

SPP (Japan) originated

Product Specification

for

CRS03-04-PS Rev 6

(Commercial Rate Sensor) & CRS03-04R-PS CRS03-04S-PS



友精密工業株式 <u>EMS事 業 開</u> 2006. 8.	発室					SST-	-0016 rev.6	
SSS UP					DOC. NUMB	ER	REV.	
	PROD SILICO	 PRODUCT SPECIFICATION FOR SINGLE AXIS SILICON VIBRATING STRUCTURE GYRO <i>CRS03-04/CRS03-04R</i> <i>CRS03-04S</i>				SST – 0016		
	Limite from whon produ Contr [Cust the G the s whict SSSJ settle SSSJ [Cust Cust	and/or Purchaser [Cu ed and its affiliates, inc and against any and never asserted and reg tot supplied by SSSU act, directly or indirectl omer] for any purpose yro product for training upport or maintenance indemnification will b IL shall provide reasor any such claim withou L is not warranted in a omer] prior to purchas ustion, security, etc.) of	istomer] shall indemnify and hold Silicon luding its members, shareholders, manage all liabilities, claims, demands, actions, c lardless of nature or kind, including withou to [Customer], claims for personal injun y, in whole or in part, attributed to or arisin including but without limitation, installing th g or simulation purposes in relation to a pr e of a product, equipment, or vehicle of a e sought. [Customer] shall have the right table co-operation and information to [Cus ut the prior written consent of SSSJL, whice ing.Applications that require extra reliabilit or any applications which are thought to be ohibited. 禁無斯転載 本書類の日本	ers, directors, office osts or expenses (t limitation and/or pr es (including death g from the use by [re Gyro product on roduct, equipment, any kind. SSSJL sh at its expense to tomer] in order for ch consent may not kisting laws and/or r y and quality possi e beyond the focus	rs, employees, ager including all reason oduct liability claims) and damage to p Customer] of any G a product, equipme or vehicle of any k all promptly notify assume and control Customer] to defen be unreasonably w egulations unless a oly affecting the saf of the product, shou	tts and representa able legal or litiga arising from the u roperty, whether i rro product supplie it, or vehicle of any nd, or using the G Customer] of any the defence of su d the claims. [Cus] thheld. Gyro prodi greed by and betw ety of living things ild be consulted w	tives, harmless tition costs), by se of any Gyro n tort or under d by SSSJL to y kind, or using yro product for such claim for uch claims and tomer] may not uct supplied by een SSSJ and (e.g. transport,	
	6		P2 : Add an alternate ASIC r P2 : Mechanical Description P6 : Fig.3 added	-	04S).	'06.08.01	小山山川 巻口科淵	
	- 5		P2 : Model Number revised (RoHS compliance) P2 : Mechanical Description revised P4 : Fig.1 amended P5 : Fig.2 added			'05.11.14	小 山山 巻南科口	
	- 4		P1 : Notice revised P2 : 4.Performance Current dissipation reviced P4 : Fig.1 amended			'04.04.20	小 山 中 巻 南 科 村 卓	
	3		P4 : Fig.1 amended	'02.10.17	徳 北 坂 中 江 村 本 卓			
	в	SCN-0200	SCN-0200 P1,P2	'01.10.01	RT TK KS KY MT			
	- A	SCN-0150	SCN-0150 All pages	[.] 01.02.05	RT TK KS KY MT			
	REV.	MODIFY No.	REVISED P	AGES	·	DATE	CHECKED	
	1-10 F	on Sensing Fuso-cho, Amaga el +81-6-6489-58	Systems Japan Ltd. Isaki, Hyogo 660-0891 Japan 68 Fax +81-6-6489-5910 sssj@spp.co.jp	DATE 2000.12.28	APPROVED	CHECKED kitamura	PREPARED Yoshioka Sakamoto	

/6)

1. DESCRIPTION/概要

The silicon vibrating structure gyroscope (Si-VSG) is a solid state single axis rate sensor. It is a stand aloneunit and dc output is proportional to the rate of rotation and supply voltage.

The new concept ring-shaped micro-machined resonator shows distinguished resistance against external shocks and vibrations over a wide range of temperature.

本シリコン振動ジャイロは1軸ソリッドステート角速度センサであり角速度と供給電圧に比例した直流電圧を出力する。 マイクロマシニングのリング型振動子により広い温度範囲で外部衝撃や振動に対し優れた耐性を発揮するものである。

2. MODEL NUMBER/製品型名

CRS03 - 04 Con	nector output range200deg/secコネクタ出力タイプ					
CRS03 – 04R Con	nector output range200deg/secコネクタ出力タイプ (RoHS Compliance / RoHS対応品)					
CRS03 – 04S Con	nector output range200deg/secコネクタ出力タイプ (GOA ASIC対応品)					
CRS03 Basic Model –xx Design Num –xxR Design Num	Number 基本製品番号 ber タイプ識別番号 ber タイプ識別番号 (RoHS Compliance / RoHS対応品) ber タイプ識別番号 (GOA ASIC対応品)					

3. MECHANICAL DESCRIPTION/外形

The nominal dimensions are shown in Fig.1,2,3.(Fig2 RoHS compliance, Fig3 GOA ASIC model) 図 1 参照。(図 2 RoHS 対応品、図 3 GOA ASIC 対応品)

4. PERFORMANCE/性能

	Parameter 項目	Min	Тур	Max	Unit 単位	Notes 備考
Absolute Maximum Ratings	Supply voltage 電源	0.00	5.00	6.00	v	
絶対最大定格	Storage temperature 保存温度	- 40		85	deg C	
	Operatable acceleration 使用限界加速度			981.0	m/sec ²	
Operating conditions	Supply voltage 電源電圧	4.75	5.00	5.25	V	
動作環境	Power supply noise 電源ノイズ			15.00	mVrms	0.5 to 100Hz
	Temperature 温度	- 40	23	85	deg C	
	Humidity 湿度	5		95	%RH	Non-condensing 結露無

