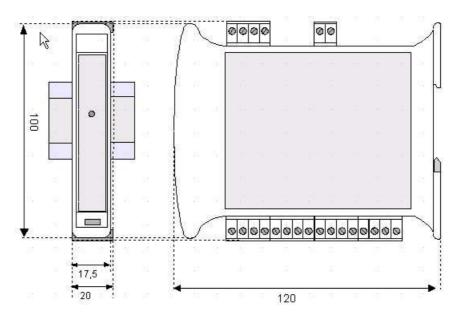
# *i*OS - Remote I/O system

iOS/M04IPX-D1 4 Input Channel (RTD)

## SPECIFICATIONS

	04IPX-D1			04IPX-D1
Number of Channels	4		Conversion Time (PLC Update Rate)	Determined by Configuration
Input Ranges	RTD Pt-100, Ni-100, Pt-1000, & Ni-1000, 0-2000hm, 0-5000hm	-	Terminal Type	Screw Type, Removable
Resolution	0.1C or 0.10hm	-	Storage Temp.	-40° to 85° Celsius
RTD Excitation	250microomp turical		Operating Temp.	-10° to 60° Celsius
Current	350microamp, typical	-	Relative Humidity	5 to 95% Non-condensing
Accuracy	+/-0.1% F.S.		Dimensions WxHxD	17.5mm x 100mm x 120mm 0.69" x 3.94" x 4.72"
External Power Supply Voltage	10-30Vdc	-	Weight	150g (6 oz.)
Required Power (Steady State)	30mA @ 24Vdc, typical		Communications	Modbus/RTU (binary) RS-485 half duplex
Required Power (Inrush)	Negligible	-	Default Comms. Parameters	38400 baud, N, 8, 1, no h/s Default Modbus ID 1
Isolation	2000Vac for 60 seconds (Input/Power & Input/Comms)		Supported Modbus Commands	1,2,3,4,5,6,8,15,16

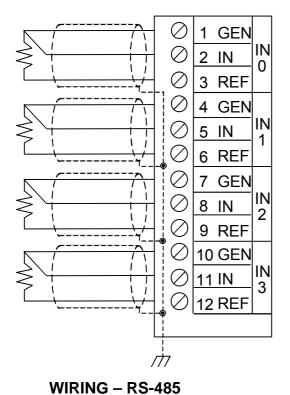


Note: Number of I/O terminal connections change with model type





## WIRING - I/O



I/O	)	RS-485
Pin #	04IP	X-D1
1	GEN	
2	IN	IN 0
3	REF	
4	GEN	
5	IN	IN 1
6	REF	
7	GEN	
8	IN	IN 2
9	REF	
10	GEN	

IN

REF

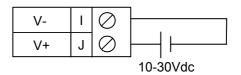
IN 3

 $\begin{array}{c|c} D- & A & \bigcirc \\ \hline D+ & B & \bigcirc \\ \hline GND & C & \bigcirc \\ \hline INIT & D & \bigcirc \\ \end{array}$ 

WIRING -	DC IN
----------	-------

11

12



#### Notes:

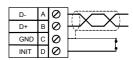
Both ends of the RS-485 network should be terminated with a  $100\Omega$ ,  $\frac{1}{4}W$ , 1% resistor.  $i^{3}$  controllers feature dipswitches or jumpers, which enable appropriate termination if the  $i^{3}$  is located on a network end.

#### Init default setup:

- 1. Install jumper between INIT and GND terminals of the RS-485 port.
- 2. Apply power to *i*OS unit.
- 3. Read parameter words to see current parameters.
- 4. Write changes if necessary.

#### The Init default RS485 settings are:

Modbus ID = 1 Baud rate = 9600 Parity = None Stop Bits = 1



# **CONFIGURATION DATA**

iOS configuration settings are mapped into Modbus register space. This configuration data may be modified with any Modbus/RTU Master device. For convenience, IMO Precision Controls have developed a variety of application files, which allow an  $i^3$  Integrated Controller to act as the iOS configurator. Initial configuration of the iOS module should be done on an individual basis, since all modules are delivered with a factory default of Modbus ID 1. Once each module on the network has its own unique Modbus ID, further configuration adjustments can be made with the entire network powered.

All configuration parameters listed below (except 40012 Channel Enable) are stored in EPROM and for this reason they should not be constantly rewritten.

