

LIN-Slave for relay and DC motor control

Features

Microcontroller: MLX16x8 RISC CPU

- 16 bit RISC-CPU 0
- Co-processor for fast multiplication and division 0
- In-circuit debug and emulation \cap

Memories

- o 32 kByte Flash with ECC
- 0 2 kByte RAM
- 384 Byte EEPROM with ECC for customer purpose

Supported bus interface

- o LIN-Interface with integrated LIN transceiver supporting LIN 2.x and SAE J2602, certified LIN protocol software provided by Melexis
- o In-Module-Programming (Flash and EE) via pin LIN using a special Melexis fast protocol
- o PWM-Interface
- o Full duplex SPI, Master/Slave, double-buffered, speed programmable

Voltage regulator

- 0 Internal voltage regulator, direct powered from 12V battery supply
- Operating voltage VS = 5.5V to 18V, IC will work down to 3.9V 0
- Possibility to put an external bypass transistor for high temperature requirements 0
- Very low SLEEP MODE current < 30uA, Wake up by LIN traffic or local sources 0

Periphery

- 4 programmable 16bit PWM modules for external transistor full bridge applications 0
- Timer unit 16 bit with 4 capture and 4 compare 0
- 25 MHz +/-5% internal RC-oscillator with PLL, optional crystal resonator 0
- Load dump and brown out interrupt function 0
- Digital watchdog for software flow tracking 0
- System-Clock-independent fully integrated watchdog 0
- On-chip temperature sensor with +/-10K accuracy 0
- 10 bit ADC with < 6 µs conversion time with multiple channels and different ADC references, DMA 0 access to RAM
- 8 multiple purpose I/Os 0
- 2 integrated relay drivers with free wheel function 0
- 2 inputs for relay contact or shunt current monitoring 0
- Over current detection, shunt current sense 0
- 1 switch-able supply output for external Hall sensor connection 0

Additional features

- Direct access to pin LIN possible 0
- Temperature range -40°C up to 150°C 0
- 0 28V jump start and 45V load dump protected
- 0 Monolithic solution: Single chip in single package realization
- Small QFN32 5x5 and TQFPeP48 7x7 package 0

Applications

0

LIN slaves for all kind of high current DC and 1 / 2 phase BLDC motor control, like

- Window lifter 0 Sun roof
- DC oil, water and fuel pumps
 Automatic head o Throttle valves
 - o lean DC/DC converters

MLX81150 - Product abstract

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Ordering Information

Order Code ^[1]	Temp. Range	Package	Delivery	Remark
MLX81150 LLQ-xAA-000-TU MLX81150 LLQ-xAA-000-RE	-40 - 150 °C -40 - 150 °C	QFN32 5x5 QFN32 5x5	Tube Reel	
MLX81150 LPF-xAA-000-TR	-40 - 150 °C	TQFP EP 48 7x7	Tray	
MLX81150 LPF-xAA-000-RE	-40 - 150 °C	TQFP EP 48 7x7	Reel	

Table 1 – Ordering Information

^[1].See Marking/Order Code.



