# **NX9415**



5A SYNCHRONOUS BUCK SWITCHING REGULATOR

## **PRODUCTION DATA SHEET**

**FEATURES Pb Free Product**

## **DESCRIPTION**

The NX9415 is synchronous buck switching converter in  $\blacksquare$ multi chip module designed for step down DC to DC converter applications. It is optimized to convert bus  $\blacksquare$ voltages from 8V to 22V to as low as 0.8V output volt- ■ age. The output current can be up to 5A. An internal  $\blacksquare$ regulator converts bus voltage to 5V, which provides voltage supply to internal logic and driver circuit. The NX9415 operates from 200kHz to 2.2MHz and employs loss-less current limiting by sensing the Rdson of synchronous MOSFET followed by hiccup feature.Feedback under volt- ■ age protection triggers hiccup.

Other features of the device are: internal schottky diode, thermal shutdown, 5V gate drive, adaptive deadband control, internal digital soft start, 5VREG undervoltage lock out and shutdown capability via the comp pin. NX9415 is available in 4x4 MCM package.

- Single supply voltage from 8V to 22V
- Internal 5V regulator
- Programmable frequency up to 2.2MHz
- Internal Digital Soft Start Function
- Internal boost schottky diode
- Prebias Startup
- Less than 50 nS adaptive deadband
- Current limit triggers hiccup by sensing Rdson of Synchronous MOSFET
- Pb-free and RoHS compliant

## **APPLICATIONS**

- Low Profile On board DC to DC Application
- **LCD TV**
- **Hard Disk Drive**
- n ADSL Modem

# **TYPICAL APPLICATION**



#### Figure 1 - Typical application of 9415

# **ORDERING INFORMATION**





# **ABSOLUTE MAXIMUM RATINGS**



CAUTION: Stresses above those listed in "ABSOLUTE MAXIMUM RATINGS", may cause permanent damage to the device. This is a stress only rating and operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied.

## **PACKAGE INFORMATION**

24-LEAD PLASTIC MCM 4 x 4





# **ELECTRICAL SPECIFICATIONS**

Unless otherwise specified, these specifications apply over Vin = 12V, and T<sub>A</sub>=0 to 70°C. Followings are bypass capacitors:C<sub>vIN</sub>=1uF, C<sub>svREG</sub>=4.7uF, all X5R ceramic capacitors. Typical values refer to T<sub>A</sub> = 25°C. Low duty cycle pulse testing is used which keeps junction and case temperatures equal to the ambient temperature.



# **PIN DESCRIPTIONS**





# **BLOCK DIAGRAM**

**12/28/09**



Figure 2 - Simplified block diagram of the NX9415



## **TYPICAL APPLICATION**

Input Voltage=12V Output Voltage=5V@5A Working Frequency=2.2MHz



Figure 3- Demo board schematic



# **Bill of Materials**





### **Demoboard waveforms**





Figure 4 - Output ripple (CH1 SW 10V/DIV, CH2 VOUT AC 50mV/DIV, CH4 OUTPUT CURRENT 5A/DIV)



Figure 6 - Over current protection(CH4 OUTPUT CURRENT 5A/DIV) Efficiency v.s. lout



Figure 8 - Output Efficiency @VOUT=5V,VIN=12V

**12/28/09**

 Figure 5 - Output voltage transient response ( CH2 VOUT AC 50mV/DIV, CH4 OUTPUT CURRENT 5A/DIV)



Figure 7 - Startup(CH2 VOUT 2V/DIV, CH4 OUTPUT CURRENT 2A/DIV)



# **APPLICATION INFORMATION**

## **Symbol Used In Application Information:**



- 
- F<sub>s</sub> Working frequency
- $\Delta$ IRIPPLE Inductor current ripple

## **Output Inductor Selection**

The selection of inductor value is based on inductor ripple current, power rating, working frequency and efficiency. Larger inductor value normally means smaller ripple current. However if the inductance is chosen too large, it brings slow response and lower efficiency. Usually the ripple current ranges from 20% to 40% of the output current. This is a design freedom which can be decided by design engineer according to various application requirements. The inductor value can be calculated by using the following equations:

$$
L_{\text{OUT}} = \frac{V_{\text{IN}} \cdot V_{\text{OUT}}}{\Delta I_{\text{RIPPLE}}} \times \frac{V_{\text{OUT}}}{V_{\text{IN}}} \times \frac{1}{F_{\text{S}}}
$$
...(1)

where k is between 0.2 to 0.4.

## **Output Capacitor Selection**

Output capacitor is basically decided by the amount of the output voltage ripple allowed during steady state(DC) load condition as well as specification for the load transient. The optimum design may require a couple of iterations to satisfy both condition.

The amount of voltage ripple during the DC load condition is determined by equation(2).

$$
\Delta V_{\text{RIPPLE}} = \text{ESR} \times \Delta I_{\text{RIPPLE}} + \frac{\Delta I_{\text{RIPPLE}}}{8 \times F_{\text{s}} \times C_{\text{OUT}}} \quad ...(2)
$$

Where ESR is the output capacitors' equivalent series resistance,  $C_{\text{out}}$  is the value of output capacitors.

Typically when ceramic capacitors are selected as output capacitors, DC ripple spec is easy to be met, but mutiple ceramic capacitors are required at the output to meet transient requirement.

