (0.23 ns/pF) C <sub>L</sub>	-	80	160	ns	
			15 V		42 ns + (0.16 ns/pF) C <sub>L</sub>	-	50	100	ns	
		$Qn \rightarrow Qn + 1;$	5 V		-	-	25	50	ns	
		see Figure 4	10 V		-	-	10	20	ns	
			15 V		-	-	6	12	ns	
		$MR\toQn;$	5 V		73 ns + (0.55 ns/pF) C <sub>L</sub>	-	100	200	ns	
		HIGH to LOW	10 V		29 ns + (0.23 ns/pF) C <sub>L</sub>	-	40	80	ns	
		see Figure 4	15 V		22 ns + (0.16 ns/pF) C <sub>L</sub>	-	30	60	ns	
tt	transition time		5 V	[3]	10 ns + (1.00 ns/pF) C <sub>L</sub>	-	60	120	ns	
			10 V		9 ns + (0.42 ns/pF) C <sub>L</sub>	-	30	60	ns	
			15 V		6 ns + (0.28 ns/pF) C <sub>L</sub>	-	20	40	ns	
tw	pulse width	ulse width minimum width; RS HIGH;	5 V			120	60	-	ns	
			10 V			50	25	-	ns	
		see <u>Figure 4</u> minimum width MR HIGH;	15 V			30	15	-	ns	
			minimum width;	5 V			50	25	-	ns
				10 V			30	15	-	ns
		see <u>Figure 4</u>	15 V			20	10	-	ns	
t <sub>rec</sub>	recovery time	input MR;	5 V			160	80	-	ns	
		see Figure 4	10 V			80	40	-	ns	
			15 V			60	30	-	ns	
max	maximum frequency	input RS;	5 V			4	8	-	MH	
		see Figure 4	10 V			10	20	-	MH	
			15 V			15	30	-	MH	

[1] The typical values of the propagation delay and transition times are calculated from the extrapolation formulas shown (C<sub>L</sub> in pF).

[2]  $t_{pd}$  is the same as  $t_{PHL}$  and  $t_{PLH}$ .

[3]  $t_t$  is the same as  $t_{THL}$  and  $t_{TLH}$ .

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#### Table 8. **Power dissipation**

Dynamic power dissipation $P_D$ and total	I power dissipation $P_{tot}$ can be calculated from the formula	as shown. T <sub>amb</sub> = 25 ℃.

Symbol	Parameter	Conditions	$V_{DD}$	Typical formula for $P_D$ and $P_{tot}$ ( $\mu W)^{[1]}$		
PD	P <sub>D</sub> dynamic power per device		5 V	$P_{D} = 700 \times f_{i} + \Sigma (f_{o} \times C_{L}) \times V_{DD}^{2}$		
	dissipation				10 V	$P_{D} = 3300 \times f_{i} + \Sigma (f_{o} \times C_{L}) \times V_{DD}^{2}$
			15 V	$P_{D} = 8900 \times f_{i} + \Sigma (f_{o} \times C_{L}) \times V_{DD}^{2}$		
P <sub>tot</sub>	P <sub>tot</sub> total power when using dissipation the on-chip oscillator	0	5 V	$P_{tot} = 700 \times f_{osc} + \Sigma(f_o \times C_L) \times V_{DD}^2 + 2 \times C_t \times V_{DD}^2 \times f_{osc} + 690 \times V_{DD}$		
			10 V	$P_{tot} = 3300 \times f_{osc} + \Sigma(f_o \times C_L) \times V_{DD}^2 + 2 \times C_t \times V_{DD}^2 \times f_{osc} + 6900 \times V_{DD}$		
		1	15 V	$P_{tot} = 8900 \times f_{osc} + \Sigma (f_o \times C_L) \times V_{DD}^2 + 2 \times C_t \times V_{DD}^2 \times f_{osc} + 22000 \times V_{DD}$		

[1] Where:

 $f_i$  = input frequency in MHz;  $f_o$  = output frequency in MHz;

