

## AM26S02

### *Schottky Dual Retriggerable, Resettable Monostable Multivibrator*

The AM26S02 is a dual DC level sensitive, retriggerable, resettable monostable multivibrator built using advanced Schottky technology. The output pulse duration and accuracy depend on the external timing components of each multivibrator. The AM26S02 features PNP inputs to reduce the input loading.

Provision is made on each multivibrator circuit for triggering the PNP inputs on either the rising or falling edge of an input signal by including an inverting and non-inverting trigger input. These PNP inputs are DC coupled making triggering independent of the input rise or fall time. Each time the monostable trigger input is activated from the OR trigger gate, full pulse length triggering occurs independent of the present state of the monostable.

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### **Rochester Electronics Manufactured Components**

Rochester branded components are manufactured using either die/wafers purchased from the original suppliers or Rochester wafers recreated from the original IP. All recreations are done with the approval of the OCM.

Parts are tested using original factory test programs or Rochester developed test solutions to guarantee product meets or exceeds the OCM data sheet.

### **Quality Overview**

- ISO-9001
- AS9120 certification
- Qualified Manufacturers List (QML) MIL-PRF-38535
  - Class Q Military
  - Class V Space Level
- Qualified Suppliers List of Distributors (QSLD)
  - Rochester is a critical supplier to DLA and meets all industry and DLA standards.

Rochester Electronics, LLC is committed to supplying products that satisfy customer expectations for quality and are equal to those originally supplied by industry manufacturers.

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*The original manufacturer's datasheet accompanying this document reflects the performance and specifications of the Rochester manufactured version of this device. Rochester Electronics guarantees the performance of its semiconductor products to the original OEM specifications. 'Typical' values are for reference purposes only. Certain minimum or maximum ratings may be based on product characterization, design, simulation, or sample testing.*

# Am26S02

Schottky Dual Retriggerable, Resettable Monostable Multivibrator

Am26S02

## DISTINCTIVE CHARACTERISTICS

- Advanced Schottky technology with PNP inputs
- Retriggerable 0% to 100% duty cycle
- 28ns to  $\infty$  output pulse width range
- 100k $\Omega$  maximum timing resistor value
- Am26S02XM typical pulse width change of only 1.0% over  $-55^{\circ}\text{C}$  to  $+125^{\circ}\text{C}$  with  $R_x = 100\text{k}\Omega$
- Am26S02XC typical pulse width change of only 0.4% over  $0^{\circ}\text{C}$  to  $+70^{\circ}\text{C}$  with  $R_x = 100\text{k}\Omega$

## GENERAL DESCRIPTION

The Am26S02 is a dual DC level sensitive, retriggerable, resettable monostable multivibrator built using advanced Schottky technology. The output pulse duration and accuracy depend on the external timing components of each multivibrator. The Am26S02 features PNP inputs to reduce the input loading.

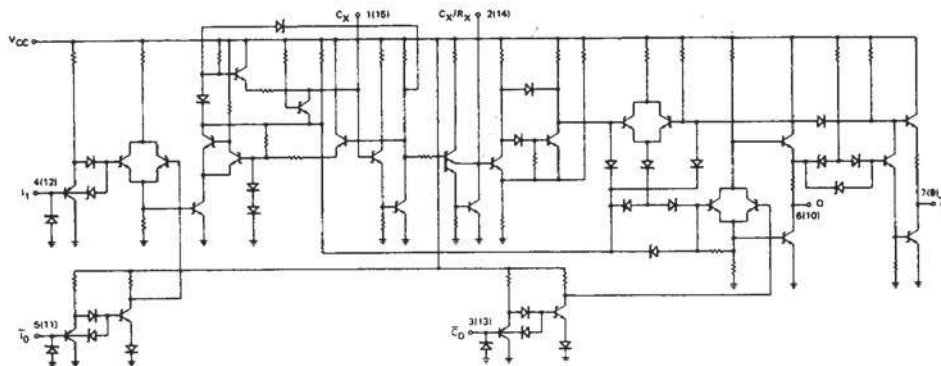
Provision is made on each multivibrator circuit for triggering the PNP inputs on either the rising or falling edge of an input signal by including an inverting and non-inverting trigger input. These PNP inputs are DC coupled making triggering independent of the input rise or fall time. Each time the monostable trigger input is activated from the OR

trigger gate, full pulse length triggering occurs independent of the present state of the monostable.