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1. Functional diagram

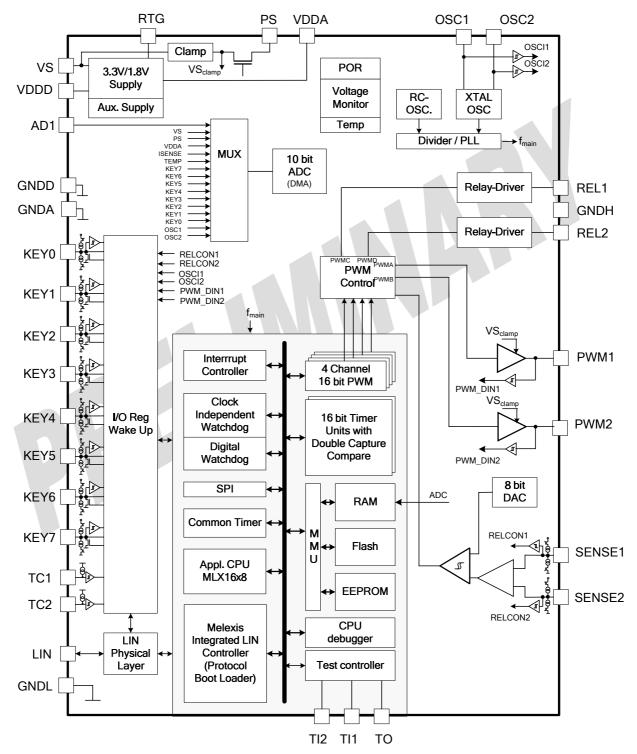


Figure 1- Block diagram



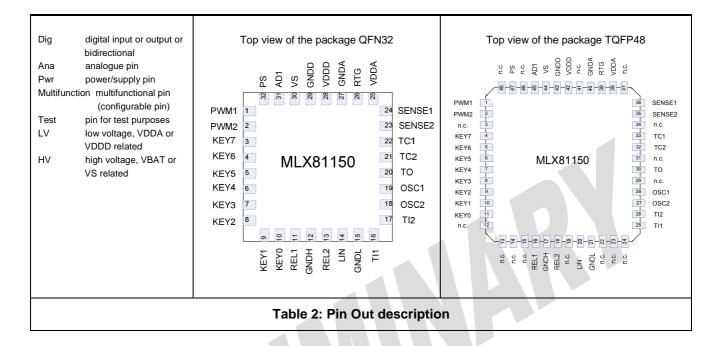
MLX81150 LIN-Slave for relay and DC motor control

2. Pin description

Pin No. QFN32	Pin No. TQFP48	Pad count	Pin name	voltage range	remarks and description
30	44	1	VS	Pwr HV	Battery supply voltage; external protection against reverse polarity needed, external blocking capacitors
29	43	2	GNDD	Pwr	Ground pin for Digital part
27	40	2	GNDA	Pwr	Ground pin for Analogue part
12	17	2	GNDH	Pwr	Ground pin for Relay Driver
15	21	1	GNDL	Pwr	Ground pin for LIN
25	38	2	VDDA	Pwr LV	Regulator output (~3.3 V), external blocking capacitors
28	42	2	VDDD	Pwr LV	Regulator output (~1.8 V), external blocking capacitors
26	39	1	RTG	Ana LV	Output for external bipolar transistor in case of HT applications
32	47	1	PS	Ana HV	High-side switch with Ron < 40 Ohm at 20mA, Switch-able supply (<15 V) for external components
[3:10]	[4:11]	8	KEY[7:0]	Multi- function HV	High voltage I/O port with wake-up function, Input for high or low active switches, ADC input, Low-side driver output 4mA (15mA), Weak current sources for pin diagnosis and WAKE UP in SLEEP MODE SPI Interface Pins (valid for KEY[3:0], DI, DO, CLK, CS)
31	45	1	AD1	Ana HV	High voltage ADC input (for VBAT measurement), Low side driver 30 □A (only for test purposes)
13, 11	18, 16	2, 2	REL[2:1]	Ana HV	Low-side switch with Ron < 7 Ohm at 150 mA @150°C, Relay driver with free wheel function, PWM controlled output
23, 24	35, 36	2	SENSE[2:1]	Ana HV	High voltage input for read out the status of relay contacts, Current sense function for shunt current
2, 1	2, 1	2	PWM[2:1]	Ana HV	Push pull output with Ron < 50 Ohm at 20mA, high output level is supply related but max approx. 14V, PWM controlled output
21, 22	32, 33	2	TC[2:1]	Ana LV	Input for timer capture unit, Low voltage input
18, 19	27, 28	2	OSC[2:1]	Ana LV	Crystal oscillator pin, Low voltage input, load capacitors external, ADC input
14	20	1	LIN	Ana HV	LIN 2.x transceiver BUS pin, slave only, High voltage I/O
17, 16	26, 25	1	TI[2:1]	Dig input	Test inputs for Melexis, debug interface - connect via resistor to GND in application mode, so that Flashing via these test pins is possible
20	30	1	то	Dig output	Test output for Melexis, debug interface, unconnected in application mode
-	3, 12, 13, 14, 15, 19, 22, 23, 24, 29, 31, 34, 37, 41, 46, 48	-	not connected	-	not connected pins



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3. Electrical characteristics

All voltages are referenced to ground (GND). Positive currents flow into the IC. The absolute maximum ratings given in the table below are limiting values that do not lead to a permanent damage of the device but exceeding any of these limits may do so. Long term exposure to limiting values may affect the reliability of the device. Reliable operation of the MLX81150 is only specified within the limits shown in "Operating conditions".

