

25AA160C/D, 25LC160C/D

16K SPI Bus Serial EEPROM

Device Selection Table

Part Number	Vcc Range	Page Size	Temp. Ranges	Packages
25LC160C	2.5-5.5V	16 Byte	I,E	P, SN, ST, MS, MN
25AA160C	1.8-5.5V	16 Byte	I	P, SN, ST, MS, MN
25LC160D	2.5-5.5V	32 Byte	I,E	P, SN, ST, MS, MN
25AA160D	1.8-5.5V	32 Byte	I	P, SN, ST, MS, MN

Features:

- · Max. Clock 10 MHz
- · Low-Power CMOS Technology:
 - Max. write current: 5 mA at 5.5V
 - Read current: 5 mA at 5.5V, 10 MHz
 - Standby current: 5 uA at 5.5V
- 2048 x 8-bit Organization
- 16-Byte Page ('C' version devices)
- 32-Byte Page ('D' version devices)
- · Self-Timed Erase and Write Cycles (5 ms max.)
- · Block Write Protection:
 - Protect none, 1/4, 1/2 or all of array
- · Built-In Write Protection:
 - Power-on/off data protection circuitry
 - Write enable latch
- Write-protect pin
- Sequential Read
- · High Reliability:
 - Endurance: > 1M erase/write cycles
 - Data retention: > 200 years
 - ESD protection: > 4000V
- Temperature Ranges Supported:
 - Industrial (I): -40°C to +85°C - Automotive (E): -40°C to +125°C
- · Pb-Free and RoHS Compliant

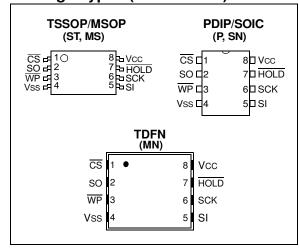
Description:

The Microchip Technology Inc. 25AA160C/D, 25LC160C/D (25XX160C/D) are 16 Kbit Serial Electrically Erasable PROMs. The memory is accessed via a simple Serial Peripheral Interface (SPI) compatible serial bus. The bus signals required are a clock input (SCK) plus separate data in (SI) and data out (SO) lines. Access to the device is controlled through a Chip Select (CS) input.

Communication to the device can be paused via the hold pin (HOLD). While the device is paused, transitions on its inputs will be ignored, with the exception of Chip Select, allowing the host to service higher priority interrupts.

The 25XX160C/D is available in standard packages including 8-lead PDIP and SOIC, and advanced packaging including 8-lead MSOP, TSSOP, and 2x3 TDFN. All packages are Pb-free and RoHS compliant.

Package Types (not to scale)



*25XX160C/D is used in this document as a generic part number for the 25AA160C/D, 25LC160C/D devices.

1.0 ELECTRICAL CHARACTERISTICS

Absolute Maximum Ratings(†)

Vcc	6.5V
All inputs and outputs w.r.t. Vss	-0.6V to Vcc+1.0V
Storage temperature	65℃ to 150℃
Ambient temperature under bias	40 ℃ to 125 ℃
ESD protection on all pins	4 kV

† NOTICE: Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operational listings of this specification is not implied. Exposure to maximum rating conditions for an extended period of time may affect device reliability.

TABLE 1-1: DC CHARACTERISTICS

I	DC CHARACTERISTICS				-40 °C to -40 °C to		
Param. No.	Sym Characteristic		Min. Max.		Units	Test Conditions	
D001	VIH1	High-level input voltage	0.7 Vcc	VCC+1	V	_	
D002	VIL1	Low-level input	-0.3	0.3 Vcc	V	Vcc ≥ 2.7V	
D003	VIL2	voltage	-0.3	0.2 Vcc	V	Vcc < 2.7V	
D004	VOL1	Low-level output		0.4	V	IOL = 2.1 mA	
D005	VOL2	voltage		0.2	V	IOL = 1.0 mA, VCC < 2.5V	
D006	Vон	High-level output voltage	Vcc-0.5	_	V	ΙΟΗ = -400 μΑ	
D007	ILI	Input leakage current		±1	μΑ	$\overline{\text{CS}}$ = VCC, VIN = VSS OR VCC	
D008	ILO	Output leakage current	_	±1	μΑ	CS = Vcc, Vout = Vss or Vcc	
D009	CINT	Internal Capacitance (all inputs and outputs)	_	7	pF	TA = 25 °C, CLK = 1.0 MHz, VCC = 5.0V (Note)	
D010	Icc Read		_	5	mA	VCC = 5.5V; FCLK = 10.0 MHz; SO = Open	
		Operating Current	_	2.5	mA	VCC = 2.5V; FCLK = 5.0 MHz; SO = Open	
D011	Icc Write		_	5 3	mA mA	VCC = 5.5V VCC = 2.5V	
D012	Iccs	Standby Current	_	5	μΑ	CS = Vcc = 5.5V, Inputs tied to Vcc or Vss, +125°C	
		, - -	_	1	μΑ	CS = Vcc = 5.5V, Inputs tied to Vcc or Vss, +85°C	

Note: This parameter is periodically sampled and not 100% tested.