The direct clear PNP input allows a timing cycle to be terminated at any time during the cycle. A LOW on the clear input forces the Q output LOW regardless of the  $I_0$  or  $\bar{I}_1$  inputs.

The Am26S02XM has a typical pulse width change of only 1.0% over the full military  $-55^{\circ}\text{C}$  to  $+125^{\circ}\text{C}$  temperature range and the Am26S02XC has a typical pulse width change of only 0.4% over the commercial  $0^{\circ}\text{C}$  to  $+70^{\circ}\text{C}$  temperature range with a  $R_x = 100\text{k}\Omega$ .

## SCHEMATIC DIAGRAM (One Monostable Multivibrator Shown)

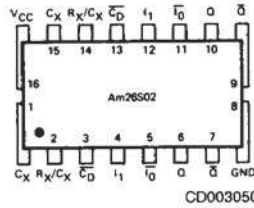


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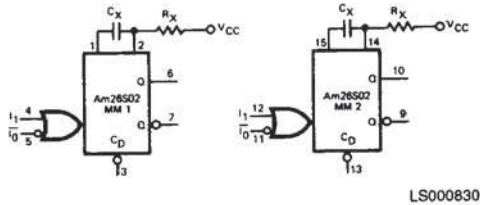
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**CONNECTION DIAGRAM  
Top View**



Note: Pin 1 is marked for orientation

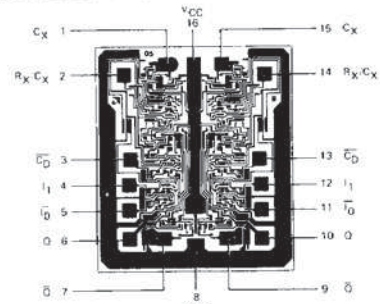
**LOGIC SYMBOL**



LS000830

V<sub>CC</sub> = Pin 16  
GND = Pin 8

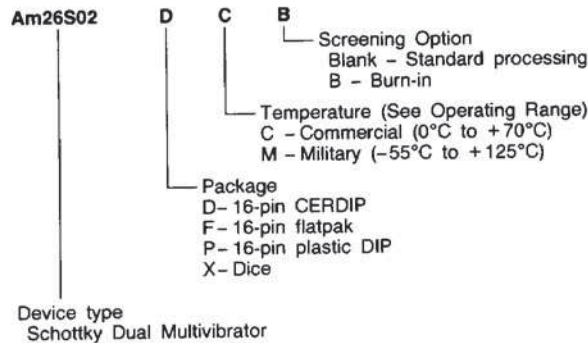
**METALLIZATION AND PAD LAYOUT**



DIE SIZE 0.062" x 0.071"

**ORDERING INFORMATION**

AMD products are available in several packages and operating ranges. The order number is formed by a combination of the following: Device number, speed option (if applicable), package type, operating range and screening option (if desired).



Valid Combinations	
Am26S02	PC DC, DM FM XC, XM

**Valid Combinations**  
Consult the AMD sales office in your area to determine if a device is currently available in the combination you wish.

## PIN DESCRIPTION

Pin No.	Name	I/O	Description
13	$\overline{C}_D$	I	Asynchronous direct CLEAR. A LOW on the clear input resets the monostable regardless of the other inputs.
11	$\overline{I}_0$	I	Active-LOW input. With $I_1$ LOW, a HIGH-to-LOW transition will trigger the monostable.
12	$I_1$	I	Active-HIGH input. With $\overline{I}_0$ HIGH, a LOW-to-HIGH transition will trigger the monostable.
10	Q	O	The TRUE monostable output.
9	$\overline{Q}$	O	The Complement monostable output.