Configuration Parameters – Registers 40001 through 40013					
Modbus Register	Description	Min	Max	Default	
40001-40005	Reserved				
40006	Communications Parameters	See Table 38.4kbaud, N, 8, 1, R Mode		38.4kbaud, N, 8, 1, RTU Mode	
40007	Modbus ID	1	255	1	
40008	Rx/Tx Delay (in 2mS steps)	0	255	0mS	
40009	Watchdog Timer (in 0.5s steps)	0	255	10 (5s)	
40010	Modbus Coil Data	Not	Configura	ation Data – See I/O Data	
40011	Input Type	See Table 23 (RTD Pt-100 Type)		23 (RTD Pt-100 Type)	
40012	Channel Enable			255 (All channels enabled)	
40013	Reserved			· · · · · · · · · · · · · · · · · · ·	

	Register 40006 (Communications Parameters) Bit Definition						
Bits 7-15	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Unused	Mode	Pa	rity	Data Bits		Baud Rate	
			Meaning		Value	Mea	ning
	0 = ASCII Mode	0	Mark	0 = 7 Data Bits	0	1200	baud
		1	Even		1	2400	baud
	1 = RTU	2	Odd	1 = 8 Data	2	4800	baud
	Mode	3	Space	Bits	3	9600	baud
				DIIS	4	19200	baud
					5-7	38400	baud

Register 40011 (Input Type) Value Definition				
Value	Input Type			
7	0-2000ohm Resistance			
8	0-500ohm Resistance			
23	RTD Pt-100 Type			
24	RTD Ni-100 Type			
25 RTD Pt-1000 Type				
26 RTD Ni-1000 Type				

Register 40012 (Channel Enable) Bit Definition						
Bit 4-15 Bit 3 Bit 2 Bit 1 Bit 0						
	Input 3	Input 2	Input 1	Input 0		
Unused	0 = Disable Input					
		1 = Enal	ble Input			

# **INPUT / OUTPUT DATA**

*i*OS Analog I/O utilizes both Modbus Registers (40001-40030) and Coils (1-11). It is possible to access all data using Registers only - Coils can be accessed through Register 40010.

I/O Register Data (Registers 40014-40022)						
Modbus						
Register	Description	Access	Minimum	Maximum	Units	
40010	Mirror of Coil Data	Read/Write	n/a	n/a	n/a	
40014	Cold Junction	Bood only	-1000	6000	0.01 degrees C	
40014	Temperature	Read-only	-1000	0000	0.01 degrees C	
40015	Input 0	Read-only				
40016	Input 1	Read-only				
40017	Input 2	Read-only	Denende	Denende		
40018	Input 3	Read-only	Depends	Depends	0.1C or 0.1	
40019	Input 4	Read-only	on Input Type	on Input	ohm	
40020	Input 5	Read-only	туре	Туре		
40021	Input 6	Read-only	1			
40022	Input 7	Read-only	1			

The following tables list all Modbus I/O data available.

Modbus Coil	Description	Access	Watchdog Event & Power-up Event Operation
00001	Open Detect Input 0	Read/Write	If Coil 9 (Watchdog Enabled) is set,
00002	Open Detect Input 1	Read/Write	Coil 10 (Watchdog Event) will set if the
00003	Open Detect Input 2	Read/Write	Watchdog Timeout value is exceeded.
00004	Open Detect Input 3	Read/Write	The Watchdog Timeout value is set in
00005	Open Detect Input 4	Read/Write	Register 40009. When set, Coil 10
00006	Open Detect Input 5	Read/Write	can be reset by the controller when
00007	Open Detect Input 6	Read/Write	normal communications resumes.
00008	Open Detect Input 7	Read/Write	
00009	Watchdog Enabled	Read/Write	The Power-up Event (Coil 11) is set
00010	Watchdog Event	Read/Write	every time the power is applied. It can
00011	Power-up Event	Read/Write	be cleared by the controller if desired.

RTD Sensor Temperature Ranges				
RTD Sensor Type	Minimum Temperature	Maximum Temperature		
Pt-100	-200 degrees C	+850 degrees C		
Ni-100	-80 degrees C	+180 degrees C		
Pt-1000	-200 degrees C	+200 degrees C		
Ni-1000	-60 degrees C	+150 degrees C		

# **INSTALLATION / SAFETY**

**Warning:** Remove power from the  $i^3$  Controller, CAN port, and any peripheral equipment connected to this local system before adding or replacing this or any module.

- a. All applicable codes and standards should be followed in the installation of this product.
- b. Shielded, twisted-pair wiring should be used for best performance.
- c. Shields may be terminated at the module terminal strip.
- d. In severe applications, shields should be tied directly to the ground block within the panel.
- e. Use the following wire type or equivalent: Belden 8441.

When found on the product, the following symbols specify:



Warning: Consult user documentation.



Warning: Electrical Shock Hazard.