TABLE 1-2: AC CHARACTERISTICS

	AC CH	ARACTERISTICS	Industrial (I) Automotive		-40℃ to - -40℃ to -	
Param. No.	Sym.	Characteristic	Min.	Max.	Units	Test Conditions
1	FCLK	Clock Frequency	_ _ _	10 5 3	MHz MHz MHz	4.5V ≤ VCC ≤ 5.5V 2.5V ≤ VCC < 4.5V 1.8V ≤ VCC < 2.5V
2	Tcss	CS Setup Time	50 100 150		ns ns ns	4.5V ≤ VCC ≤ 5.5V 2.5V ≤ VCC < 4.5V 1.8V ≤ VCC < 2.5V
3	Тсѕн	CS Hold Time	100 200 250	_ _ _	ns ns ns	4.5V ≤ VCC ≤ 5.5V 2.5V ≤ VCC < 4.5V 1.8V ≤ VCC < 2.5V
4	TCSD	CS Disable Time	50	_	ns	_
5	Tsu	Data Setup Time	10 20 30	_ _ _	ns ns ns	4.5V ≤ VCC ≤ 5.5V 2.5V ≤ VCC < 4.5V 1.8V ≤ VCC < 2.5V
6	THD	Data Hold Time	20 40 50	_ _ _	ns ns ns	4.5V ≤ VCC ≤ 5.5V 2.5V ≤ VCC < 4.5V 1.8V ≤ VCC < 2.5V
7	TR	CLK Rise Time	_	2	μs	(Note 1)
8	TF	CLK Fall Time	_	2	μs	(Note 1)
9	Тні	Clock High Time	50 100 150	_ _ _	ns ns ns	4.5V ≤ VCC ≤ 5.5V 2.5V ≤ VCC < 4.5V 1.8V ≤ VCC < 2.5V
10	TLO	Clock Low Time	50 100 150	_ _ _	ns ns ns	4.5V ≤ VCC ≤ 5.5V 2.5V ≤ VCC < 4.5V 1.8V ≤ VCC < 2.5V
11	TCLD	Clock Delay Time	50		ns	_
12	TCLE	Clock Enable Time	50	_	ns	_
13	Tv	Output Valid from Clock Low	_ _ _	50 100 160	ns ns ns	4.5V ≤ VCC ≤ 5.5V 2.5V ≤ VCC < 4.5V 1.8V ≤ VCC < 2.5V
14	Тно	Output Hold Time	0	_	ns	(Note 1)
15	TDIS	Output Disable Time	_ _ _	40 80 160	ns ns ns	$4.5V \le VCC \le 5.5V$ (Note 1) $2.5V \le VCC \le 4.5V$ (Note 1) $1.8V \le VCC \le 2.5V$ (Note 1)
16	THS	HOLD Setup Time	20 40 80	_ _ _	ns ns ns	4.5V ≤ VCC ≤ 5.5V 2.5V ≤ VCC < 4.5V 1.8V ≤ VCC < 2.5V

Note 1: This parameter is periodically sampled and not 100% tested.

^{2:} Two begins on the rising edge of $\overline{\text{CS}}$ after a valid write sequence and ends when the internal write cycle is complete.

^{3:} This parameter is not tested but ensured by characterization. For endurance estimates in a specific application, please consult the Total Endurance™ Model which can be obtained from our web site: www.microchip.com.

TABLE 1-2: AC CHARACTERISTICS (CONTINUED)

AC CHARACTERISTICS			Industrial (I): $TA = -40 ^{\circ}\text{C}$ to + Automotive (E): $TA = -40 ^{\circ}\text{C}$ to +			
Param. No.	Sym.	Characteristic	Min.	Max.	Units	Test Conditions
17	Тнн	HOLD Hold Time	20 40 80	_ _ _	ns ns ns	4.5V ≤ Vcc ≤ 5.5V 2.5V ≤ Vcc < 4.5V 1.8V ≤ Vcc < 2.5V
18	THZ	HOLD Low to Output High-Z	30 60 160	_ _ _	ns ns ns	4.5V ≤ Vcc ≤ 5.5V (Note 1) 2.5V ≤ Vcc < 4.5V (Note 1) 1.8V ≤ Vcc < 2.5V (Note 1)
19	Тнv	HOLD High to Output Valid	30 60 160	_ _ _	ns ns ns	4.5V ≤ Vcc ≤ 5.5V 2.5V ≤ Vcc < 4.5V 1.8V ≤ Vcc < 2.5V
20	Twc	Internal Write Cycle Time	_	5	ms	(NOTE 2)
21	_	Endurance	1M		E/W Cycles	(NOTE 3)

- **Note 1:** This parameter is periodically sampled and not 100% tested.
 - 2: Two begins on the rising edge of $\overline{\text{CS}}$ after a valid write sequence and ends when the internal write cycle is complete.
 - **3:** This parameter is not tested but ensured by characterization. For endurance estimates in a specific application, please consult the Total Endurance™ Model which can be obtained from our web site: www.microchip.com.

TABLE 1-3: AC TEST CONDITIONS

AC Waveform:					
VLO = 0.2V	_				
VHI = VCC - 0.2V	(Note 1)				
VHI = 4.0V	(Note 2)				
CL = 50 pF	_				
Timing Measurement Reference Level					
Input	0.5 Vcc				
Output	0.5 Vcc				