 $C_L$  = output load capacitance in pF;

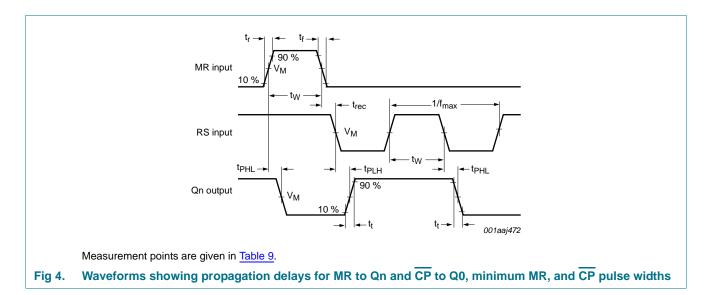
V<sub>DD</sub> = supply voltage in V;

 $\Sigma(f_o \times C_L)$  = sum of the outputs;

 $C_t$  = timing capacitance (pF);

 $f_{osc}$  = oscillator frequency (MHz).

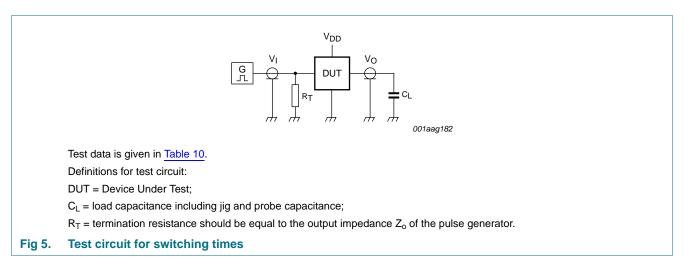
### 11. Waveforms



#### Table 9. **Measurement points**

Supply voltage	Input	Output
V <sub>DD</sub>	V <sub>M</sub>	V <sub>M</sub>
5 V to 15 V	0.5V <sub>DD</sub>	0.5V <sub>DD</sub>

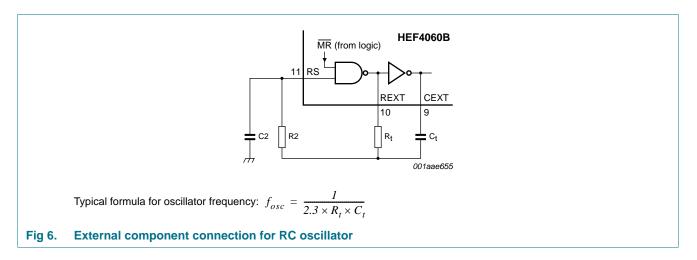
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#### Table 10. Measurement point and test data

Supply voltage	Input	Load	
V <sub>DD</sub>	VI	t <sub>r</sub> , t <sub>f</sub>	CL
5 V to 15 V	V <sub>SS</sub> or V <sub>DD</sub>	$\leq$ 20 ns	50 pF

## 12. RC oscillator



### 12.1 Timing component limitations

The oscillator frequency is mainly determined by  $R_t \times C_t$ , provided  $R_t << R2$  and  $R2 \times C2 << R_t \times C_t$ . The influence of the forward voltage across the input protection diodes on the frequency is minimized by R2. The stray capacitance C2 should be kept as small as possible. In consideration of accuracy,  $C_t$  must be larger than the inherent stray capacitance.  $R_t$  must be larger than the LOCMOS (Local Oxidation Complementary Metal-Oxide Semiconductor) 'ON' resistance in series with it, which typically is 500  $\Omega$  at  $V_{DD} = 5 \text{ V}$ , 300  $\Omega$  at  $V_{DD} = 10 \text{ V}$  and 200  $\Omega$  at  $V_{DD} = 15 \text{ V}$ .