3.1 Operating conditions

Parameter	Symbol	Conditions	Min	Limit Typ	Max	Unit
Supply Voltage Range	VS		5.5 (3.9 ^[1])		18	V
Ambient Temperature	ТА		-40		105 (150 ^[2])	°C

Table 3: Operational conditions

The IC can have 6 different hardware modes. The exact functionality of these modes depends on the hardware and software configuration:

- Reset:
 - triggered by hardware. When VS or VDDA or VDDD drop below a critical level, the complete chip is powered down.
 - The analogue and digital supply regulators are disabled. No functionality is available in this mode.
- Normal mode. Main application running
 - o Microcontroller fully functional
 - Analogue fully functional
- Power Saving Mode
 - Application CPU halted
 - Wake-up by interrupt possible
- Under voltage: triggered by the hardware under voltage detection interrupt. (VS_UV)
 - Microcontroller fully functional.
 - Analogue functionality under software control.
 - Reduced current capability on VDDA below VS=5.5V.
 - Over voltage: triggered by the hardware over voltage detection interrupt. (VS_OV)
 - Microcontroller fully functional
 - Analogue functionality powered down by hardware or software.
 - Sleep Mode: Triggered by the software.
 - Microcontroller powered down
 - Digital and analogue supply powered down.
 - Sleep Mode and wake-up functionality running on help supply Vaux
- [1] Development target, IC will work down to 3.9V with reduced analogue characteristics, Digital part still works, Memories will keep their content. Some analogue parameter will drift out of limits, but chip function can be guaranteed. Before going down to 3.9V the VS has to be at the startup of the IC for a certain time > 6V to guarantee a correct reset! Evaluation will only be done on sample basis in the preproduction phase; no production test; no life time test
- [2] Target ambient temperature after qualification: With temperature applications at TA>105°C a reduction of chip internal power dissipation with an external transistor in the voltage regulator path is obligatory. The extended temperature range is only allowed for a limited period of time, customer's mission profile has to be agreed by Melexis as an obligatory part of the Part Submission Warrant (PSW). Some analogue parameter may drift out of limits, but chip function can be guaranteed.



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3.2 Absolute maximum ratings

Parameter	Symbol	Condition	Limit Min	Limit Max	Unit
Supply voltage	VS	t < 5 min	-0.3	28	V
		t < 500 ms	-0.3	45	
	VS.tr1	ISO 7637-2 pulse 1 ^[1] VS=13.5V, TA=(23 ± 5)°C	-100		
	VS.tr2	ISO 7637-2 pulse 2 ^[1] VS=13.5V, TA=(23 ± 5)°C		+50	
	VS.tr3	ISO 7637-2 pulses 3A, 3B ^[1] VS=13.5V, TA=(23 ± 5)°C	-150	+100	-
	VS.tr5	ISO 7637-2 pulses 5b ^[1] VS=13.5V, TA=(23 ± 5)°C	+65	+87	
Output voltage	VDDA		-0.3	3.6	
Output voltage	VDDD		-0.3	1.95	
LIN Bus	VLIN	T < 500ms	-22	40	
	VLIN.tr1	ISO 7637-2 pulse 1 ^[2] VS=13.5V, TA=(23 ± 5)°C	100		
	VLIN.tr2	ISO 7637-2 pulse 2 ^[2] VS=13.5V, TA=(23 ± 5)°C		+75	-
	VLIN.tr3	ISO 7637-2 pulses 3A, 3B ^[2] VS=13.5V, TA=(23 ± 5)°C	-150	+100	
Voltage on Analogue HV	VANA_HV	Without external resistor; Pins KEY[7:0], AD1 Pin PWM[2:1]	-0.3	VS+0.3 V(PS) +0.3	
		With external resistor of 47 kΩ Pins KEY[7:0], AD1		VBAT	
	VmaxPS	Pin PS		15	
	VmaxSENSE [2:1]	Pins SENSE[2:1]		VS+0.3	
	VmaxREL[2:1]	Pins REL[2:1]		39	
Voltage on Analogue LV	VANA_LV	Pins RTG, TC[2:1], OSC[2:1]	-0.3	VDDA +0.3	
		RTG (in case of external bipolar transistor)		5	
Digital Output Voltage	VOUT_DIG	Pin TO	-0.3	VDDA +0.3	
Digital Input Voltage	VIN_DIG	Pins TI[2:1]	-0.3	VDDA +0.3	
Digital Input Current	IIN_DIG	Pins TI[2:1]	-10	10	mA
Maximum latch–up free current at any pin	ILATCH	according to JEDEC JESD78, AEC-Q100-004	-250	250	
ESD capability of pin LIN	ESDHBM_LIN	Human body model [7]	-6	+6	kV
ESD capability of pin LIN	ESDIEC_LIN	Acc. To IEC 61000-4-2 ^[6]	-6	+6	kV
ESD capability of any other pin, except LIN	ESDHBM	Human body model ^[7]	-2	+2	kV
ESD capability at any pin	ESDCDM	Charge Device Model	-500	+500	V
Storage temperature	Tstg		-55	150	°C



