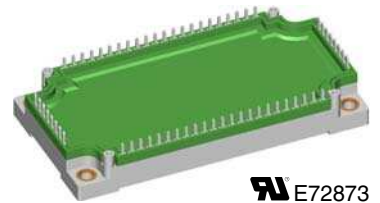
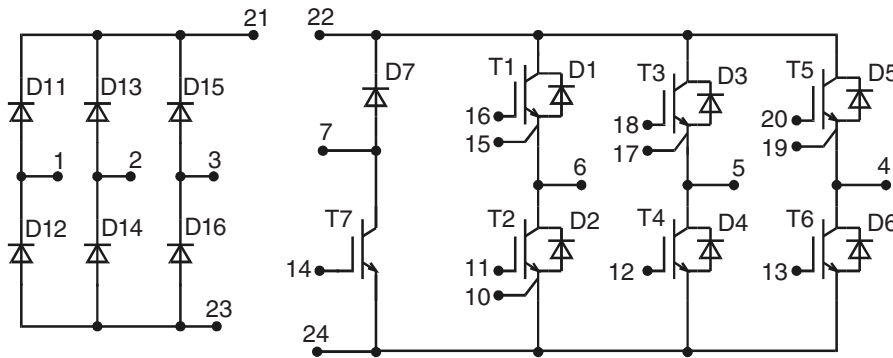
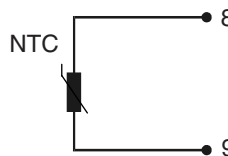


# Converter - Brake - Inverter Module (CBI3)


**IXYS** E72873

See outline drawing for pin arrangement

## Preliminary data



Three Phase Rectifier	Brake Chopper	Three Phase Inverter
$V_{RRM} = 1600\text{ V}$	$V_{CES} = 600\text{ V}$	$V_{CES} = 600\text{ V}$
$I_{FAVM} = 70\text{ A}$	$I_{C25} = 50\text{ A}$	$I_{C25} = 100\text{ A}$
$I_{FSM} = 700\text{ A}$	$V_{CE(sat)} = 2.0\text{ V}$	$V_{CE(sat)} = 2.0\text{ V}$

### Input Rectifier D11 - D16

Symbol	Conditions	Maximum Ratings	
$V_{RRM}$		1600	V
$I_{FAV}$	$T_C = 80^\circ\text{C}$ ; sine 180°	50	A
$I_{DAVM}$	$T_C = 80^\circ\text{C}$ ; rectangular; $d = 1/3$ ; bridge	140	A
$I_{FSM}$	$T_{VJ} = 25^\circ\text{C}$ ; $t = 10\text{ ms}$ ; sine 50 Hz	700	A
$P_{tot}$	$T_C = 25^\circ\text{C}$	135	W

Symbol	Conditions	Characteristic Values ( $T_{VJ} = 25^\circ\text{C}$ , unless otherwise specified)		
		min.	typ.	max.
$V_F$	$I_F = 75\text{ A}$ ; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		1.2 1.2	V V
$I_R$	$V_R = V_{RRM}$ ; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		0.8	0.05 mA mA
$R_{thJC}$	(per diode)			0.94 K/W

## Application: AC motor drives with

- € Input from single or three phase grid
- € Three phase synchronous or asynchronous motor
- € electric braking operation

## Features

- € High level of integration - only one power semiconductor module required for the whole drive
- € NPT IGBT technology with low saturation voltage, low switching losses, high RBSOA and short circuit ruggedness
- € Epitaxial free wheeling diodes with Hiperfast and soft reverse recovery
- € Industry standard package with insulated copper base plate and soldering pins for PCB mounting
- € Temperature sense included

**Output Inverter T1 - T6**

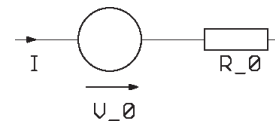
Symbol	Conditions	Maximum Ratings	
$V_{CES}$	$T_{VJ} = 25^{\circ}\text{C}$ to $150^{\circ}\text{C}$	600	V
$V_{GES}$	Continuous	$\pm 20$	V
$I_{C25}$	$T_C = 25^{\circ}\text{C}$	100	A
$I_{C80}$	$T_C = 80^{\circ}\text{C}$	65	A
<b>RBSOA</b>	$V_{GE} = \pm 15\text{ V}$ ; $R_G = 15\ \Omega$ ; $T_{VJ} = 125^{\circ}\text{C}$ Clamped inductive load; $L = 100\ \mu\text{H}$	$I_{CM} = 150$ $V_{CEK} \leq V_{CES}$	A
<b><math>t_{SC}</math> (SCSOA)</b>	$V_{CE} = V_{CES}$ ; $V_{GE} = \pm 15\text{ V}$ ; $R_G = 15\ \Omega$ ; $T_{VJ} = 125^{\circ}\text{C}$ non-repetitive	10	$\mu\text{s}$
<b><math>P_{tot}</math></b>	$T_C = 25^{\circ}\text{C}$	320	W