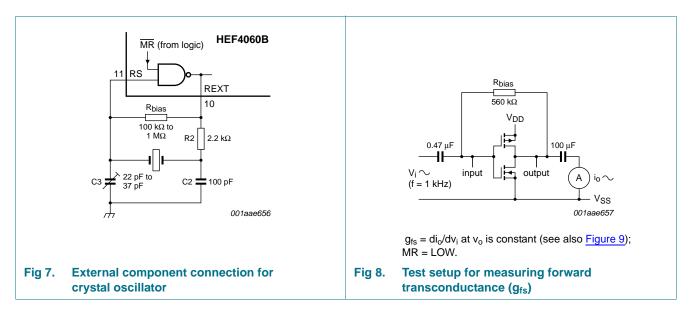
The recommended values for these components to maintain agreement with the typical oscillation formula are:

 $C_t \ge 100 \text{ pF}$ , up to any practical value,

10 k $\Omega \le R_t \le 1$  M $\Omega$ .

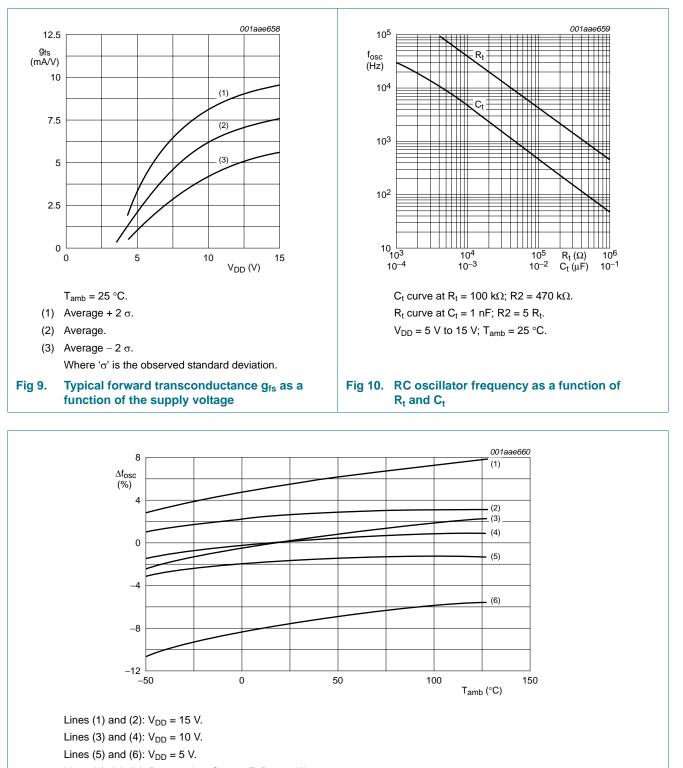
### 12.2 Typical crystal oscillator circuit

In <u>Figure 7</u>, R2 is the power limiting resistor. For starting and maintaining oscillation a minimum transconductance is necessary.



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Lines (1), (3), (6):  $R_t = 100 \text{ k}\Omega$ ;  $C_t = 1 \text{ nF}$ ; R2 = 0 W. Lines (2), (4), (5):  $R_t = 100 \text{ k}\Omega$ ;  $C_t = 1 \text{ nF}$ ;  $R2 = 300 \text{ k}\Omega$ .