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Junction Temperature	TJ		-40	150 (155) ^{[4][5]}	°C
Thermal resistance QFN32 ^[3]	Rth	in free air, air flow 0m/s	~	32	K/W

Table 4: Absolute maximum ratings

- ISO 7637 test pulses are applied to VS via a reverse polarity diode and >1µF blocking capacitor; [1]
- ISO 7637 test pulses are applied to LIN via a coupling capacitance of 1nF;
- [2] [3] [4] Simulated value for low conductance board (JEDEC).
- 150°C ambient temperature is a target value. For temperatures >105°C an external bipolar regulator transistor in the regulator path should be used. Ambient temperatures of 150°C are only allowed for limited periods of time to be agreed in a mission profile with the customer.
- 155°C is a development target value. [5]
- Equivalent to discharging a 150pF capacitor through a 330Ω resistor;
- [6] [7] The specified values are a target to be verified on first prototypes. Based on the evaluation results, additional external protection components might be recommended to reach the specified system ESD levels. Equivalent to discharging a 100pF capacitor through a $1.5k\Omega$ resistor conform to MIL STD 883 method 3015.7.
- [8]



4. Application Examples

The following sections show typical application examples ^[1].

[1] The application examples are principal application schematics only. The details need to be worked out for each application schematic separately, depending on the application requirements.

4.1 Single DC motor drive

In this sample application the IC can realize the driving of a DC motor via an external relay bridge. Speed, position sensing and anti trap or block detection are done by means of external Hall latches connected to a timer capture unit. The Hall sensors are switched off during standby mode via a switchable battery voltage output. Additionally relay contact monitoring can done by checking the voltages over it.

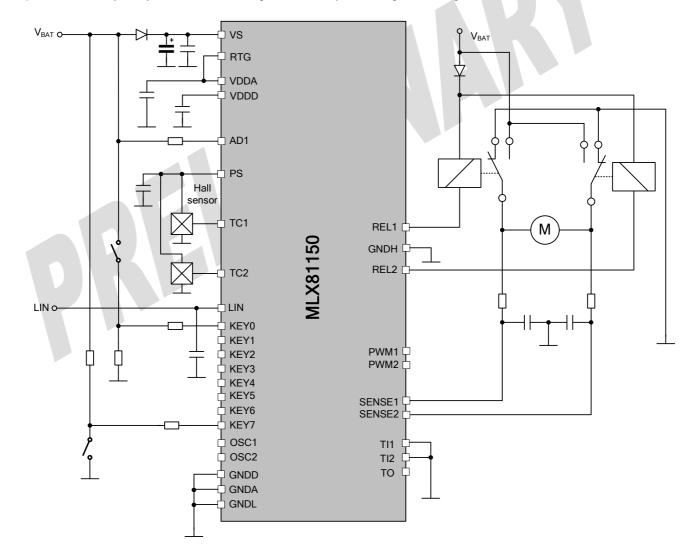


Figure 2 – Principle application diagram showing a common relay driver controlled by external switches and LIN bus



4.2 Single DC motor drive with soft start / stop

For some applications it might be necessary:

- To control the motor speed especially during start / stop,
- To have an independent switching channel in case the relay "hangs",
- To switch the power via the power transistor and to increase with this the life time of the relay contacts
- To monitor the motor current (current sensing and over current shut off).