Note 1: For VCC ≤ 4.0V **2:** For VCC > 4.0V

FIGURE 1-1: HOLD TIMING

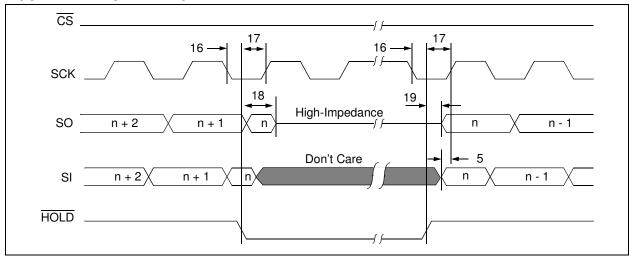


FIGURE 1-2: SERIAL INPUT TIMING

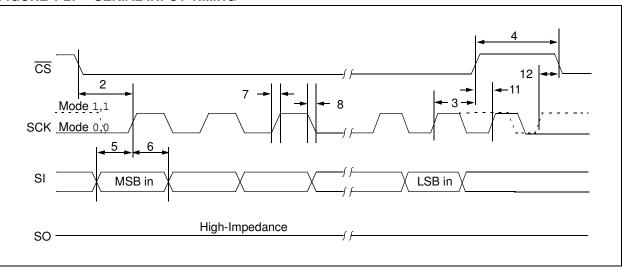
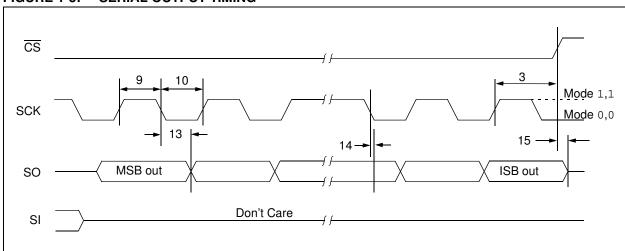


FIGURE 1-3: SERIAL OUTPUT TIMING



2.0 FUNCTIONAL DESCRIPTION

2.1 Principles of Operation

The 25XX160C/D are 2048 byte Serial EEPROMs designed to interface directly with the Serial Peripheral Interface (SPI) port of many of today's popular microcontroller families, including Microchip's PIC® microcontrollers. It may also interface with microcontrollers that do not have a built-in SPI port by using discrete I/O lines programmed properly with the software.

The 25XX160C/D contains an 8-bit instruction register. The device is accessed via the SI pin, with data being clocked in on the rising edge of SCK. The $\overline{\text{CS}}$ pin must be low and the $\overline{\text{HOLD}}$ pin must be high for the entire operation.

Table 2-1 contains a list of the possible instruction bytes and format for device operation. All instructions, addresses, and data are transferred MSB first, LSB last.

Data $\underline{(SI)}$ is sampled on the first rising edge of SCK after \overline{CS} goes low. If the clock line is shared with other peripheral devices on the SPI bus, the user can assert the \overline{HOLD} input and place the $\underline{25XX160C/D}$ in 'HOLD' mode. After releasing the \overline{HOLD} pin, operation will resume from the point when the \overline{HOLD} was asserted.

2.2 Read Sequence

The device is selected by pulling $\overline{\text{CS}}$ low. The 8-bit READ instruction is transmitted to the 25XX160C/D followed by the 16-bit address, with the five MSBs of the address being "don't care" bits. After the correct READ instruction and address are sent, the data stored in the memory at the selected address is shifted out on the SO pin. The data stored in the memory at the next address can be read sequentially by continuing to provide clock pulses. The internal Address Pointer is automatically incremented to the next higher address after each byte of data is shifted out. When the highest address is reached (07FFh), the address counter rolls over to address 0000h allowing the read cycle to be continued indefinitely. The read operation is terminated by raising the $\overline{\text{CS}}$ pin (Figure 2-1).

2.3 Write Sequence

Prior to any attempt to write data to the 25XX160C/D, the write enable latch must be set by issuing the WREN instruction (Figure 2-4). This is done by setting \overline{CS} low and then clocking out the proper instruction into the 25XX160C/D. After all eight bits of the instruction are transmitted, the \overline{CS} must be brought high to set the write enable latch. If the write operation is initiated immediately after the WREN instruction without \overline{CS} being brought high, the data will not be written to the array because the write enable latch will not have been properly set.

Once the write enable <u>latch</u> is set, the user may proceed by setting the <u>CS</u> low, issuing a <u>WRITE</u> instruction, followed by the 16-bit address, with the five MSBs of the address being "don't care" bits, and then the data to be written. Up to 16 bytes (25XX160C) or 32 bytes (25XX160D) of data can be sent to the device before a write cycle is necessary. The only restriction is that all of the bytes must reside in the same page.

Note:

Page write operations are limited to writing bytes within a single physical page, regardless of the number of bytes actually being written. Physical page boundaries start at addresses that are integer multiples of the page buffer size (or 'page size') and, end at addresses that are integer multiples of page size - 1. If a Page Write command attempts to write across a physical page boundary, the result is that the data wraps around to the beginning of the current page (overwriting data previously stored there), instead of being written to the next page as might be expected. It is therefore necessary for the application software to prevent page write operations that would attempt to cross a page boundary.

For the data to be actually written to the array, the CS must be brought high after the Least Significant bit (D0) of the *n*th data byte has been clocked in. If $\overline{\text{CS}}$ is brought high at any other time, the write operation will not be completed. Refer to Figure 2-2 and Figure 2-3 for more detailed illustrations on the byte write sequence and the page write sequence, respectively. While the write is in progress, the STATUS register may be read to check the status of the WPEN, WIP, WEL, BP1 and BP0 bits (Figure 2-6). A read attempt of a memory array location will not be possible during a write cycle. When the write cycle is completed, the write enable latch is reset.