Symbol	Conditions	Characteristic Values ( $T_{VJ} = 25^{\circ}\text{C}$ , unless otherwise specified)		
		min.	typ.	max.
$V_{CE(sat)}$	$I_C = 75\text{ A}$ ; $V_{GE} = 15\text{ V}$ ; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$	2.0 2.3	2.5	V V
$V_{GE(th)}$	$I_C = 1.5\text{ mA}$ ; $V_{GE} = V_{CE}$	4.5	6.5	V
$I_{CES}$	$V_{CE} = V_{CES}$ ; $V_{GE} = 0\text{ V}$ ; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$	1.5	1.4	mA mA
$I_{GES}$	$V_{CE} = 0\text{ V}$ ; $V_{GE} = \pm 20\text{ V}$		200	nA
$t_{d(on)}$ $t_r$ $t_{d(off)}$ $t_f$ $E_{on}$ $E_{off}$	Inductive load, $T_{VJ} = 125^{\circ}\text{C}$ $V_{CE} = 300\text{ V}$ ; $I_C = 75\text{ A}$ $V_{GE} = \pm 15\text{ V}$ ; $R_G = 15\ \Omega$	150		ns
		60		ns
		450		ns
		40		ns
		4.0		mJ
		3.3		mJ
$C_{ies}$	$V_{CE} = 25\text{ V}$ ; $V_{GE} = 0\text{ V}$ ; $f = 1\text{ MHz}$	4.2		nF
$Q_{Gon}$	$V_{CE} = 300\text{ V}$ ; $V_{GE} = 15\text{ V}$ ; $I_C = 100\text{ A}$	260		nC
$R_{thJC}$	(per IGBT)		0.39	K/W

**Output Inverter D1 - D6**

Symbol	Conditions	Maximum Ratings	
$I_{F25}$	$T_C = 25^{\circ}\text{C}$	140	A
$I_{F80}$	$T_C = 80^{\circ}\text{C}$	85	A

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$V_F$	$I_F = 75\text{ A}$ ; $V_{GE} = 0\text{ V}$ ; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$	1.7 1.2	2.0	V V
$I_{RM}$ $t_{rr}$	$I_F = 60\text{ A}$ ; $di_F/dt = -500\text{ A}/\mu\text{s}$ ; $T_{VJ} = 125^{\circ}\text{C}$ $V_R = 300\text{ V}$ ; $V_{GE} = 0\text{ V}$	28		A
		100		ns
$R_{thJC}$	(per diode)		0.61	K/W

**Equivalent Circuits for Simulation**
**Conduction**

 IGBT (typ. at  $V_{GE} = 15\text{ V}$ ;  $T_J = 125^{\circ}\text{C}$ )  
T1-T6

$$V_0 = 1.21\text{ V}; R_0 = 15\text{ m}\Omega$$

T7

$$V_0 = 1.06\text{ V}; R_0 = 36\text{ m}\Omega$$

 Diode (typ. at  $T_J = 125^{\circ}\text{C}$ )

D1-D6

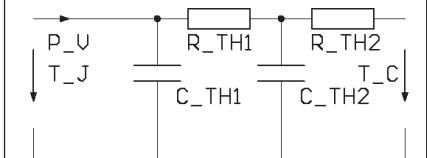
$$V_0 = 1.1\text{ V}; R_0 = 2\text{ m}\Omega$$

D7

$$V_0 = 1.1\text{ V}; R_0 = 12\text{ m}\Omega$$

D11-D16

$$V_0 = 0.85\text{ V}; R_0 = 5\text{ m}\Omega$$

**Thermal Response**


IGBT (typ.)

T1-T6

$$C_{th1} = 0.177\text{ J/K}; R_{th1} = 0.293\text{ K/W}$$

$$C_{th2} = 1.228\text{ J/K}; R_{th2} = 0.097\text{ K/W}$$

T7

$$C_{th1} = 0.088\text{ J/K}; R_{th1} = 0.583\text{ K/W}$$

$$C_{th2} = 0.799\text{ J/K}; R_{th2} = 0.167\text{ K/W}$$

Diode (typ.)

