

*i*OS - Remote I/O system

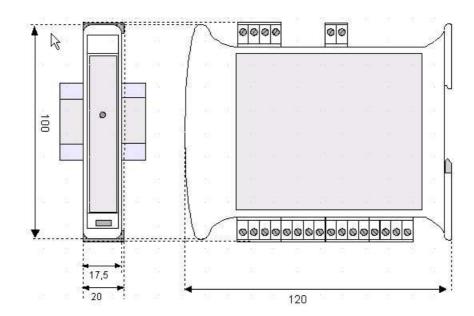
iOS/M08OXV-D2 8 Output Channel (0-10V)



SPECIFICATIONS

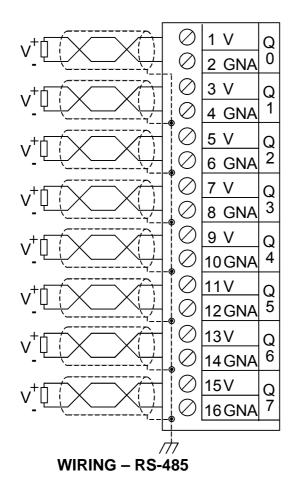
| | 08OXV-D1 | | | |
|-------------------------------|---|--|--|--|
| Number of Channels | 8 | | | |
| Output Ranges | 0-10V | | | |
| Resolution | Approximately 14-Bit | | | |
| Load Resistance | Voltage: >5Kohm | | | |
| Output Calibration | Voltage: +/-10mV | | | |
| External Power Supply Voltage | 18-30Vdc | | | |
| Required Power (Steady State) | 30mA @ 24Vdc, typical | | | |
| Required Power (Inrush) | Negligible | | | |
| Isolation | 2000Vac for 60 seconds (Input/Power & Input/Comms) | | | |

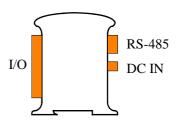
| | 08OXV-D1 | | |
|---------------------------------------|--|--|--|
| Thermal Drift | 100ppm max | | |
| Terminal Type | Screw Type, Removable | | |
| Storage Temp. | -40° to 85° Celsius | | |
| Operating Temp. | -10° to 60° Celsius | | |
| Relative Humidity | 5 to 95% Non-condensing | | |
| Dimensions WxHxD | 17.5mm x 100mm x 120mm 0.69" x 3.94" x 4.72" | | |
| Weight | 150g (6 oz.) | | |
| Communications | Modbus/RTU (binary) RS-485 half duplex | | |
| Default Comms. Parameters | 38400 baud, N, 8, 1, no h/s Default Modbus ID 1 | | |
| Supported Modbus Commands (family) | 1,2,3,4,5,6,8,15,16 | | |



Note: Number of I/O terminal connections change with model type

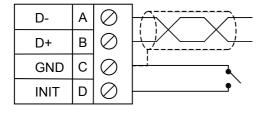
WIRING - I/O

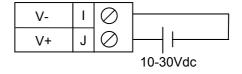




| Pin# | 08OOXV-D1 | | |
|------|-----------|-------|--|
| 1 | V | OUT 0 | |
| 2 | GNA | 0010 | |
| 3 | > | OUT 1 | |
| 4 | GNA | 0011 | |
| 5 | V | OUT 2 | |
| 6 | GNA | 0012 | |
| 7 | V | OUT 3 | |
| 8 | GNA | 0013 | |
| 9 | V | OUT 4 | |
| 10 | GNA | 0014 | |
| 11 | V | OUT 5 | |
| 12 | GNA | 0015 | |
| 13 | V | OUT 6 | |
| 14 | GNA | 0016 | |
| 15 | V | OUT 7 | |
| 16 | GNA | OUT 7 | |

WIRING - DC IN





Notes:

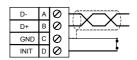
Both ends of the RS-485 network should be terminated with a 100Ω , ${}^{1}\!\!/\!\!4W$, 1% resistor. i^{3} controllers feature dipswitches or jumpers, which enable appropriate termination if the i^{3} is located on a network end.

Init default setup:

- 1. Install jumper between INIT and GND terminals of the RS-485 port.
- 2. Apply power to iOS unit.
- 3. Read parameter words to see current parameters.
- 4. Write changes if necessary.

The Init default RS485 settings are:

Modbus ID = 1 Baud rate = 9600 Parity = None Stop Bits = 1



CONFIGURATION DATA

iOS configuration settings are mapped into Modbus register space. This configuration data may be modified with any Modbus/RTU Master device. For convenience, IMO Precision Controls have developed a variety of application files, which allow an i^3 Integrated Controller to act as the iOS configurator. Initial configuration of the iOS module should be done on an individual basis, since all modules are delivered with a factory default of Modbus ID 1. Once each module on the network has its own unique Modbus ID, further configuration adjustments can be made with the entire network powered.