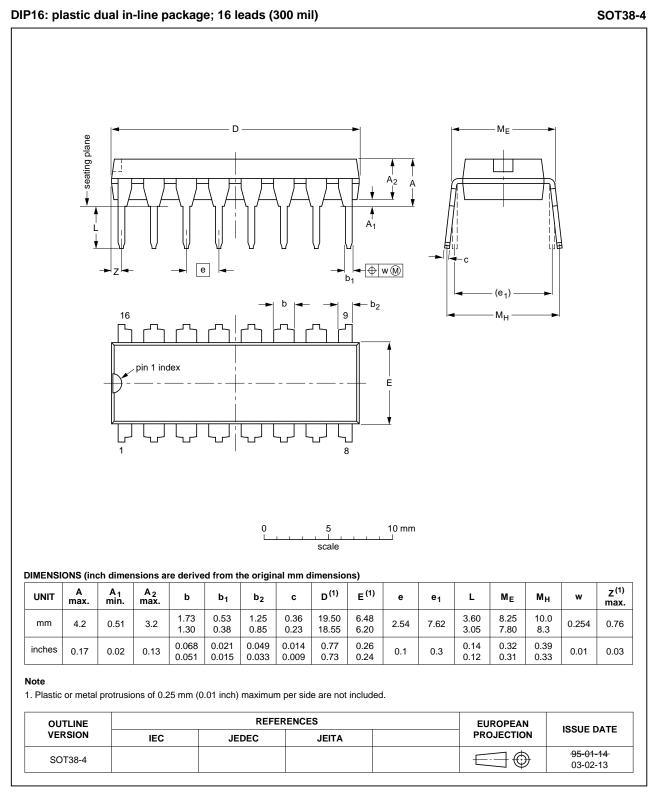
Referenced at:  $f_{osc}$  at  $T_{amb}$  = 25 °C and  $V_{DD}$  = 10 V.



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## 13. Package outline



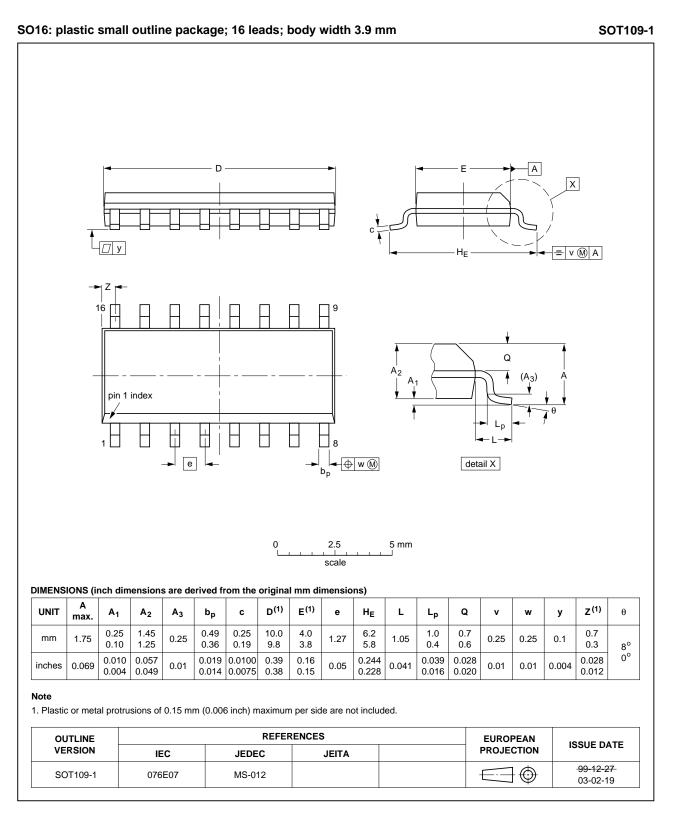
#### Fig 12. Package outline SOT38-4 (DIP16)

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#### Fig 13. Package outline SOT109-1 (SO16)

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## 14. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes	
HEF4060B v.7	20111116	Product data sheet	-	HEF4060B v.6	
Modifications:	<ul> <li>Legal pages updated.</li> </ul>				
	<ul> <li>Changes in "General description" and "Features and benefits".</li> </ul>				
	<ul> <li>Section "Ap</li> </ul>	plications" removed.			
HEF4060B v.6	20110511	Product data sheet	-	HEF4060B v.5	
HEF4060B v.5	20091127	Product data sheet	-	HEF4060B v.4	
HEF4060B v.4	20090817	Product data sheet	-	HEF4060B_CNV v.3	
HEF4060B_CNV v.3	19950101	Product specification	-	HEF4060B_CNV v.2	
HEF4060B CNV v.2	19950101	Product specification	-	-	

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#### 15.1 Data sheet status

Document status[1][2]	Product status <sup>[3]</sup>	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

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