## **Compensator Design**

Due to the double pole generated by LC filter of the power stage, the power system has 180° phase shift, and therefore, is unstable by itself. In order to achieve accurate output voltage and fast transient response, compensator is employed to provide highest possible bandwidth and enough phase margin.Ideally,the Bode plot of the closed loop system has crossover frequency between1/10 and 1/5 of the switching frequency, phase margin greater than 50 $^{\circ}$  and the gain crossing 0dB with -20dB/decade. Power stage output capacitors usually decide the compensator type. If electrolytic capacitors are chosen as output capacitors, type II compensator can be used to compensate the system, because the zero caused by output capacitor ESR is lower than crossover frequency. Otherwise type III compensator should be chosen.

## **A. Type III compensator design**

 For low ESR output capacitors, typically such as Sanyo oscap and poscap, the frequency of ESR zero caused by output capacitors is higher than the crossover frequency. In this case, it is necessary to compensate the system with type III compensator. The following figures and equations show how to realize the type III compensator by transconductance amplifier.

$$
F_{z_1} = \frac{1}{2 \times \pi \times R_4 \times C_2}
$$
...(3)

$$
F_{z2} = \frac{1}{2 \times \pi \times (R_2 + R_3) \times C_3}
$$
...(4)

$$
F_{p_1} = \frac{1}{2 \times \pi \times R_3 \times C_3}
$$
...(5)

$$
F_{p_2} = \frac{1}{2 \times \pi \times R_4 \times \frac{C_1 \times C_2}{C_1 + C_2}} \qquad ...(6)
$$

where Fz1, Fz2, FP1 and FP2 are poles and zeros in the compensator. Their locations are shown in figure 10.

The transfer function of type III compensator for transconductance amplifier is given by:

$$
\frac{V_{\text{e}}}{V_{\text{OUT}}} = \frac{1 - g_{\text{m}} \times Z_{\text{f}}}{1 + g_{\text{m}} \times Z_{\text{in}} + Z_{\text{in}} / R_{\text{f}}}
$$





For the voltage amplifier, the transfer function of

compensator is

$$
\frac{V_e}{V_{OUT}} = \frac{-Z_f}{Z_{in}}
$$

To achieve the same effect as voltage amplifier, the compensator of transconductance amplifier must **satisfy this condition: R**<sup>4</sup> >>2/gm. And it would be desirable if  $\mathsf{R}_{_1}||\mathsf{R}_{_2}||\mathsf{R}_{_3}>>$ 1/gm  $\,$  can be met at the same time.



 Figure 9 - Type III compensator using transconductance amplifier



# **B. Type II compensator design**

Type II compensator can be realized by simple RC circuit without feedback as shown in figure 12.  $\mathsf{R}_{_{\text{3}}}$  and  $\mathsf{C}_{_{\text{1}}}$ introduce a zero to cancel the double pole effect.  $C<sub>2</sub>$ introduces a pole to suppress the switching noise. The following equations show the compensator pole zero location and constant gain.

$$
Gain = g_m \times \frac{R_1}{R_1 + R_2} \times R_3 \qquad \dots (7)
$$
  
\n
$$
F_z = \frac{1}{2 \times \pi \times R_3 \times C_1} \qquad \dots (8)
$$
  
\n
$$
F_p \approx \frac{1}{2 \times \pi \times R_3 \times C_2} \qquad \dots (9)
$$

For this type of compensator,  $\mathsf{F}_\mathsf{O}$  has to satisfy  $\mathsf{F}_{\text{\tiny{LC}}}$ < $\mathsf{F}_{\text{\tiny{ESR}}}$ << $\mathsf{F}_{\text{\tiny{O}}}$ <=1/10~1/5 $\mathsf{F}_{\text{\tiny{s.}}}$ 



Figure 11 - Bode plot of Type II compensator

Figure 10 - Bode plot of Type III compensator





 Figure 12 - Type II compensator with transconductance amplifier

## **Output Voltage Calculation**

Output voltage is set by reference voltage and external voltage divider. The reference voltage is fixed at 0.8V. The divider consists of two ratioed resistors so that the output voltage applied at the Fb pin is 0.8V when the output voltage is at the desired value. The following equation and picture show the relationship between  $V_{\text{OUT}}$ ,  $V_{\text{REF}}$  and voltage divider.

$$
R_{1} = \frac{R_{2} \times V_{REF}}{V_{OUT} - V_{REF}} \qquad ...(10)
$$

where  $R_2$  is part of the compensator, and the value of R1 value can be set by voltage divider.

See compensator design for  $\mathsf{R}_{_{1}}$  and  $\mathsf{R}_{_{2}}$  selection.



Figure 13 - Voltage divider

## **Over Current Protection**

Over current protection is achieved by sensing current through the low side MOSFET. A typical internal current source of 37uA flowing through an external resistor connected from OCP pin to SW node sets the over current protection threshold. When synchronous FET is on, the voltage at node SW is given as

 $V_{SW} = -I_L \times R_{DSON}$ 

The voltage at pin OCP is given as

 $I_{OCP} \times R_{OCP} + V_{SW}$ 

When the voltage is below zero, the over current occurs.



Figure 14 - Over current protection

The over current limit can be set by the following equation

$$
I_{\text{SET}} = \frac{I_{\text{OCP}} \times R_{\text{OCP}}}{K \times R_{\text{DSON}}}
$$

## **Frequency Selection**

The frequency can be set by external Rt resistor. The relationship between frequency and RT pin is shown as follows.



#### **NX9415 Frequency vs Rt**

Figure 15 - Frequency versus Rt resistor



## **MCM 24 PIN 4 x 4 PACKAGE OUTLINE DIMENSIONS**