Block Diagram

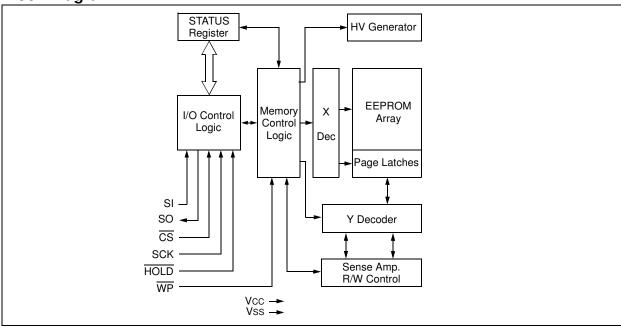


TABLE 2-1: INSTRUCTION SET

Instruction Name	Instruction Format	Description
READ	0000 0011	Read data from memory array beginning at selected address
WRITE	0000 0010	Write data to memory array beginning at selected address
WRDI	0000 0100	Reset the write enable latch (disable write operations)
WREN	0000 0110	Set the write enable latch (enable write operations)
RDSR	0000 0101	Read STATUS register
WRSR	0000 0001	Write STATUS register

FIGURE 2-1: READ SEQUENCE

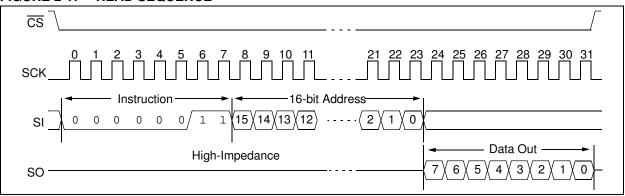


FIGURE 2-2: BYTE WRITE SEQUENCE

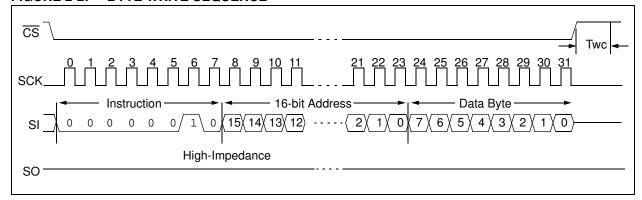
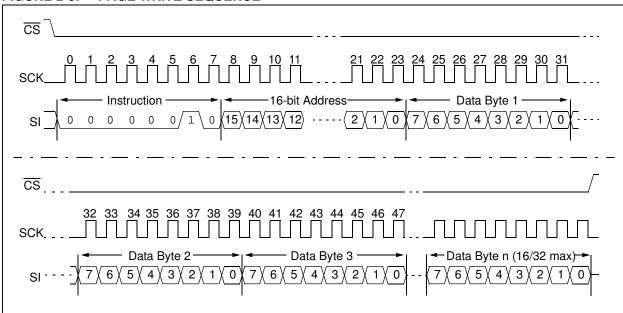


FIGURE 2-3: PAGE WRITE SEQUENCE



2.4 Write Enable (WREN) and Write Disable (WRDI)

The 25XX160C/D contains a write enable latch. See Table 2-4 for the Write-Protect Functionality Matrix. This latch must be set before any write operation will be completed internally. The WREN instruction will set the latch, and the WRDI will reset the latch.

The following is a list of conditions under which the write enable latch will be reset:

- Power-up
- WRDI instruction successfully executed
- WRSR instruction successfully executed
- WRITE instruction successfully executed

FIGURE 2-4: WRITE ENABLE SEQUENCE (WREN)

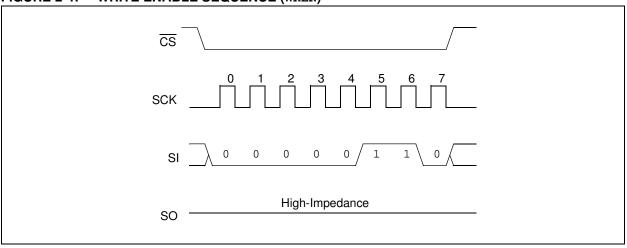
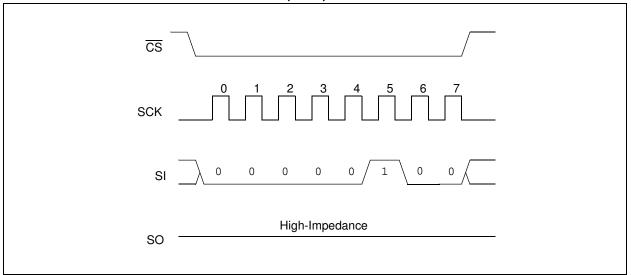


FIGURE 2-5: WRITE DISABLE SEQUENCE (WRDI)



2.5 Read Status Register (RDSR) Instruction

The Read Status Register (RDSR) instruction provides access to the STATUS register. The STATUS register may be read at any time, even during a write cycle. The STATUS register is formatted as follows:

TABLE 2-2: STATUS REGISTER

7	6	5	4	3	2	1	0	
W/R	_	-	-	W/R	W/R	R	R	
WPEN	Χ	Χ	Χ	BP1	BP0	WEL	WIP	
W/R = w	W/R = writable/readable. R = read-only.							

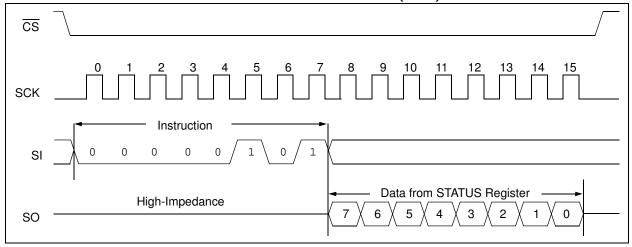
The **Write-In-Process (WIP)** bit indicates whether the 25XX160C/D is busy with a write operation. When set to a '1', a write is in progress, when set to a '0', no write is in progress. This bit is read-only.