This application requires then also a reverse polarity protection in the power path. Following application diagram shows the practical realization in principle:

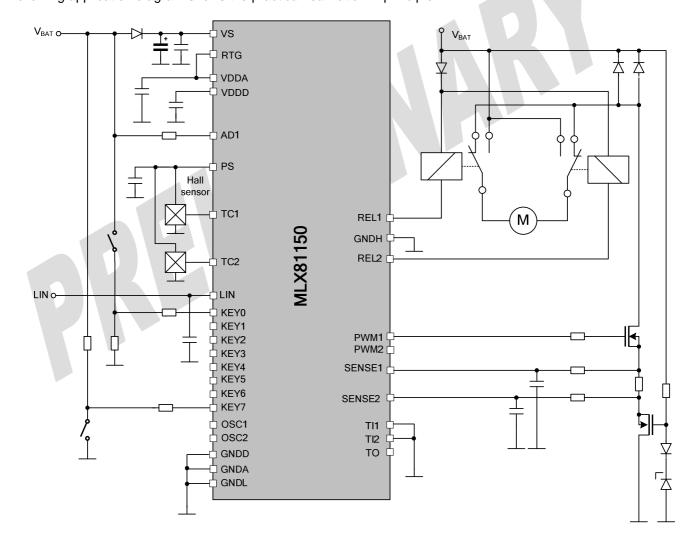


Figure 3 – Principle application diagram showing a common relay driver controlled by external switches and LIN bus, with soft start / stop and motor current sense



4.3 Single DC motor drive in FET controlled full bridge applications

By adding some external additional circuitry, the IC will also allow to drive DC motors in full bridge applications. Position, speed and direction sensing is done via external Hall latches.

By having one PWM on the low side path of the half bridge and the inverse PWM (with programmable interlock delay in the high side path) the p channel can be actively switched on in case the current wheels out.

Same is for the n-channel Transistor.

The other side of the full bridge is then statically switched on or off.

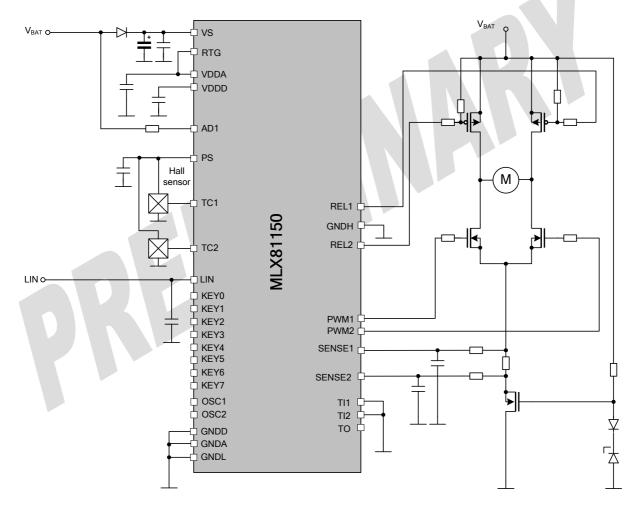


Figure 4 – Principle application diagram showing a DC motor in a full bridge application



4.4 LED-Lamp driver, switch mode power supply

In this application the MLX81150 drives a LED lamp with several high power LEDs in a DC-DC converter configuration. The module itself is controlled via the LIN bus. The current in the LED is regulated to a given value. Adjusting PWM frequency and PWM ratio allow to control the transformator in a very efficient way from EMC perspective as well as from energy point of view.