## FUNCTION TABLE

OSC <sub>D</sub>	INPUTS		OUTPUTS	
	$I_1$	$\overline{I}_0$	$\overline{I}_0$	Q
L	X	X	L	H
H	H	X	L	H
H	L	↓	⎓	⎓
H	X	L	L	H
H	↑	H	⎓	⎓

H = HIGH  
 L = LOW  
 ↑ = LOW-to-HIGH Transition  
 ↓ = HIGH-to-LOW Transition  
 ⎓ = LOW-HIGH-LOW Pulse  
 ⎓ = HIGH-LOW-HIGH Pulse  
 X = Don't Care

## LOADING RULES (In Unit Loads)

Input/ Output	Pins No.'s	Input Unit Load	Fan-out	
			Output HIGH	Output LOW
C <sub>X</sub>	Mono 1	1	-	-
R <sub>X</sub> /C <sub>X</sub>		2	-	-
$\overline{C}_D$		3	0.4	-
$I_1$		4	0.4	-
$\overline{I}_0$		5	0.4	-
Q		6	-	40
$\overline{Q}$		7	-	40
GND		8	-	-
$\overline{Q}$	Mono 2	9	-	40
Q		10	-	40
$\overline{I}_0$		11	0.4	-
$I_1$		12	0.4	-
$\overline{C}_D$		13	0.4	-
R <sub>X</sub> /C <sub>X</sub>		14	-	-
C <sub>X</sub>		15	-	-
V <sub>CC</sub>		16	-	-

A Schottky TTL Unit Load is defined as 50μA measured at 2.7V HIGH and -2.0mA measured at 0.5V LOW.

## OPERATION RULES

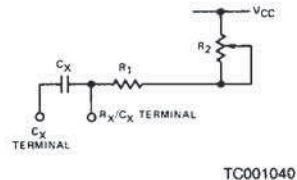
## TIMING

- Timing components C<sub>X</sub> and R<sub>X</sub> values.

## Operating Temperature Range

	0°C to 70°C	-55°C to +125°C
R <sub>X</sub> MIN	5kΩ	5kΩ
R <sub>X</sub> MAX	100kΩ	50kΩ
C <sub>X</sub>	any value	any value

- Remote adjustment of timing.



$$R_1 + R_2 = R_x$$

$$R_1 \geq R_{x\text{MIN}}$$

$$R_2 < R_{x\text{MAX}} - R_1$$

In the above arrangement, R<sub>1</sub> and C<sub>X</sub> should be as close as possible to the device pins to minimize stray capacitance and external noise pickup. The variable resistor R<sub>2</sub> can be located remotely from the device if reasonable care is used.

**OPERATION RULES (Cont.)**

**3. Pulse width change measurements.**

The pulse width  $t_{pwQ}$  is specified and measured with components of better than 0.1% accuracy. If measurements are made with reduced component tolerances, the expected accuracy should be adjusted accordingly. Note that pulse width temperature stability improves as  $R_x$  increases.

**4. Timing for  $C_x \leq 1000$  pF.**

When using capacitor of less than or equal to 1000 pF in value, the output pulse width should be determined from the output pulse width versus external timing capacitance graph.

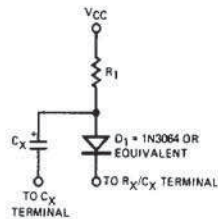
**5. Timing for  $C_x > 1000$  pF.**

For capacitors of greater than 1000 pF in value, the output pulse width,  $t_{pwQ}$ , is determined by:

$$t_{pwQ} = 0.30C_xR_x \left( 1 + \frac{0.11}{R_x} \right)$$

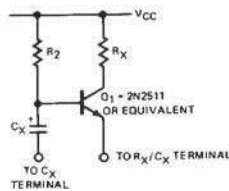
where

$R_x$  is in kilohms  
 $C_x$  is in picofarads  
 $t_{pwQ}$  is in nanoseconds



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$$R_1 \leq 0.6 \times R_x \text{ MAX.}$$



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$$R_2 < 0.7 \times h_{FEQ1} \times R_x$$

**6. Protection of electrolytic timing capacitors.**

If the electrolytic capacitor to be used as  $C_x$  cannot withstand 1.0 volt reverse bias, one of the two circuit techniques shown below should be used to protect the electrolytic capacitor from the reverse voltage. The accuracy of the pulse width may be dependent on the diode (transistor) characteristics.

The output pulse width,  $t_{pwQ}$  for the diode circuit modifies the previous timing equation as follows:

$$t_{pwQ} = 0.26C_xR_x \left( 1 + \frac{0.13}{R_x} \right)$$

The output pulse width for the transistor circuit is:

$$t_{pwQ} = 0.21C_xR_x \left( 1 + \frac{0.16}{R_x} \right)$$

Notice that the transistor circuit allows values of timing resistor  $R_2$  larger than the  $R_x$  MIN.  $< R_x < R_x$ MAX. to obtain longer output pulse widths for a given  $C_x$ .