The following specifications apply for Vdd=5.00V and Temp=23deg C unless otherwise specified. 特に指定無き場合下記はVdd-5.00V、温度23℃を条件とする。

Parameter 項目	Limit 限度	Unit 単位	Notes 備考
Rate range 測定範囲	+/- 200	deg/sec	Reference 参考值
Rate range 測定範囲	+/- 3.491	rad/sec	
Scale Factor 感度	10	mV/(deg/sec) typ.	Reference 参考值
Scalc Factor 感度	11.46	% of Vdd/(rad/sec) typ.	
Initial Scale Factor accuracy 感度初期設定確度	+/- i	% typ.	
Initial Scale Factor accuracy 感度初期設定確度	+/- 3	%	
Scale Factor variation with temp.感度温度変動	+/- 3	% typ.	Op temp. range 動作温度範囲
Scale Factor variation with temp.感度温度変動	+/- 5	%	Op temp. range 動作温度範囲
Scale Factor ratiometric error 感度電源電圧変動誤差	+/- 1	%	Op voltage range動作電圧範囲
Bias ゼロ点	50	% typ. of Vdd	
Bias initial error ゼロ点初期設定誤差	+/- 60	mV	
Bias variation with temp.ゼロ点温度変動	+/- 60	mV	Op temp. range 動作温度範囲
Bias ratiometric error ゼロ点電源電圧変動誤差	+/- 20	mV	Op voltage range動作電圧範囲
Non linearity 非直線性	< 0.5	% of FS typ.	
Non linearity 非直線性	< 3	% of FS	
Quiescent noise 静止ノイズ	< 1	mVrms typ. (3~10Hz)	
Bandwidth 帯域	> 10	Hz	Gain (- 3dB)
Cross axis sensitivity 他軸感度	< 5	%	
Power up time 起動時間	< 0.5	see	From $Vdd = 4.50V$
Current dissipation 電流消費	< 50	mA	170mA when initializing(起動時)
Output Impedance 出力インピーダンス	100	Ω typ.	
Available output current 保証最小出力電流	> 0.5	mA	

5. TYPICAL RATE OUTPUT 出力電圧

$$Vo = \frac{1}{2} \times Vdd + \left(Ra \times SF \times \frac{Vdd}{5}\right) \quad \text{; (Unit:Volt typ.)} \quad \text{if } dV \text{ typ.)}$$

where: Vo: Rateout (V), Vdd: Supply voltage (V), Ra: Applied rate (deg/s), SF: Scale Factor (V/ (deg/s)) ここで:Vo:ジャイ叩出力(V), Vdd:電源電圧(V), Ra:角速度(deg/s), SF:感度(V/(deg/s))

6. RATIOMETRIC ERROR レシオメトリック・エラー(電源電圧による変動の誤差)

6.1 Bias ratiometric error ゼロ点電源電圧変動誤差

Bias ratiometric error are calculated as follows; ゼロ点電源電圧変動誤差は次の式で表される

$$Errb = Vb - \left(Vb_5 \times \frac{Vdd}{5}\right)$$
(V)

where Errb: Bias ratiometric error (V), Vb: Bias at Vdd (V), Vb₅: Bias at 5.00V (V), Vdd: Supply voltage (V) ここで Errb: た い 点 レシオメトリックエラー(V), Vb: Vdd での た い 点 (V), Vb₅: 5.00V時の た い 点 (V), Vdd: 電源電圧(V)

6.2 Scale Factor ratiometric error 感度電源電圧変動誤差

Scale Factor ratiometric error are calculated as follows; 感度電源電圧変動誤差は次の式で表される

$$Errs = \left[SF - \left(SF_5 \times \left(\frac{Vdd}{5}\right)\right)\right] \times \frac{100}{SF} \quad (\%)$$

where

Errs: Scale Factor ratiometric error (%), SF: Scale Factor at Vdd (V/ (deg/s))

SF₅: Scale Factor at 5.00V (V/ (deg/s)), Vdd: Supply voltage (V)

Errs: 感度レシオメトリックエラー(%), SF:Vdd時の感度 (V/(deg/s)) SF5: 5.00V時の感度(V/(deg/s)), Vdd:電源電圧(V)

7. SOLDERING / 半田付け

The product may not be subjected to beyond the maximum storage temperature (e.g. solder reflow chamber) at any time. Hand soldering is recommended.

本製品は何時も最高保存温度以上の環境(たとえば半田リフロー内)に置かれてはならない。 従い手半田が推奨される。

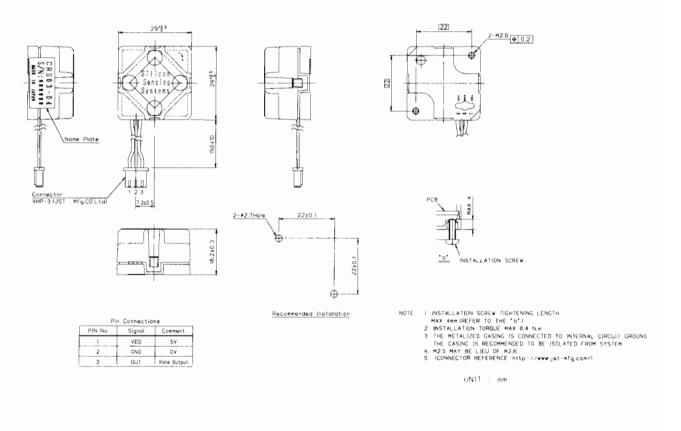


Fig.1 CRS03-04