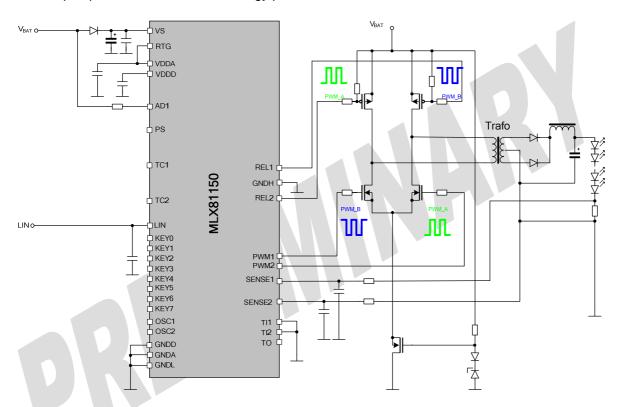


Figure 5 – Principle application diagram showing a DC/DC converter for high power LED lamp driving controlled by a LIN bus



4.5 MLX81150 in 1- and 2- phase BLDC (brush less DC) Motor control applications

BLDC motors are used today in several permanent running automotive applications. 1- and 2-phase BLDC motors are applied in several auxiliary applications as small pumps and blowers. In case these pumps request a LIN or PWM interface connection, the MLX81150 is a perfect solution for that. The commutation information for the brush less DC motors is provided by a hall switch/latch reacting on positive and negative magnet field of the permanent magnet rotor.

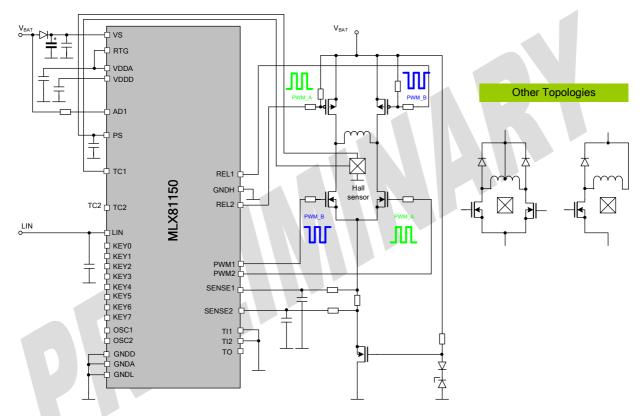


Figure 6 – Principle application diagram showing a 1 / 2 phase BLDC motor drive



4.6 Higher VDDA loads or higher ambient temperatures

If it is necessary to supply higher currents to external 3.3V loads or if high ambient temperatures >105°C are requested, it is possible to connect to the RTG pin an external load transistor. This external load transistor provides a higher current for possible external devices and also decreases the internal power dissipation.

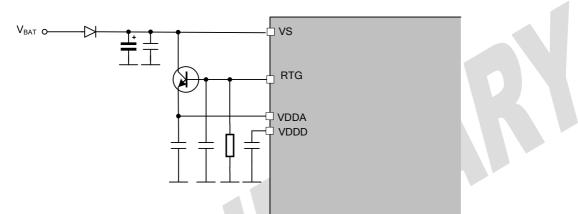


Figure 7 – Principle application diagram in case of higher VDDA loads or if high ambient temperatures are applied

4.7 Use of external resonator

It is possible to use an external resonator in case a higher precision of the frequency is requested.

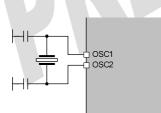


Figure 8 – Principle application diagram using an external resonator



4.8 Key inputs with different wetting currents in active and sleep configuration

Depending on different application requests for the key inputs it might be necessary to use in active mode relatively high wetting currents for the external switches. These currents will be provided by external pull up / pull down resistors. The IC will read the switches then with suitable threshold levels. In SLEEP MODE relatively low wetting currents might be necessary. These currents will also be provided by external pull up / pull down resistors. Wake up will be then just with a rising or falling edge of the incoming signal. An external bipolar transistor will just select the suitable series resistor for active mode or sleep mode.