**TRIGGER AND RETRIGGER**

**1. Triggering.**

The minimum pulse width signal into input  $I_0$  or input  $I_1$  to cause the device to trigger is 20ns. Refer to the truth table for the appropriate input conditions.

**2. Retriggering.**

The retriggered pulse width,  $t_{pwrQ}$ , is the time during which the output is active after the device is retriggered during a timing cycle. It differs from the initial pulse width  $t_{pwQ}$  timing equations as follows:

$$t_{pwrQ} = t_{pwQ} + t_{PLH}$$

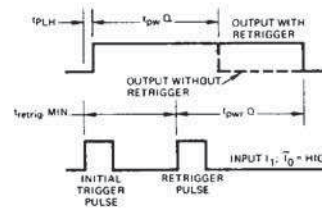
where  $t_{PLH}$  is the propagation delay time from the  $I_0$  or  $I_1$  input to the output. Note that  $t_{PLH}$  is typically 14ns and therefore becomes relatively unimportant as  $t_{pwQ}$  increases.

**3. Rapid retriggering.**

A minimum retriggering time does exist. That is, the device cannot be retriggered until a minimum recovery time has elapsed. The minimum retrigger time is approximately:

$$t_{retrigMIN.} = 0.2C_x$$

$C_x$  is in picofarads  
 $t$  is in nanoseconds



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**CLEAR**

A LOW on the clear inputs terminates the timing cycle. A new trigger cycle cannot be initiated while the clear is LOW. With the clear HIGH, the device is under the command of the  $I_1$  and  $I_0$  inputs.

**ABSOLUTE MAXIMUM RATINGS**

Storage Temperature ..... -65°C to +150°C  
 Ambient Temperature Under Bias ..... -55°C to +125°C  
 Supply Voltage to Ground Potential  
 (Pin 16 to Pin 8) Continuous ..... -0.5V to +7.0V  
 DC Voltage Applied to Outputs For  
 HIGH Output State ..... -0.5V to +V<sub>CC</sub> max  
 DC Input Voltage ..... -0.5V to +5.5V  
 DC Output Current, Into Outputs ..... 30mA  
 DC Input Current ..... -30mA to +5.0mA

Stresses above those listed under ABSOLUTE MAXIMUM RATINGS may cause permanent device failure. Functionality at or above these limits is not implied. Exposure to absolute maximum ratings for extended periods may affect device reliability.

**OPERATING RANGES**

Commercial (C) Devices  
 Temperature ..... 0°C to +70°C  
 Supply Voltage ..... +4.75V to +5.25V  
 Military (M) Devices  
 Temperature ..... -55°C to +125°C  
 Supply Voltage ..... +4.5V to +5.5V  
 Operating ranges define those limits over which the functionality of the device is guaranteed.

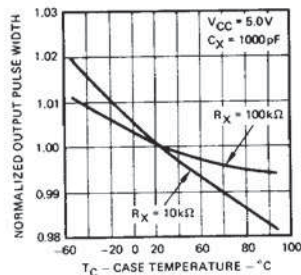
**DC CHARACTERISTICS** over operating range unless otherwise specified

Parameters	Description	Test Conditions (Note 2)	Min	Typ (Note 1)	Max	Units
V <sub>OH</sub>	Output HIGH Voltage	V <sub>CC</sub> = MIN, I <sub>OH</sub> = -2mA V <sub>IN</sub> = V <sub>IH</sub> or V <sub>IL</sub>	2.5	2.8		Volts
V <sub>OL</sub>	Output LOW Voltage	V <sub>CC</sub> = MIN, I <sub>OL</sub> = 20mA V <sub>IN</sub> = V <sub>IH</sub> or V <sub>IL</sub>		0.38	0.5	Volts
V <sub>IH</sub>	Input HIGH Level	Guaranteed input logical HIGH voltage for all inputs	2.0			Volts
V <sub>IL</sub>	Input LOW Level	Guaranteed input logical LOW voltage for all inputs			0.8	Volts
V <sub>I</sub>	Input Clamp Voltage	V <sub>CC</sub> = MIN, I <sub>IN</sub> = -18mA		-0.4	-1.2	Volts
I <sub>IL</sub> (Note 3)	Input LOW Current	V <sub>CC</sub> = MAX, V <sub>IN</sub> = 0.5V		-0.15	-0.4	mA
I <sub>IH</sub> (Note 3)	Input HIGH Current	V <sub>CC</sub> = MAX, V <sub>IN</sub> = 2.7V		0.1	20	μA
I <sub>I</sub>	Input HIGH Current	V <sub>CC</sub> = MAX, V <sub>IN</sub> = 5.5V			1.0	mA
I <sub>SC</sub>	Output Short Circuit Current (Note 4)	V <sub>CC</sub> = MAX, V <sub>OUT</sub> = 1.0V T <sub>A</sub> = 25°C Only	-8	-15	-35	mA
I <sub>CC</sub>	Power Supply Current	V <sub>CC</sub> = 5.0V, I <sub>I</sub> X = 0.33mA (Notes 5 & 6)		48	69	mA