The Write Enable Latch (WEL) bit indicates the status of the write enable latch and is read-only. When set to a '1', the latch allows writes to the array, when set to a '0', the latch prohibits writes to the array. The state of this bit can always be updated via the WREN or WRDI commands regardless of the state of write protection on the STATUS register. These commands are shown in Figure 2-4 and Figure 2-5.

The **Block Protection (BP0 and BP1)** bits indicate which blocks are currently write-protected. These bits are set by the user issuing the WRSR instruction. These bits are nonvolatile, and are shown in Table 2-3.

See Figure 2-6 for the RDSR timing sequence.

FIGURE 2-6: READ STATUS REGISTER TIMING SEQUENCE (RDSR)



2.6 Write Status Register (WRSR) Instruction

The Write Status Register (WRSR) instruction allows the user to write to the nonvolatile bits in the STATUS register as shown in Table 2-2. The user is able to select one of four levels of protection for the array by writing to the appropriate bits in the STATUS register. The array is divided up into four segments. The user has the ability to write-protect none, one, two or all four of the segments of the array. The partitioning is controlled as shown in Table 2-3.

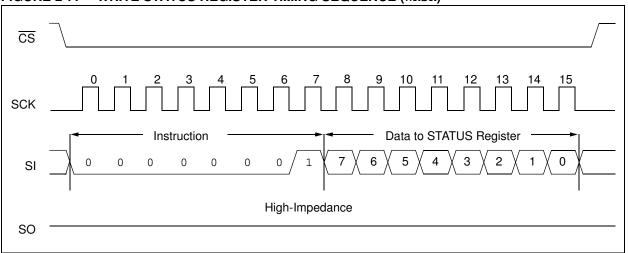
The Write-Protect Enable (WPEN) bit is a nonvolatile bit that is available as an enable bit for the \overline{WP} pin. The Write-Protect (\overline{WP}) pin and the Write-Protect Enable (WPEN) bit in the STATUS register control the programmable hardware write-protect feature. Hardware write protection is enabled when \overline{WP} pin is low and the WPEN bit is high. Hardware write protection is disabled when either the \overline{WP} pin is high or the WPEN bit is low. When the chip is hardware write-protected, only writes to nonvolatile bits in the STATUS register are disabled. See Table 2-4 for a matrix of functionality on the WPEN bit.

See Figure 2-7 for the WRSR timing sequence.

TABLE 2-3: ARRAY PROTECTION

BP1	BP0	Array Addresses Write-Protected
0	0	none
0	1	upper 1/4 (0600h-07FFh)
1	0	upper 1/2 (0400h-07FFh)
1	1	all (0000h-07FFh)

FIGURE 2-7: WRITE STATUS REGISTER TIMING SEQUENCE (WRSR)



2.7 Data Protection

The following protection has been implemented to prevent inadvertent writes to the array:

- The write enable latch is reset on power-up
- A write enable instruction must be issued to set the write enable latch
- After a byte write, page write or STATUS register write, the write enable latch is reset
- CS must be set high after the proper number of clock cycles to start an internal write cycle
- Access to the array during an internal write cycle is ignored and programming is continued

2.8 Power-On State

The 25XX160C/D powers on in the following state:

- The device is in low-power Standby mode (CS = 1)
- The write enable latch is reset
- SO is in high-impedance state

TABLE 2-4: WRITE-PROTECT FUNCTIONALITY MATRIX

WEL (SR bit 1)	WPEN (SR bit 7)	WP (pin 3)	Protected Blocks	Unprotected Blocks	STATUS Register
0	х	x	Protected	Protected	Protected
1	0	x	Protected	Writable	Writable
1	1	0 (low)	Protected	Writable	Protected
1	1	1 (high)	Protected	Writable	Writable

x = don't care

3.0 PIN DESCRIPTIONS

The descriptions of the pins are listed in Table 3-1.

TABLE 3-1: PIN FUNCTION TABLE

Name	Pin Number	Function
CS	1	Chip Select Input
SO	2	Serial Data Output
WP	3	Write-Protect Pin
Vss	4	Ground
SI	5	Serial Data Input
SCK	6	Serial Clock Input
HOLD	7	Hold Input
Vcc	8	Supply Voltage

3.1 Chip Select (CS)

A low level on this pin selects the device. A high level deselects the device and forces it into Standby mode. However, a programming cycle which is already initiated or in progress will be completed, regardless of the \overline{CS} input signal. If \overline{CS} is brought high during a program cycle, the device will go into Standby mode as soon as the programming cycle is complete. When the device is deselected, SO goes to the high-impedance state, allowing multiple parts to share the same SPI bus. A low-to-high transition on \overline{CS} after a valid write sequence initiates an internal write cycle. After power-up, a low level on \overline{CS} is required prior to any sequence being initiated.

3.2 Serial Output (SO)

The SO pin is used to transfer data out of the 25XX160C/D. During a read cycle, data is shifted out on this pin after the falling edge of the serial clock.

3.3 Write-Protect (WP)

This pin is used in conjunction with the WPEN bit in the STATUS register to prohibit writes to the nonvolatile bits in the STATUS register. When \overline{WP} is low and WPEN is high, writing to the nonvolatile bits in the STATUS register is disabled. All other operations function normally. When \overline{WP} is high, all functions, including writes to the nonvolatile bits in the STATUS register operate normally. If the WPEN bit is set, \overline{WP} low during a STATUS register write sequence will disable writing to the STATUS register. If an internal write cycle has already begun, \overline{WP} going low will have no effect on the write.