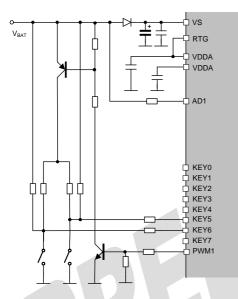


Figure 9 – Principle application diagram using different wetting currents in active and sleep mode configuration, switches are related to GND; PWM1 pin provides steady state voltage level, pull up currents

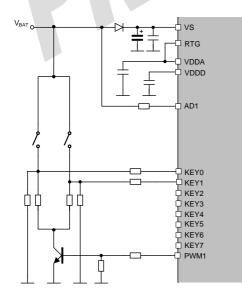


Figure 10 – Principle application diagram using different wetting currents in active and sleep mode configuration, switches are related to supply; PWM1 pin provides steady state voltage level, pull down currents



Via a 2-stage measurement, first at pin AD1 to check the V_{BAT} and second at pin KEY7, it is possible to check also the status of so called 'Matrix Switches'

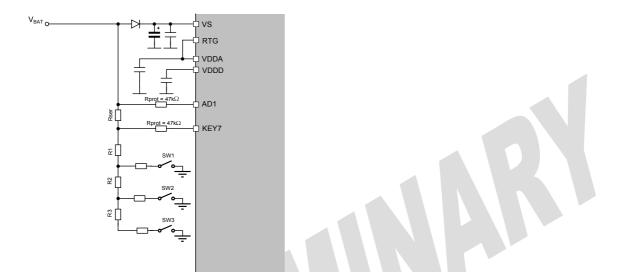


Figure 11 – Principle application diagram with matrix switch detection via KEY7 and AD1



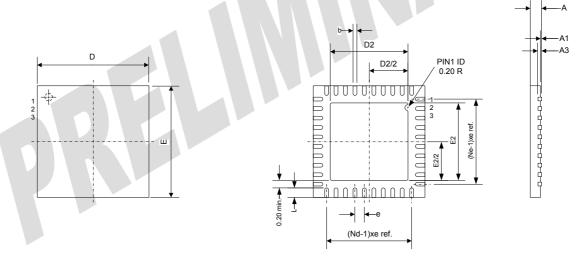
5. Mechanical Specification

5.1 Package data QFN32 (5x5, 32 leads)

[1][2]	А	A1	A3	b	D	D2	Е	E2	е	L	N[3]	ND [4]	NE[4]
min	0.80	0.00	0.20	0.18	5.00	3.50	5.00	3.50	0.50	0.3	32	8	8
nom	0.85	0.02		0.25		3.60		3.60		0.4			
max	1.00	0.05		0.30		3.70		3.70		0.5			

Table 5: Mechanical Dimensions QFN32 5x5

- [1] Dimensions and tolerances conform to ASME Y14.5M-1994
- [2] All dimensions are in Millimeters. All angels are in degrees
- [3] N is the total number of terminals
- [4] ND and NE refer to the number of terminals on each D and E side respectively



Top View

Bottom View

Side View

Figure 12: Package data QFN32



5.2 Package data TQFPeP 48L (7x7, 48 leads)

	Α	A1	A2	b	b1	D	D1	D2	E	E1	E2	е		Ν	CCC	ddd
Min	-	0.05	0.95	0.17	0.17	9.00	7.00	4.00	9.00	7.00	4.00	0.50	0.45	48	-	-
Nom	-	-	1.00	0.22	0.20								0.60		-	-
Max	1.20	0.15	1.05	0.27	0.23								0.75		0.08	0.08
2. Datum 3. Datum 4. To be (5. Dimen: 'N' is the 7. These 9. Dimen: locate 0. Control 1. maximu 2. This ou 13. A1 is 14. Dime	Plane [] [A-B] and [- determined sions D1 an a total numb dimensions to top dimens sion b does ad on the low lling dimens um allowabl ttline confor defined as i nsion D2 an	located at I -D-] to be de at seating p id E1 do not er of termina to be deten sions are sin not include wer radius o ion millimetri ms to JEDE the distance ad E2 repres	Mould Partir etermined at lane [-C-] include Mo als mined at da naller than b dam bar pro- f the foot. er. ess to be as C publicatio from the se- sent the size	tum plane [-] ottom dimen	coincident wi etween lead n. Dimensio -[-] sions and to wable dam h his package ation MS-02 to the lowes sed pad. The	s where lea ns D1 and E p of packag par protrusic family is 0.3 6, Variation point of the actual dim	ds exist, pla 1 do not inc e will not ov n shall be 0 38mm ABA, ABC o package bo	stic body at clude mould rerhang bott .08mm total & ABD. ody.	datum plane protrusion. / om of packa in excess o	≥ [- - -] Allowable mo ge. f the "b" dim	ould protrus	aximum ma	mm on D1 ar terial conditic m die size.			be
e	A−A− ↓ ↓ ↓ N/4 TIP: 20 C A−B			-D/2 -B- -B- -B- -B- -B-	E/2	possible c extectrical	bad need best ontact to ground and thermal reas					e ejector KS Are L for epad J for option Inal)		AD SII		
	[<u> </u>					זכ	- 0.05 A1-		0.08 - R. MIN. 0.20 MIN		IN. - 0.08/0.20 R.] PLANE				OR D-
	12. P	0.09/0.20														