- Notes: 1. Typical limits are at V<sub>CC</sub> = 5.0V, 25°C ambient and maximum loading.  
 2. For conditions shown as MIN, or MAX, use the appropriate value specified under Electrical Characteristics for the applicable device type.  
 3. Actual input currents = Unit Load x Input Load Factor (See Loading Rules).  
 4. Not more than one output should be shorted at a time. Duration of the short circuit test should not exceed one second.  
 5. I<sub>CC</sub> is measured with pin 5 and 11 grounded and I<sub>I</sub>X applied to pins 2 and 14.  
 6. I<sub>I</sub>X is the current into the R<sub>X</sub>C<sub>X</sub> node to simulate R<sub>X</sub>.

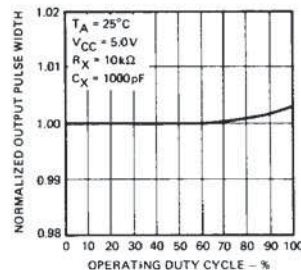
**TYPICAL PERFORMANCE CURVES**

**Typical Normalized Output Pulse Width Versus Case Temperature**



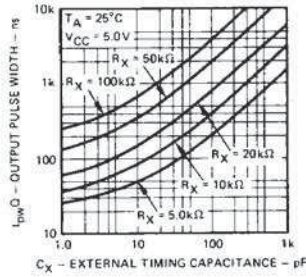
OP001280

**Normalized Output Pulse Width Versus Operating Duty Cycle**



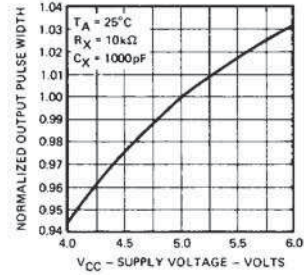
OP001320

Output Pulse Width Versus External Timing Capacitance



OP001260

Typical Normalized Output Pulse Width Versus Supply Voltage



OP001270

SWITCHING CHARACTERISTICS (TA = +25°C, VCC = 5.0V)

Parameters	Description	Test Conditions	Min	Typ	Max	Units	
tPLH	I <sub>0</sub> to Q	VCC = 5.0 V, RL = 280 Ω, CL = 15 pF, RX = 5 kΩ, CX = 0 pF		13	20	ns	
tPHL	I <sub>0</sub> to Q̄			15	23	ns	
tPLH	I <sub>1</sub> to Q			12	20	ns	
tPHL	I <sub>1</sub> to Q̄			12	20	ns	
tPLH	Clear to Q̄			21		ns	
tPHL	Clear to Q			9	13	ns	
tpw	Pulse Width		I <sub>0</sub> HIGH or I <sub>1</sub> LOW	20	10		ns
			I <sub>0</sub> LOW to I <sub>1</sub> HIGH	16	7		ns
			Clear LOW	24	16		ns
ts	Clear Recovery (inactive) to Trigger			-10	-22		ns
tPWQ (Min)	Minimum Pulse Width Q Output	VCC = 5.0 V, RX = 5.0 kΩ, CX = 0 pF RL = 1.0 kΩ	27	33	39	ns	
tPWQ	Pulse Width Q Output	VCC = 5.0 V, RL = 280 Ω, CL = 15 pF RX = 10 kΩ, CX = 1000 pF (CK05 Type)	3.23	3.42	3.61	μs	
RX	Timing Resistor	0°C to 70°C	5		100	kΩ	
		-55°C to +125°C	5		50		