The \overline{WP} pin function is blocked when the WPEN bit in the STATUS register is low. This allows the user to install the 25XX160C/D in a system with \overline{WP} pin grounded and still be able to write to the STATUS register. The \overline{WP} pin functions will be enabled when the WPEN bit is set high.

3.4 Serial Input (SI)

The SI pin is used to transfer data into the device. It receives instructions, addresses and data. Data is latched on the rising edge of the serial clock.

3.5 Serial Clock (SCK)

The SCK is used to synchronize the communication between a master and the 25XX160C/D. Instructions, addresses or data present on the SI pin are latched on the rising edge of the clock input, while data on the SO pin is updated after the falling edge of the clock input.

3.6 Hold (HOLD)

The HOLD pin is used to suspend transmission to the 25XX160C/D while in the middle of a serial sequence without having to retransmit the entire sequence again. It must be held high any time this function is not being used. Once the device is selected and a serial sequence is underway, the HOLD pin may be pulled low to pause further serial communication without resetting the serial sequence. The HOLD pin must be brought low while SCK is low, otherwise the HOLD function will not be invoked until the next SCK high-tolow transition. The 25XX160C/D must remain selected during this sequence. The SI, SCK and SO pins are in a high-impedance state during the time the device is paused and transitions on these pins will be ignored. To resume serial communication, HOLD must be brought high while the SCK pin is low, otherwise serial communication will not resume. Lowering the HOLD line at any time will tri-state the SO line.

4.0 PACKAGING INFORMATION

4.1 Package Marking Information

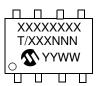
8-Lead MSOP (150 mil)



Example:



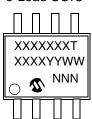
8-Lead PDIP



Example:



8-Lead SOIC



Example:



8-Lead TSSOP



Example:



8-Lead 2x3 TDFN



Example:



	1st Line Marking Codes						
Part Number	TSSOP	MSOP	TDFN				
	1350P	MISOP	I Temp.	E Temp.			
25AA160C	5AAC	5AACT	C51	_			
25AA160D	5AAD	5AADT	C61	_			
25LC160C	5LAC	5LACT	C54	C55			
25LC160D	5LAD	5LADT	C64	C65			

Note: T = Temperature grade (I, E)

Legend: XX...X Customer-specific information

Y Year code (last digit of calendar year)
YY Year code (last 2 digits of calendar year)
WW Week code (week of January 1 is week '01')

NNN Alphanumeric traceability code

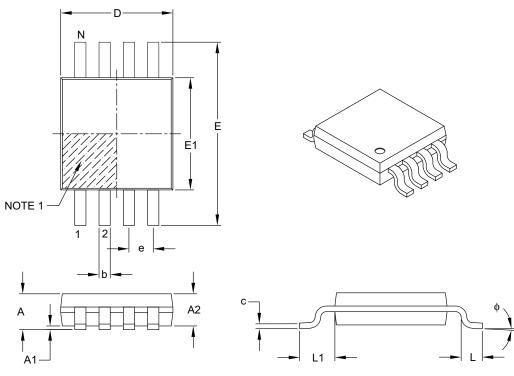
e3 Pb-free JEDEC designator for Matte Tin (Sn)

This package is Pb-free. The Pb-free JEDEC designator (e3) can be found on the outer packaging for this package.

Note: In the event the full Microchip part number cannot be marked on one line, it will be carried over to the next line, thus limiting the number of available characters for customer-specific information.

□ Lead Plastic Micro Small Outline Package ■ MS ■ [MSOP]

Note □ For the most current package drawings please see the Microchip Packaging Specification located at □ http www.microchip.com.packaging



	Units		MILLIMETERS		
	Dimension 11 imits	MIN	NOM	MAX	
Number⊚fiPins	N				
Pitch	е		BSC		
Overall Height	A	_	_		
Molded. Package ☐ hickness	A□				
Standoff□	A□		-		
Overall Width	E	□□□BSC			
Molded Package Width	EΠ	□□□BSC			
Overall Length	D	□□□BSC			
Foot Length	L				
Footprint	L	□□□REF			
Foot Angle	ф	□°	_	□°	
Lead⊡hickness	С		_		
Lead Width	b		_		

Notes□

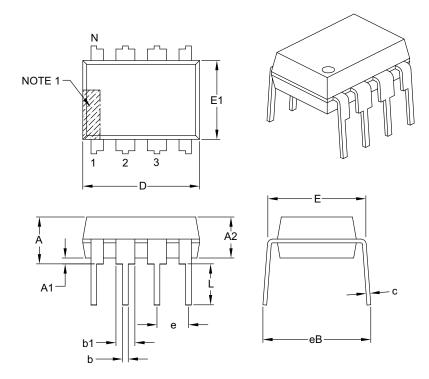
- □□ Pin □□visual index feature may vary □but must be to cated within the hatched area □
- $\begin{tabular}{ll} \square Dimensions \square D and \square do not finclude $mold flash or protrusions \square Mold flash or protrusions $not exceed \square manual perside \square and \square and$
- ☐ Dimensioning and tolerancing per ASME Y ☐ ☐ M☐

 $BSC _Basic _Dimension _Theoretically _exact _value _shown _without _tolerances _like _shown _without _without _without _without _without _without _without _without _without _$

 $REF \blacksquare Reference \blacksquare Dimension \blacksquare usually \underline{ without } \underline{ tolerance} \underline{ \ \, } \underline{ for } \underline{ information} \underline{ \ \, } \underline{ purposes} \underline{ \ \, } \underline{ only} \underline{ \ \, } \underline{$