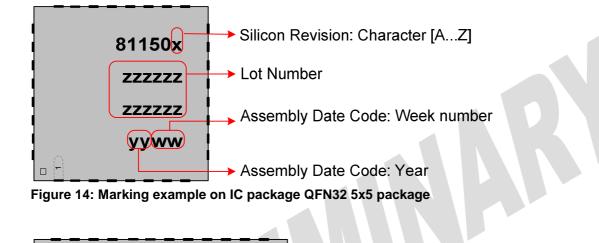
Figure 13: Package data TQFPeP48



LIN-Slave for relay and DC motor control

6. Marking/Order Code

6.1 Marking MLX81150



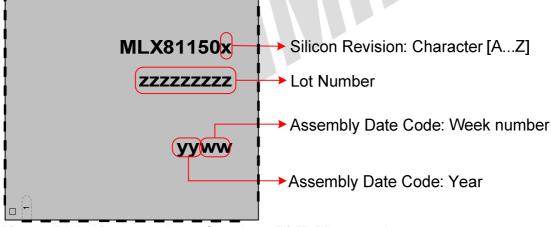
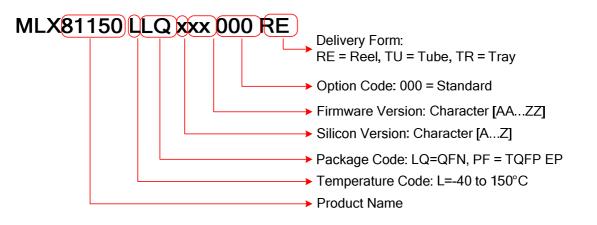


Figure 15: Marking example on IC package TQFP EP 7x7 package

6.2 Order Code MLX81150





7. Assembly Information

This Melexis device is classified and qualified regarding soldering technology, solder ability and moisture sensitivity level, as defined in this specification, according to following test methods:

- IPC/JEDEC J-STD-020 Moisture/Reflow Sensitivity Classification For No hermetic Solid State Surface Mount Devices (classification reflow profiles according to table 5-2)
- EIA/JEDEC JESD22-A113 Preconditioning of No hermetic Surface Mount Devices Prior to Reliability Testing (Reflow profiles according to table 2)
- CECC00802 Standard Method For The specification of Surface Mounting Components (SMD's) of Assessed Quality
- EIA/JEDEC JESD22-B106
 Resistance to soldering temperature for through-hole mounted devices
 EN00740.45
- EN60749-15 Resistance to soldering temperature for through-hole mounted devices
- MIL 883 Method 2003 / EIA/JEDEC JESD22-B102 Solder ability

For all soldering technologies deviating from above mentioned standard conditions (regarding peak temperature, temperature gradient, temperature profile etc) additional classification and qualification tests have to be agreed upon with Melexis. The application of Wave Soldering for SMD's is allowed only after consulting Melexis regarding assurance of adhesive strength between device and board.

Based on Melexis commitment to environmental responsibility, European legislation (Directive on the restriction of the use of certain hazardous substances, RoHS) and customer requests, Melexis has installed a roadmap to qualify their package families for lead free processes also. Various lead free generic qualifications are running, current results on request.

For more information on Melexis lead free statement see quality page at our website: http://www.melexis.com/html/pdf/MLXleadfree-statement.pdf



8. Disclaimer

The product abstract just provides an overview of the described devices. Please consult the complete product specification/datasheet in its latest revision for any detailed information.

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