All configuration parameters listed below (except 40012 Channel Enable) are stored in EPROM and for this reason they should not be constantly rewritten.

| Configuration Parameters – Registers 40001 through 40013 | | | | |
|--|--------------------------------|--|-------|---------------------------------|
| Modbus Register | Description | Min | Max | Default |
| 40001-40005 | Reserved | | • | |
| 40006 | Communications Parameters | See 7 | Гable | 38.4kbaud, N, 8, 1, RTU Mode |
| 40007 | Modbus ID | Modbus ID 1 255 | | 1 |
| 40008 | Rx/Tx Delay (in 2mS steps) | 0 | 255 | 0mS |
| 40009 | Watchdog Timer (in 0.5s steps) | Fimer (in 0.5s steps) 0 255 | | 10 (5s) |
| 40010 | Modbus Coil Data | Modbus Coil Data Not Configuration Data – See I/O Data | | |
| 40011 | Reserved | | | |
| 40012 | Reserved | | | |
| 40013 | Reserved | | | |
| 40014 | Output Type | 255 | 255 | 255 (All channels Voltage) |

| Register 40006 (Communications Parameters) Bit Definition | | | | | | | |
|---|-------------------|-------|--------------------|--------------------|-----------|-------|-------|
| Bits 7-15 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
| Unused | Mode | Pa | rity | Data Bits | Baud Rate | | |
| | Value | | Meaning | 0 - 7 Data | Value | Mea | ning |
| | 0 = ASCII Mode | 0 | Mark | 0 = 7 Data Bits | 0 | 1200 | baud |
| | | 1 | Even | | Dita | Dita | 1 |
| | 1 = RTU | 2 | Odd | 1 - 0 Data | 2 | 4800 | baud |
| Mode | 3 | Space | 1 = 8 Data Bits | 3 | 9600 | baud | |
| | ivioue | | | טונס | 4 | 19200 | baud |
| | | | | | 5-7 | 38400 | baud |

INPUT / OUTPUT DATA

*i*OS Analog I/O utilizes both Modbus Registers (40001-40030) and Coils (1-11). It is possible to access all data using Registers only - Coils can be accessed through Register 40010.

The following tables list all Modbus I/O data available.

| I/O Register Data (Registers 40010-40026) | | | | | |
|---|--------------------------|------------|---------|---------|-------|
| Modbus | | | | | |
| Register | Description | Access | Minimum | Maximum | Units |
| 40010 | Mirror of Coil Data | Read/Write | n/a | n/a | n/a |
| 40015 | Output 0 | Read/Write | 0 | 10000 | 1mV |
| 40019 | Output 1 | Read/Write | 0 | 10000 | 1mV |
| 40016 | Output 2 | Read/Write | 0 | 10000 | 1mV |
| 40020 | Output 3 | Read/Write | 0 | 10000 | 1mV |
| 40017 | Output 4 | Read/Write | 0 | 10000 | 1mV |
| 40021 | Output 5 | Read/Write | 0 | 10000 | 1mV |
| 40018 | Output 6 | Read/Write | 0 | 10000 | 1mV |
| 40022 | Output 7 | Read/Write | 0 | 10000 | 1mV |
| 40023 | Default/Safe Value Out 0 | Read/Write | 0 | 10000 | 1mV |
| 40024 | Default/Safe Value Out 1 | Read/Write | 0 | 10000 | 1mV |
| 40025 | Default/Safe Value Out 2 | Read/Write | 0 | 10000 | 1mV |
| 40026 | Default/Safe Value Out 3 | Read/Write | 0 | 10000 | 1mV |
| 40027 | Default/Safe Value Out 4 | Read/Write | 0 | 10000 | 1mV |
| 40028 | Default/Safe Value Out 5 | Read/Write | 0 | 10000 | 1mV |
| 40029 | Default/Safe Value Out 6 | Read/Write | 0 | 10000 | 1mV |
| 40030 | Default/Safe Value Out 7 | Read/Write | 0 | 10000 | 1mV |

| Modbus Coil | Description | Access |
|----------------|------------------|------------|
| 00009 | Watchdog Enabled | Read/Write |
| 00010 | Watchdog Event | Read/Write |
| 00011 | Power-up Event | Read/Write |

| Modbus Register | Description | Access |
|--------------------|------------------|------------|
| 40010 bit 0 | Watchdog Enabled | Read/Write |
| 40010 bit 1 | Watchdog Event | Read/Write |
| 40010 bit 2 | Power-up Event | Read/Write |

Watchdog Event & Power-up Event Operation

If Coil 9 (Watchdog Enabled) is set, Coil 10 (Watchdog Event) will set if the Watchdog Timeout value is exceeded. The Watchdog Timeout value is set in Register 40009. When set, Coil 10 can be reset by the controller when normal communications resumes.

The Power-up Event (Coil 11) is set every time the power is applied. It can be cleared by the controller if desired.

5 INSTALLATION / SAFETY

Warning: Remove power from the i^3 controller, CAN port, and any peripheral equipment connected to this local system before adding or replacing this or any module.

- a. All applicable codes and standards should be followed in the installation of this product.
- b. Shielded, twisted-pair wiring should be used for best performance.
- c. Shields may be terminated at the module terminal strip.
- d. In severe applications, shields should be tied directly to the ground block within the panel.
- e. Use the following wire type or equivalent: Belden 8441.

When found on the product, the following symbols specify:



Warning: Consult user documentation.



Warning: Electrical Shock Hazard.