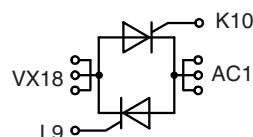


AC Controller Modules

ECO-PAC 2

Preliminary Data

V_{RSM}	V_{RRM}	Type
V_{DSM}	V_{DRM}	
V	V	
900	800	MMO230-08io7
1300	1200	MMO230-12io7
1500	1400	MMO230-14io7
1700	1600	MMO230-16io7
1900	1800	MMO230-18io7



Symbol	Conditions	Maximum Ratings		
I_{RMS}	$T_c = 85^\circ\text{C}$; 50-400 Hz (per single controller)	230	A	
I_{TRMS}		180	A	
I_{TAVM}	$T_c = 85^\circ\text{C}$; 180° sine	105	A	
I_{TSM}	$T_{VJ} = 45^\circ\text{C}$; $V_R = 0 \text{ V}$; $t = 10 \text{ ms}$ (50 Hz), sine	2250	A	
	$t = 8.3 \text{ ms}$ (60 Hz), sine	2400	A	
I^2dt	$T_{VJ} = 125^\circ\text{C}$; $V_R = 0 \text{ V}$; $t = 10 \text{ ms}$ (50 Hz), sine	2000	A	
	$t = 8.3 \text{ ms}$ (60 Hz), sine	2150	A	
$(di/dt)_{cr}$	$T_{VJ} = 45^\circ\text{C}$; $V_R = 0 \text{ V}$; $t = 10 \text{ ms}$ (50 Hz), sine	25300	A^2s	
	$t = 8.3 \text{ ms}$ (60 Hz), sine	23900	A^2s	
$(dv/dt)_{cr}$	$T_{VJ} = 125^\circ\text{C}$; $V_R = 0 \text{ V}$; $t = 10 \text{ ms}$ (50 Hz), sine	20000	A^2s	
	$t = 8.3 \text{ ms}$ (60 Hz), sine	19100	A^2s	
$(di/dt)_{cr}$	$T_{VJ} = 125^\circ\text{C}$; $f = 50 \text{ Hz}$; $t_p = 200 \mu\text{s}$; $V_D = \frac{2}{3}V_{DRM}$; $I_G = 0.45 \text{ A}$ repetitive, $I_T = 250 \text{ A}$	150	$\text{A}/\mu\text{s}$	
	$di_G/dt = 0.45 \text{ A}/\mu\text{s}$; non repetitive, $I_T = I_{TAVM}$	500	$\text{A}/\mu\text{s}$	
P_{GM}	$T_{VJ} = 125^\circ\text{C}$; $I_T = I_{TAVM}$; $t_p = 30 \text{ ms}$	≤ 10	W	
	$t_p = 300 \text{ ms}$	≤ 5	W	
P_{GAVM}		0.5	W	
V_{RGM}		10	V	
T_{VJ}		-40 ... +125	$^\circ\text{C}$	
T_{VJM}		125	$^\circ\text{C}$	
T_{stg}		-40 ... +125	$^\circ\text{C}$	
V_{ISOL}	50/60 Hz, RMS	3000	V ~	
	$I_{ISOL} \leq 1 \text{ mA}$	3600	V ~	
M_d	Mounting torque (M4)	1.5 - 2.0 14 - 18	Nm lb.in.	
Weight	typ.	26	g	

Data according to IEC 60747 refer to a single thyristor unless otherwise stated

IXYS reserves the right to change limits, test conditions and dimensions.

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$I_{RMS} = 230 \text{ A}$
 $V_{RRM} = 800 - 1800 \text{ V}$

Features

- Thyristor controller for AC (circuit W1C acc. to IEC) for mains frequency
- Isolation voltage 3000 V~
- Planar glass passivated chips
- Low forward voltage drop
- Leads suitable for PC board soldering

Applications

- Switching and control of single and three phase AC circuits
- Light and temperature control
- Softstart AC motor controller
- Solid state switches

Advantages

- Easy to mount with two screws
- Space and weight savings
- Improved temperature and power cycling
- High power density
- Small and light weight

Component

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
I_D, I_R	$T_{VJ} = 125^\circ C; V_R = V_{RRM}; V_D = V_{DRM}$		5	mA
V_T	$I_T = 300 A; T_{VJ} = 25^\circ C$		1.5	V
V_{TO}	For power-loss calculations only		0.8	V
r_T			2.4	$m\Omega$
V_{GT}	$V_D = 6 V; T_{VJ} = 25^\circ C$ $T_{VJ} = -40^\circ C$		1.5	V
I_{GT}	$V_D = 6 V; T_{VJ} = 25^\circ C$ $T_{VJ} = -40^\circ C$		150	mA
I_{GD}	$T_{VJ} = 125^\circ C; V_D = \frac{2}{3} V_{DRM}$		0.2	V
I_{GD}	$T_{VJ} = 125^\circ C; V_D = \frac{2}{3} V_{DRM}$		10	mA
I_L	$T_{VJ} = 25^\circ C; t_p = 10 ms$ $I_G = 0.45 A; di_G/dt = 0.45 A/\mu s$		450	mA
I_H	$T_{VJ} = 25^\circ C; V_D = 6 V; R_{GK} = \infty$		200	mA
t_{gd}	$T_{VJ} = 25^\circ C; V_D = \frac{1}{2} V_{DRM}$ $I_G = 0.45 A; di_G/dt = 0.45 A/\mu s$		2	μs
R_{thJC}	per Thyristor; DC per module		0.26	K/W
R_{thCH}	per Thyristor; DC per module	0,2 0,1	0.13	K/W
d_s	Creeping distance on surface		11.2	mm
d_A	Creeping distance in air		5.0	mm
a	Max. allowable acceleration		50	m/s^2

Dimensions in mm (1 mm = 0.0394")