D1-D6

$$C_{th1} = 0.138\text{ J/K}; R_{th1} = 0.48\text{ K/W}$$

$$C_{th2} = 0.957\text{ J/K}; R_{th2} = 0.13\text{ K/W}$$

D7

$$C_{th1} = 0.038\text{ J/K}; R_{th1} = 1.725\text{ K/W}$$

$$C_{th2} = 0.439\text{ J/K}; R_{th2} = 0.375\text{ K/W}$$

D11-D16

$$C_{th1} = 0.086\text{ J/K}; R_{th1} = 0.738\text{ K/W}$$

$$C_{th2} = 0.621\text{ J/K}; R_{th2} = 0.202\text{ K/W}$$

**Brake Chopper T7**

Symbol	Conditions	Maximum Ratings	
$V_{CES}$	$T_{VJ} = 25^{\circ}\text{C}$ to $150^{\circ}\text{C}$	600	V
$V_{GES}$	Continuous	$\pm 20$	V
$I_{C25}$	$T_C = 25^{\circ}\text{C}$	50	A
$I_{C80}$	$T_C = 80^{\circ}\text{C}$	35	A
<b>RBSOA</b>	$V_{GE} = \pm 15\text{ V}$ ; $R_G = 33\ \Omega$ ; $T_{VJ} = 125^{\circ}\text{C}$ Clamped inductive load; $L = 100\ \mu\text{H}$	$I_{CM} = 60$ $V_{CEK} \leq V_{CES}$	A
$t_{SC}$ <b>(SCSOA)</b>	$V_{CE} = V_{CES}$ ; $V_{GE} = \pm 15\text{ V}$ ; $R_G = 33\ \Omega$ ; $T_{VJ} = 125^{\circ}\text{C}$ non-repetitive	10	$\mu\text{s}$
$P_{tot}$	$T_C = 25^{\circ}\text{C}$	165	W

Symbol	Conditions	Characteristic Values ( $T_{VJ} = 25^{\circ}\text{C}$ , unless otherwise specified)		
		min.	typ.	max.
$V_{CE(sat)}$	$I_C = 35\text{ A}$ ; $V_{GE} = 15\text{ V}$ ; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$	2.0	2.5	V
		2.3		V
$V_{GE(th)}$	$I_C = 0.7\text{ mA}$ ; $V_{GE} = V_{CE}$	4.5	6.5	V
$I_{CES}$	$V_{CE} = V_{CES}$ ; $V_{GE} = 0\text{ V}$ ; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$	0.3	0.5	mA mA
$I_{GES}$	$V_{CE} = 0\text{ V}$ ; $V_{GE} = \pm 20\text{ V}$		200	nA
$t_{d(on)}$ $t_r$ $t_{d(off)}$ $t_f$ $E_{on}$ $E_{off}$	Inductive load, $T_{VJ} = 125^{\circ}\text{C}$ $V_{CE} = 300\text{ V}$ ; $I_C = 35\text{ A}$ $V_{GE} = \pm 15\text{ V}$ ; $R_G = 33\ \Omega$	50		ns
		50		ns
		270		ns
		40		ns
		1.63		mJ
		1.17		mJ
$C_{ies}$	$V_{CE} = 25\text{ V}$ ; $V_{GE} = 0\text{ V}$ ; $f = 1\text{ MHz}$	1.6		nF
$Q_{Gon}$	$V_{CE} = 300\text{ V}$ ; $V_{GE} = 15\text{ V}$ ; $I_C = 25\text{ A}$	94		nC
$R_{thJC}$			0.75	K/W

**Brake Chopper D7**

Symbol	Conditions	Maximum Ratings	
$V_{RRM}$	$T_{VJ} = 25^{\circ}\text{C}$ to $150^{\circ}\text{C}$	600	V
$I_{F25}$	$T_C = 25^{\circ}\text{C}$	35	A
$I_{F80}$	$T_C = 80^{\circ}\text{C}$	24	A

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$V_F$	$I_F = 35\text{ A}$ ; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$	2.0	2.3	V
		1.5		V
$I_R$	$V_R = V_{RRM}$ ; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$	0.1	0.1	mA mA
$I_{RM}$ $t_{rr}$	$I_F = 15\text{ A}$ ; $di_F/dt = -400\text{ A}/\mu\text{s}$ ; $T_{VJ} = 125^{\circ}\text{C}$ $V_R = 300\text{ V}$	13		A
		90		ns
$R_{thJC}$			2.1	K/W

IXYS reserves the right to change limits, test conditions and dimensions.