Lead Plastic Dual In Line P ... mil Body [PDIP]

Note☐ For the most current package drawings please see the Microchip Packaging Specification to cated at http://www.microchip.com/packaging



Units		INCHES			
Dimensi	ion Limits	MIN	NOM	MAX	
Number of Pins	N				
Pitch	е		BSC		
Top to Seating Plane	Α	_	-		
Molded@Package@Thickness	A□				
Base to Seating Plane	A□		-	_	
Shoulder to Shoulder Width	Е				
Molded Package Width	EΠ				
Overall Length	D				
TipɪtoɪSeatingɪPlane	L				
Lead Thickness	С				
Upper Lead Width	b□				
Lower Lead Width	b				
Overall Row Spacing \$	eB	_	_		

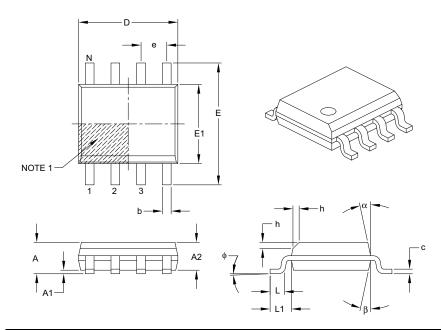
Notes□

- $\begin{tabular}{l} \square Pin \blacksquare visual index feature \square wary \blacksquare but \square us the flocated \square index feature \square and \square are \square and \square index feature \square are \square index feature \square index feature \$\square\$ index feature \$\square\$ index feature \$\square index feature \$\max_{n}\$ in \$n = n\$ in \$n = n\$ in \$n = n\$ in
- □□ § Significant Characteristic □
- Dimensions Diand Endo not include mold flash or protrusions Mold flash or protrusions shall not exceed per side
- □□ Dimensioning and tolerancing per ASME Y □□□M□

BSC Basic Dimension Theoretically exact value shown without tolerances

□ Lead Plastic Small Outline SN → Narrow □ □ □ mm Body [SOIC]

Note For the most current package drawings please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



Units		MILLIMETERS		
	Dimension Limits	MIN	NOM	MAX
Number⊚fiPins	N			
Pitch	е		□□□BSC	_
Overall Height	A	_	-	
Molded. Package Thickness	A□		-	_
Standoff S	A□		-	
Overall Width	E	BSC		
Molded Package Width	E□	□□□BSC		
Overall Length	D	□□□□BSC		
Chamfer ⊡ optional □	h		-	
Foot Length	L		-	
Footprint	L		□□□REF	
Foot Angle	ф	Ľ	_	□°
Lead Thickness	С		-	
Lead Width	b		_	
Mold Draft Angle Top	α	ď	_	
Mold Draft Angle Bottom	β	°	_	

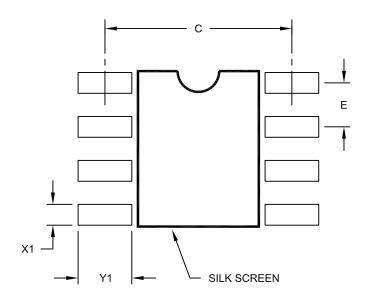
Notes□

- $\ \, \square \ \, \text{Pin} \\ \boxed{\square visual index feature may vary } \\ \boxed{\text{but must be located within the hatched area}} \\$
- □□ § Significant Characteristic □
- Dimensions D and E do not include mold flash or protrusions Mold flash or protrusions shall not exceed when more resided

BSC Basic Dimension Theoretically exact value shown without tolerances

□Lead Plastic Small Outline SN → Narrow □□□ mm Body [SOIC]

For the most current package drawings please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



RECOMMENDED LAND PATTERN

Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch	Е		1.27 BSC	
Contact Pad Spacing	С		5.40	
Contact Pad Width (X8)	X1			0.60
Contact Pad Length (X8)	Y1			1.55

Notes:

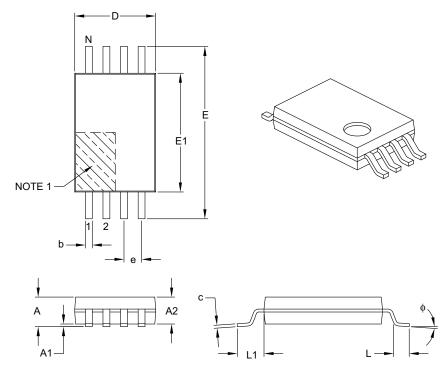
1. Dimensioning and tolerancing per ASME Y14.5M

 ${\it BSC: Basic \ Dimension. Theoretically \ exact \ value \ shown \ without \ tolerances.}$

Microchip Technology Drawing No. C04-2057A

□ Lead Plastic Thin Shrink Small Outline ST → □ □ □ mm Body [TSSOP]

Note For the most current package drawings please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



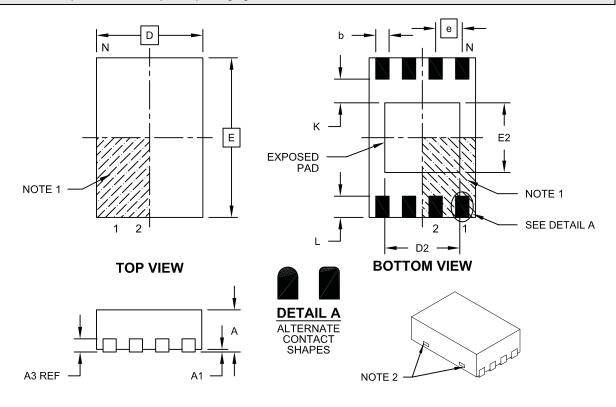
Units		MILLIMETERS		
Dimens	ion⊈imits	MIN	NOM	MAX
Number of Pins	N			
Pitch	е		BSC	
Overall Height	Α	-	_	
Molded Package Thickness	A□			
Standoff□	A□		_	
Overall Width	Е	□□□BSC		
Molded:Package:Width	E□			
Molded@ackage@ength	D			
Foottength	L			
Footprint	L	□ □ □ REF		
Foot⊠ngle	ф	□°	_	□°
Lead⊡hickness	С		_	
Lead Width	b		_	

Notes□

- $\begin{tabular}{ll} \square Dimensions \square D and \square do not finclude $mold flash or protrusions \square Mold flash or protrusions $not exceed \square and $not exceed not include not flash or protrusions not flash or protrusions not flash or protrusions not flash $not$$
- ☐ Dimensioning and tolerancing per ASME Y ☐ ☐ M ☐
 - BSC Basic Dimension Theoretically exact value shown without tolerances
 - $REF \square Reference \textcircled{D} imension \textcircled{u} sually \textcircled{w} it hout \textcircled{I} tolerance \textcircled{I} for \textcircled{i} n formation \textcircled{p} urposes \textcircled{o} n \\ ly \square$

□Lead Plastic Dual Flat No Lead Package MN □ x x □ □ mm Body [TDFN]

ote☐ For the most current package drawings please see the Microchip Packaging Specification to cated at http www.microchip.compackaging



Units		MILLIMETERS			
Dimension	Limits	MIN	NOM	MAX	
Number of Pins	N		8		
Pitch	е		0.50 BSC		
Overall Height	Α	0.70	0.75	0.80	
Standoff	A1	0.00	0.02	0.05	
Contact Thickness	A3	0.20 REF			
Overall Length	D	2.00 BSC			
Overall Width	Е	3.00 BSC			
Exposed Pad Length	D2	1.20	-	1.60	
Exposed Pad Width	E2	1.20	-	1.60	
Contact Width	b	0.20	0.25	0.30	
Contact Length	L	0.25	0.30	0.45	
Contact-to-Exposed Pad	K	0.20	-	-	

Notes:

- 1. Pin 1 visual index feature may vary, but must be located within the hatched area.
- 2. Package may have one or more exposed tie bars at ends.
- 3. Package is saw singulated
- 4. Dimensioning and tolerancing per ASME Y14.5M

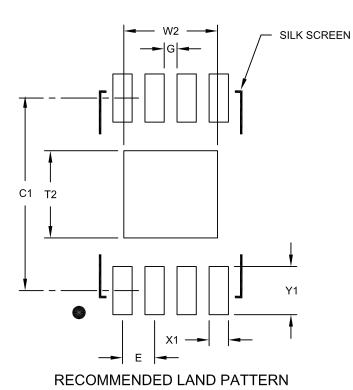
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing No. C04-129B

□ Lead Plastic Dual Flat No Lead Package MN → x x □ □ □ mm Body [TDFN]

For the most current package drawings please see the Microchip Packaging Specification to cated at http://www.microchip.com/packaging



Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch E		0.50 BSC		
Optional Center Pad Width	W2			1.46
Optional Center Pad Length	T2			1.36
Contact Pad Spacing	C1		3.00	
Contact Pad Width (X8)	X1			0.30
Contact Pad Length (X8)	Y1			0.75
Distance Between Pads	G	0.20		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2129A

APPENDIX A: REVISION HISTORY

Revision A (4/2009)

Original release of this document.

25XX160C/D

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5.	What deletions from the document coul	ld be made without affecting the overall usefulness?
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7.	How would you improve this document	?

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PART NO.	X	– <u>X</u> <u>/XX</u>
Device	Tape & Ree	el Temp Range Package
Device:	25AA160C 25AA160D 25LC160C 25LC160D	16 Kbit, 1.8V, 32 Byte Page SPI Serial EEPROM
Tape & Reel:	Blank = T =	Standard packaging Tape & Reel
Temperature Range:	I = E =	-40°C to+85°C -40°C to+125°C
Package:	MS = P = SN = ST = MNY ⁽¹⁾ =	Plastic MSOP (Micro Small Outline), 8-lead Plastic DIP (300 mil body), 8-lead Plastic SOIC (3.90 mm body), 8-lead TSSOP, 8-lead 8-lead 2x3 mm TDFN
Note 1: "Y"	indicates a Nick	xel Palladium Gold (NiPdAu) finish.

Examples:

- a) 25AA160C-I/MS = 16 Kbit, 16-byte page, 1.8V Serial EEPROM, Industrial temp., MSOP package
- b) 25AA160CT-I/SN = 16 Kbit, 16-byte page, 1.8V Serial EEPROM, Industrial temp., Tape & Reel, SOIC package
- c) 25LC160DT-I/SN = 16 Kbit, 32-byte page, 2.5V Serial EEPROM, Industrial temp., Tape & Reel, SOIC package
- d) 25LC160DT-I/ST = 16 Kbit, 32-byte page, 2.5V Serial EEPROM, Industrial temp., Tape & Reel, TSSOP package

25XX160C/D

NOTES:

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- Microchip products meet the specification contained in their particular Microchip Data Sheet.
- Microchip believes that its family of products is one of the most secure families of its kind on the market today, when used in the
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- There are dishonest and possibly illegal methods used to breach the code protection feature. All of these methods, to our
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