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## Temperature Sensor NTC

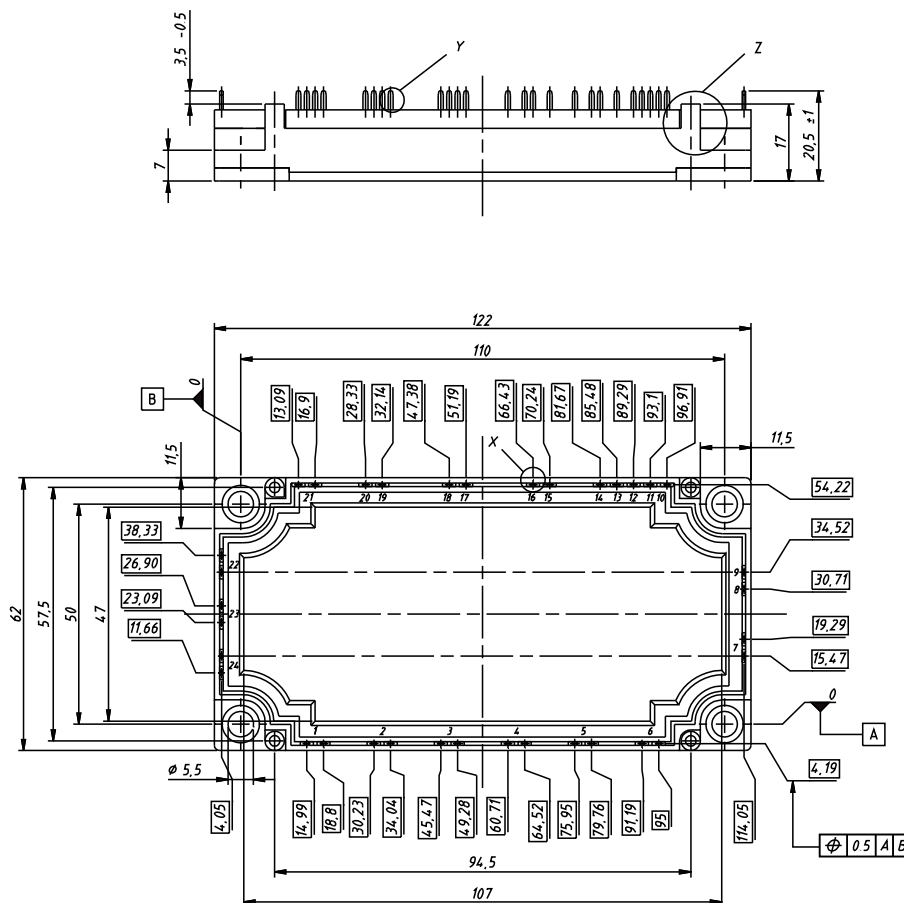
Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$R_{25}$	$T = 25^{\circ}\text{C}$	4.75	5.0	5.25 k $\Omega$
$B_{25/50}$			3375	K

## Module

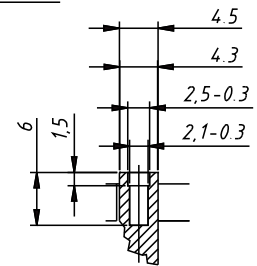
Symbol	Conditions	Maximum Ratings	
$T_{VJ}$	operating	-40...+125	$^{\circ}\text{C}$
$T_{JM}$		+150	$^{\circ}\text{C}$
$T_{stg}$		-40...+125	$^{\circ}\text{C}$
$V_{ISOL}$	$I_{ISOL} \leq 1 \text{ mA}; 50/60 \text{ Hz}$	2500	V~
$M_d$	Mounting torque (M5)	3 - 6	Nm

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$R_{pin-chip}$			5	m $\Omega$
$d_s$	Creepage distance on surface	6		mm
$d_A$	Strike distance in air	6		mm
$R_{thCH}$	with heatsink compound		0.01	K/W
Weight			300	g

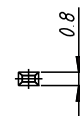
Dimensions in mm (1 mm = 0.0394")



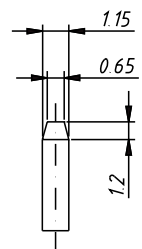
Detail Z



Detail X



Detail Y



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